

Network/Grid Computing: *Modeling, Algorithm, and Software*

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Network/Grid Computing

vs. Conventional Parallel/Distributed Computing

- Resource sharing
 - Hardware
 - Software
 - Data
 - Collaborative research/computing
- Remote vs. local computing nodes
- Service-oriented vs. client-oriented
- Communication
- More resources
- More flexibility
- More loosely coupled
 - System structures
 - Data structures
 - Models and algorithms
- More uncertainties
- Less user control

Challenges

- Software integration
 - Multi-languages
 - Multi-sources
 - Multi-nodes
- Collaborative computing
 - Multi-clients
 - Multi-models
 - Multi-methods
 - Multi-data

Scientific Computing with Multi-modeling

- Interaction of standing shock with boundary layer
- Inviscid-viscous flows
- Compressible-incompressible flows
- Turbulent-laminar flows
- Interface stability with different media
- Composite materials
- Complex systems

Modeling in Network/Grid Computing

- Different models in local regimes
- Interface coupling conditions
- Complexity across the interfaces
 - Physical
 - Discontinuity
 - Boundary layer
 - Geometrical
 - Topology
 - Moving interfaces

Applications

- Originated from a underlying problem where a global model approximation might be inappropriate, or even not be applicable—physically, mathematically, or computationally
- Reduced from a underlying global model
 - Computational efficiency
 - Approximation accuracy
 - Stiffness
 - Domain decomposition

Features of New Computational Frameworks

- Network/Grid computing (service-based)
 - Loosely coupled
 - Less central control
 - Local solvers with mature methods and existing codes
 - Less local information exposed
- Scientifically
 - Modeling complex physical systems
 - Sharp resolution of interface structures
 - More accurate and efficient in some cases

1-D, Scalar, Linear Hybrid Model

(1) Inflow on Γ

- Local models (boundary layer problem with small viscosity)

$$\begin{cases} v_t + av_x = 0, & x < 0 \\ u_t + bu_x = vu_{xx}, & x > 0 \end{cases}$$
$$v > 0, \quad ab > 0$$

- Interface condition

$$\begin{cases} (bu - vu_x)|_{\Gamma} = (av)|_{\Gamma}, & \text{(flux continuity)} \\ av|_{\Gamma} = bu|_{\Gamma}, \text{ if } a < 0, & \text{(inflow and solution continuity)} \end{cases}$$

$$\Rightarrow u_x|_{\Gamma} = 0$$

- Boundary conditions

$$u(t, \tau) = u_{\tau} \text{ (boundary layer with thickness } \tau \text{)}$$

- Initial condition consistent with the boundary and interface conditions
- Fully decoupled: Viscous->inviscid

1-D, Scalar, Linear Hybrid Model

(2) Outflow on Γ

- Local models: Same as before, but with $a>0$, $b>0$
- Interface condition

$$(bu - vu_x)|_{\Gamma} = (av)|_{\Gamma}, \quad (\text{flux continuity})$$

- Boundary conditions

$$v(t, -1) = v_a \quad (\text{inflow})$$

$$u(t, \tau) = 0 \quad (\text{boundary layer with thickness } \tau)$$

- Fully decoupled: inviscid \rightarrow viscous

Steady State (Outflow on Γ)

- Exact solution

$$v(x) = v_a, x \leq 0$$

$$u(x) = \frac{a}{b} v |_{\Gamma} (1 - e^{-\frac{b(x-\tau)}{v}}), x \geq 0$$

- Boundary layer

$$\tau = O(v^\alpha), 0 < \alpha < 1$$

- Discontinuity at the interface

$$\begin{aligned} u |_{\Gamma} &= \frac{a}{b} v |_{\Gamma} (1 - e^{-\frac{b}{v^{(1-\alpha)}}}) \\ &\approx \frac{a}{b} v |_{\Gamma} \end{aligned}$$

Algorithm

- Inviscid solver
 - Upwind scheme
 - Explicit computation
- Viscous solver
 - Central difference plus upwind for the elliptic operator
 - Forward difference for interface condition with input from the inviscid solver
- Fully decoupled computation for different models
- **Cheap** inviscid computation with “large” spacing
- **Sharp** boundary layer structure with few grid points

Extensions

- HDD of D-N type (Quateroni, et al)
 - Linear
 - 2-D, steady state or unsteady state with continuous solutions
 - Discontinuous solutions?
 - Nonlinear?
 - Linearization+HDD

Hybrid Burgers Equations

- Simplified 1-D model for standing shock-boundary layer interaction

Conservation laws $\begin{cases} u_t + \left(\frac{1}{2}u^2\right)_x = 0 \\ v_t + \left(\frac{1}{2}v^2\right)_x = \varepsilon v_{xx}, \quad \varepsilon > 0, \end{cases}$

- Boundary condition: $u(x_l) = 1, v(x_r) = -1$
- Interface conditions

$$\begin{cases} \frac{1}{2}u^2|_\Gamma = \left(\frac{1}{2}v^2 - \varepsilon v_x\right)|_\Gamma, & \text{(flux continuity)} \\ \frac{1}{2}u^2|_\Gamma = \frac{1}{2}v^2|_\Gamma, & \text{(Rankine - Hugoniot condition)} \end{cases}$$

- Vs. traditional domain decomposition framework
 - Local models
 - Interface condition
- Fully decoupled in special cases such as 1-D steady state

Framework of Interface Relaxation

- Select interface variables, say $\mathbf{W} = \begin{bmatrix} \mathbf{u}|_{\Gamma} \\ \mathbf{v}|_{\Gamma} \end{bmatrix}$
- \mathbf{W} is the solution implicitly defined by the interface conditions $\mathbf{F}(\mathbf{W}) = 0$
- Evaluation of $\mathbf{F}(\mathbf{W})$ usually involves local PDE solvers
- Relaxation with the approximation of \mathbf{W} at the interface (preconditioned “R-F” or residual correction on interface)

$$\mathbf{W}^{n+1} = \mathbf{W}^n - \mathbf{P}\mathbf{F}(\mathbf{W}^n)|_{\Gamma}, n = 0, 1, 2, \dots,$$

where \mathbf{P} is a preconditioner

Local solver 1: Inviscid Solver

- Conservation law

$$\frac{\partial u}{\partial t} + \frac{\partial f(u)}{\partial x} = 0 \quad f(u) = \frac{1}{2}u^2$$

- Godunov Scheme

- Riemann solver for each pair of adjacent cells
(modified with the last cell at the interface)

$$\begin{cases} u_t + (f(u))_x = 0, & x_{j-\frac{1}{2}} < x < x_{j+\frac{3}{2}}, \quad t^n \leq t \leq t^{n+1} \\ u(x, 0) = u_0(x) = \begin{cases} U_l = U_j^n, & \text{if } x_{j-\frac{1}{2}} < x < x_{j+\frac{1}{2}} \\ U_r = U_{j+1}^n, & \text{if } x_{j+\frac{1}{2}} < x < x_{j+\frac{3}{2}} \end{cases} \end{cases}$$

- Cell average update locally on the current time level

$$U_j^{n+1} = U_j^n - \frac{\Delta t}{\Delta x} [f(u_{RP}(x_{j+\frac{1}{2}}, t)) - f(u_{RP}(x_{j-\frac{1}{2}}, t))]$$

Local Solver 2: Viscous Solver

- Viscous flow model

$$v_t + \left(\frac{1}{2}v^2\right)_x = \epsilon v_{xx}, \epsilon > 0, \text{ where } f(v) = \frac{1}{2}v^2 - \epsilon v_x$$

- Explicit scheme
- Spatial discretization:
 - convection term: upwind
 - viscous term: central finite difference
- Update local solution on the current time level

Relaxation with Newton-type Preconditioner

- Interface condition

$$\begin{cases} \frac{1}{2}u_{\Gamma}^2 - \left(\frac{1}{2}v_{\Gamma}^2 - \mathcal{E}\frac{v_1 - v_{\Gamma}}{h_r}\right) = 0, & \text{(flux continuity)} \\ \frac{1}{2}u_{\Gamma}^2 - \frac{1}{2}v_{\Gamma}^2 = 0, & \text{(Rankine - Hugoniot condition)} \end{cases}$$

- Relaxation with “Newton iteration”

$$- P = J^{-1}(W^{(n)})$$

$$\begin{bmatrix} u_{\Gamma} \\ v_{\Gamma} \end{bmatrix}^{(n+1)} = \begin{bmatrix} u_{\Gamma} \\ v_{\Gamma} \end{bmatrix}^{(n)} + \begin{bmatrix} \frac{1}{2} \frac{[(v_{\Gamma}^{(n)})^2 - (u_{\Gamma}^{(n)})^2] + 2v_{\Gamma}^{(n)}(v_1 - v_{\Gamma}^{(n)})}{u_{\Gamma}^{(n)}} \\ v_1 - v_{\Gamma}^{(n)} \end{bmatrix}$$

Relaxation with Newton-type Preconditioner

- Interface condition

$$\begin{cases} \frac{1}{2}u_{\Gamma}^2 - \left(\frac{1}{2}v_{\Gamma}^2 - \mathcal{E}\frac{v_1 - v_{\Gamma}}{h_r}\right) = 0, & \text{(flux continuity)} \\ \frac{1}{2}u_{\Gamma}^2 - \frac{1}{2}v_{\Gamma}^2 = 0, & \text{(Rankine - Hugoniot condition)} \end{cases}$$

- Relaxation with “Newton iteration”

$$\begin{bmatrix} u_{\Gamma} \\ v_{\Gamma} \end{bmatrix}^{(n+1)} = \begin{bmatrix} u_{\Gamma} \\ v_{\Gamma} \end{bmatrix}^{(n)} - PF\left(\begin{bmatrix} u_{\Gamma} \\ v_{\Gamma} \end{bmatrix}^{(n)}\right)$$

- $P = J^{-1}(W^{(n)})$

Numerical Experiments

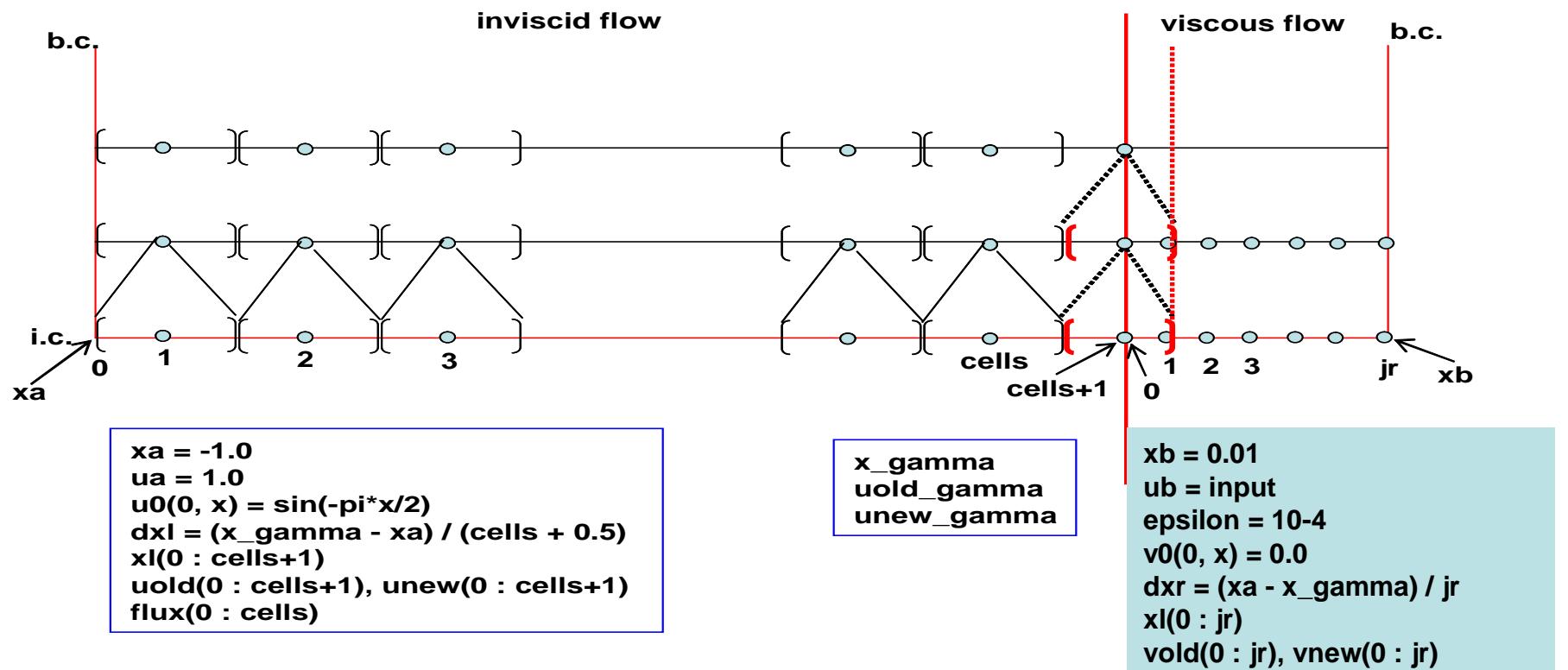
- Boundary condition:
 $U_a = 1, V_b = -1$
- Unique solution of the steady state
 - Continuous locally
 - Standing shock at the interface
 $U(x) = 1, V(x) = -1$
- Initial conditions: Set A and Set B

$$\begin{cases} u_0(x) = 1.0, & -1.0 \leq x \leq 0.0 \\ v_0(x) = -200x + 1.0, & 0.0 \leq x \leq 0.01 \end{cases} \quad \begin{cases} u_0(x) = \sin(-\frac{\pi x}{2}), & -1.0 \leq x \leq 0.0 \\ v_0(x) = -50x - 0.5, & 0.0 \leq x \leq 0.01 \end{cases}$$

Set A	time step = 24979	Set B	time step = 601
Inviscid flow part		Inviscid flow part	
<pre> unew(0) = 1.00000000 unew(1) = 1.00000000 unew(2) = 1.00000000 unew(3) = 1.00000000 unew(4) = 1.00000000 unew(5) = 1.00000000 unew(6) = 1.00000000 unew(7) = 1.00000000 unew(8) = 1.00000000 unew(9) = 1.00000000 unew(10) = 1.00000000 unew(11) = 1.00000000 unew(12) = 1.00000000 unew(13) = 1.00000000 unew(14) = 1.00000000 unew(15) = 1.00000000 unew(16) = 1.00000000 unew(17) = 1.00000000 unew(18) = 1.00000000 unew(19) = 1.00000000 unew(20) = 1.00000000 unew(21) = .99999922 </pre>		<pre> unew(0) = 1.00000000 unew(1) = 1.00000000 unew(2) = 1.00000000 unew(3) = 1.00000000 unew(4) = 1.00000000 unew(5) = 1.00000000 unew(6) = 1.00000000 unew(7) = 1.00000000 unew(8) = 1.00000000 unew(9) = 1.00000000 unew(10) = 1.00000000 unew(11) = 1.00000000 unew(12) = 1.00000000 unew(13) = 1.00000000 unew(14) = 1.00000000 unew(15) = .99999999 unew(16) = .99999997 unew(17) = .99999988 unew(18) = .99999948 unew(19) = .99999765 unew(20) = .99998921 unew(21) = 1.00000000 </pre>	
Viscous flow part		Viscous flow part	
<pre> vnew(0) = -.99999922 vnew(1) = -.99999922 vnew(2) = -.99999964 vnew(3) = -.99999987 vnew(4) = -.99999996 vnew(5) = -.99999999 vnew(6) = -1.00000000 vnew(7) = -1.00000000 vnew(8) = -1.00000000 vnew(9) = -1.00000000 vnew(10) = -1.00000000 </pre>		<pre> vnew(0) = -1.00000000 vnew(1) = -1.00000000 vnew(2) = -1.00000000 vnew(3) = -1.00000000 vnew(4) = -1.00000000 vnew(5) = -1.00000000 vnew(6) = -1.00000000 vnew(7) = -1.00000000 vnew(8) = -1.00000000 vnew(9) = -1.00000000 vnew(10) = -1.00000000 </pre>	

Hybrid Burgers Equation

- Modified HMM (Engquist, E)
- Interface Relaxation
 - Local solvers: (Inviscid, Viscous)
 - Interface Relaxed: Finite volume



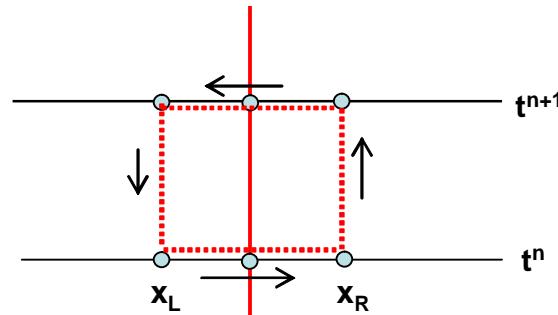
Interface Treatment

- Finite volume

$$U_{\Gamma}^{n+1} = U_{\Gamma}^n - \frac{\Delta t}{(x_R - x_L)} (f_R^{n+\frac{1}{2}} - f_L^{n+\frac{1}{2}})$$

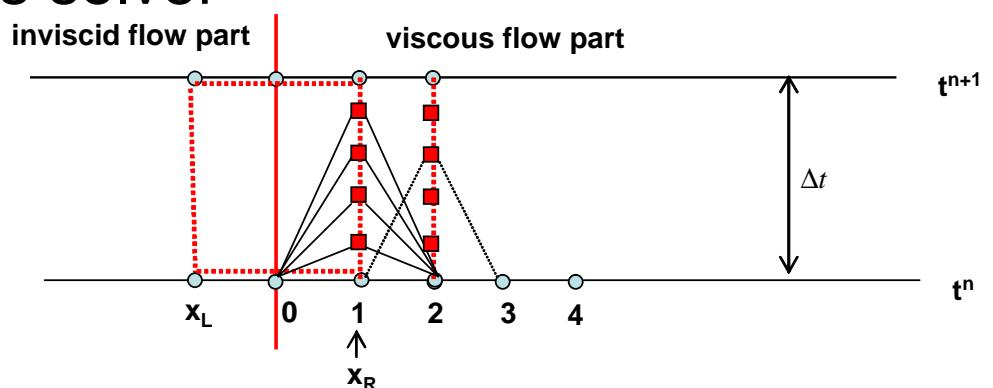
- Information from inviscid solver

$$\begin{aligned} f_L^{n+\frac{1}{2}} &\approx \frac{1}{\Delta t} \int_{t^n}^{t^{n+1}} f(u_{RP}(x_L, t)) dt \\ &= \frac{1}{\Delta t} f(u_{RP}(x_L, t^{n+1})) \Delta t \quad (\text{since } u_{RP}(x_L, t) \text{ is constant at } t^n \leq t \leq t^{n+1}) \\ &= f(u_{RP}(x_L, t^{n+1})) \end{aligned}$$



- Information from viscous solver

$$f_R^{n+\frac{1}{2}} = \frac{1}{\Delta t} \int_{t^n}^{t^{n+1}} \tilde{f}(v(x_R, t)) dt$$



Set A dt = 0.0004, time step = 73

Inviscid flow part

```
unew( 0 ) = 1.000000
unew( 1 ) = 1.000000
unew( 2 ) = 1.000000
unew( 3 ) = 1.000000
unew( 4 ) = 1.000000
unew( 5 ) = 1.000000
unew( 6 ) = 1.000000
unew( 7 ) = 1.000000
unew( 8 ) = 1.000000
unew( 9 ) = 1.000000
unew( 10 ) = 1.000000
unew( 11 ) = 1.000000
unew( 12 ) = 1.000000
unew( 13 ) = 1.000000
unew( 14 ) = 1.000000
unew( 15 ) = 1.000000
unew( 16 ) = 1.000000
unew( 17 ) = 1.000000
unew( 18 ) = 1.000000
unew( 19 ) = 1.000000
unew( 20 ) = 1.000000
unew( 21 ) = 1.000001
```

Viscous flow part

```
vnew( 0 ) = 1.000001
vnew( 1 ) = .999990
vnew( 2 ) = .999866
vnew( 3 ) = .998501
vnew( 4 ) = .983498
vnew( 5 ) = .819807
vnew( 6 ) = -.819817
vnew( 7 ) = -.983507
vnew( 8 ) = -.998511
vnew( 9 ) = -.999876
vnew( 10 ) = -1.000000
```

Set 2

dt = 0.0004

time step = 406

Inviscid flow part

```
unew( 0 ) = 1.00000000
unew( 1 ) = 1.00000000
unew( 2 ) = 1.00000000
unew( 3 ) = 1.00000000
unew( 4 ) = 1.00000000
unew( 5 ) = 1.00000000
unew( 6 ) = 1.00000000
unew( 7 ) = .99999999
unew( 8 ) = .99999996
unew( 9 ) = .99999976
unew( 10 ) = .99999879
unew( 11 ) = .99999433
unew( 12 ) = -.36233667
unew( 13 ) = -.99999925
unew( 14 ) = -.99999989
unew( 15 ) = -.99999999
unew( 16 ) = -1.00000000
unew( 17 ) = -1.00000000
unew( 18 ) = -1.00000000
unew( 19 ) = -1.00000000
unew( 20 ) = -1.00000000
unew( 21 ) = -1.00000000
```

Viscous flow part

```
vnew( 0 ) = -1.00000000
vnew( 1 ) = -1.00000000
vnew( 2 ) = -1.00000000
vnew( 3 ) = -1.00000000
vnew( 4 ) = -1.00000000
vnew( 5 ) = -1.00000000
vnew( 6 ) = -1.00000000
vnew( 7 ) = -1.00000000
vnew( 8 ) = -1.00000000
vnew( 9 ) = -1.00000000
vnew( 10 ) = -1.00000000
```

Computational Components of Interface Relaxation

- A collection of fully decoupled local solvers
 - Provided by whatever best services available on grid nodes
 - With their own
 - Geometric domains
 - Physical models
 - Computational methods

Computational Components of Interface Relaxation (cont'd)

- Interface relaxer
 - Provided by the client or host server
 - Limited development and computational overhead
 - Global coupling and central control
 - Invoke local solvers with the available interface information
 - Collect the computed boundary information from local solvers
 - Update interface information with preconditioned residual correction or alike to relax the interface constraints
 - Iterate until the interface conditions are all satisfied

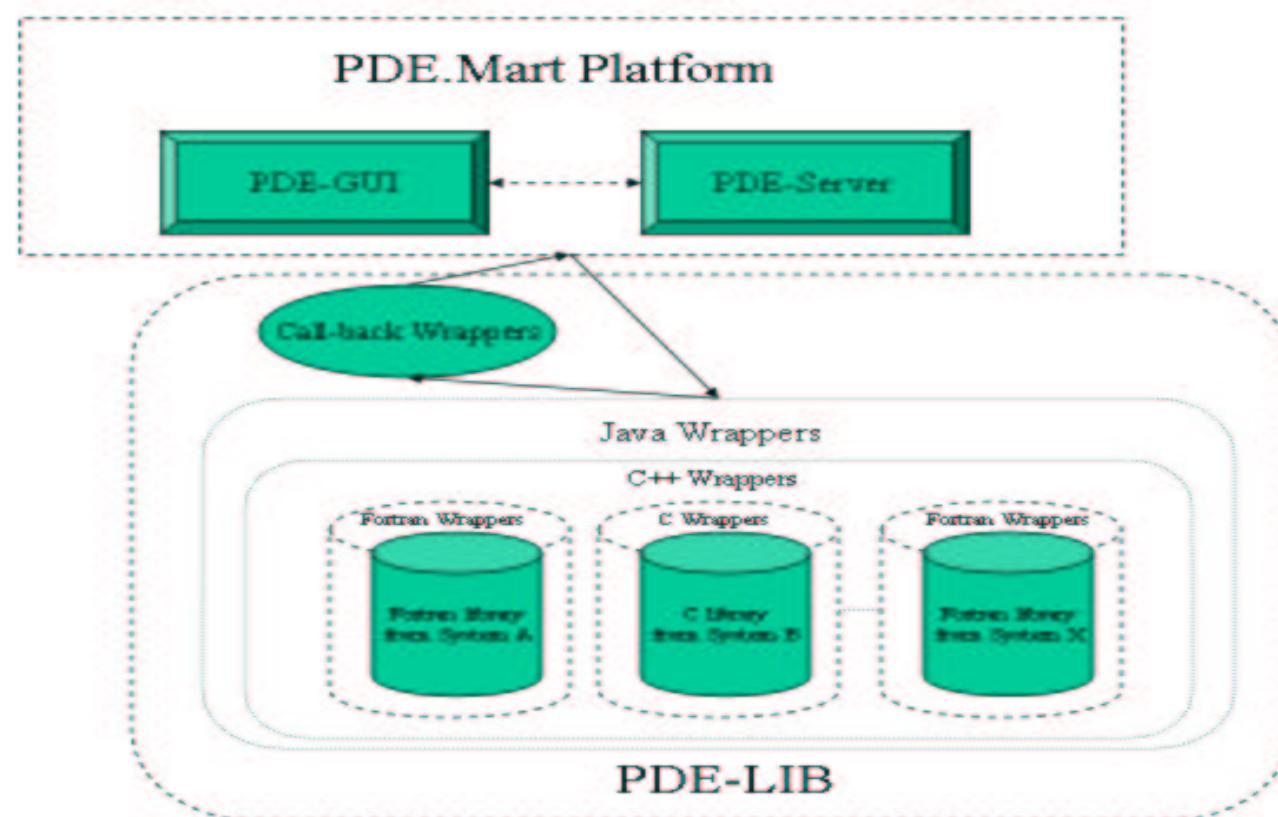
Changing Face of Mathematical Software

To cope with the changes in

- Computing platforms
- Scientific modeling
- Computational methodologies



System Structure



PDE.Mart

- Network-based PSE à Grid computing
- Client-server protocol
 - Building relaxer
 - Distributing and deploying local solvers
- Object-oriented Java platform
 - PDE solving objects: Domain, PDE, Mesh, Discrete, Indexing, Solution
 - Plug-and-play
 - Local solver composition
 - Computational steering
- Software integration with native codes from multi-sources and in multi-languages
 - PDE-API
 - API-based wrapper framework