



# *Standard Problems and Public Code for Micromagnetics*

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Materials Science & Engineering Laboratory, NIST

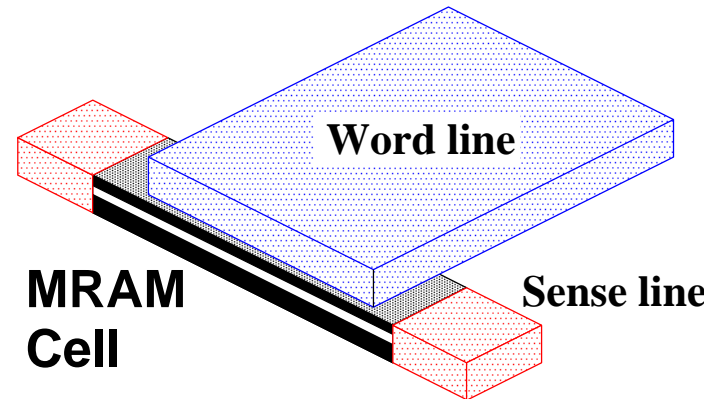
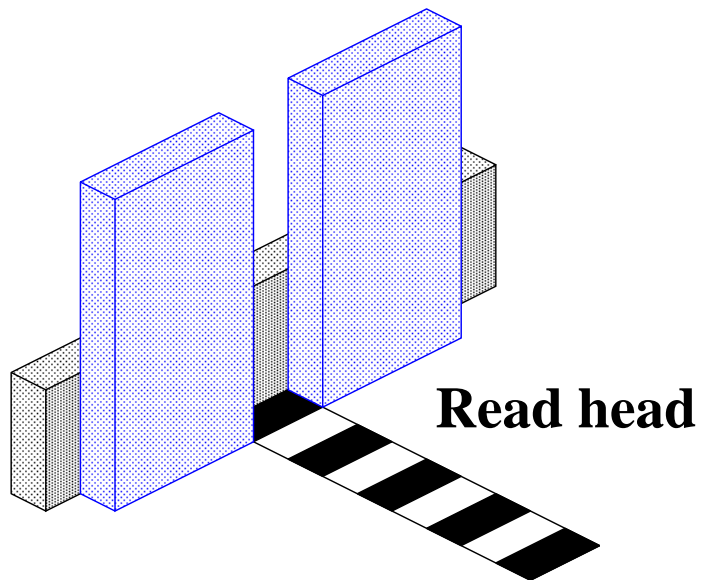


# Overview

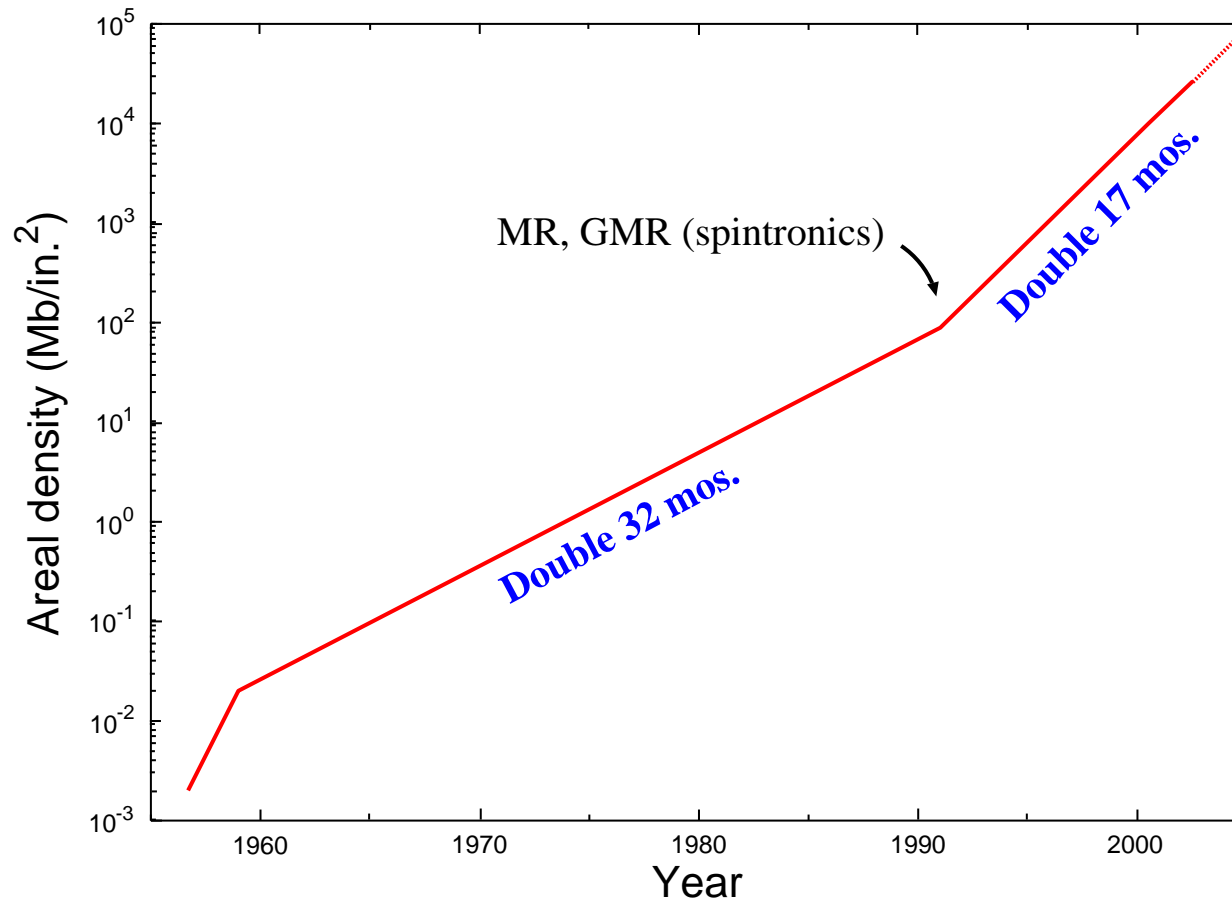
- Micromagnetics background
- $\mu$ MAG
  - Standard problems
  - Public code

# Why Computational Micromagnetics?

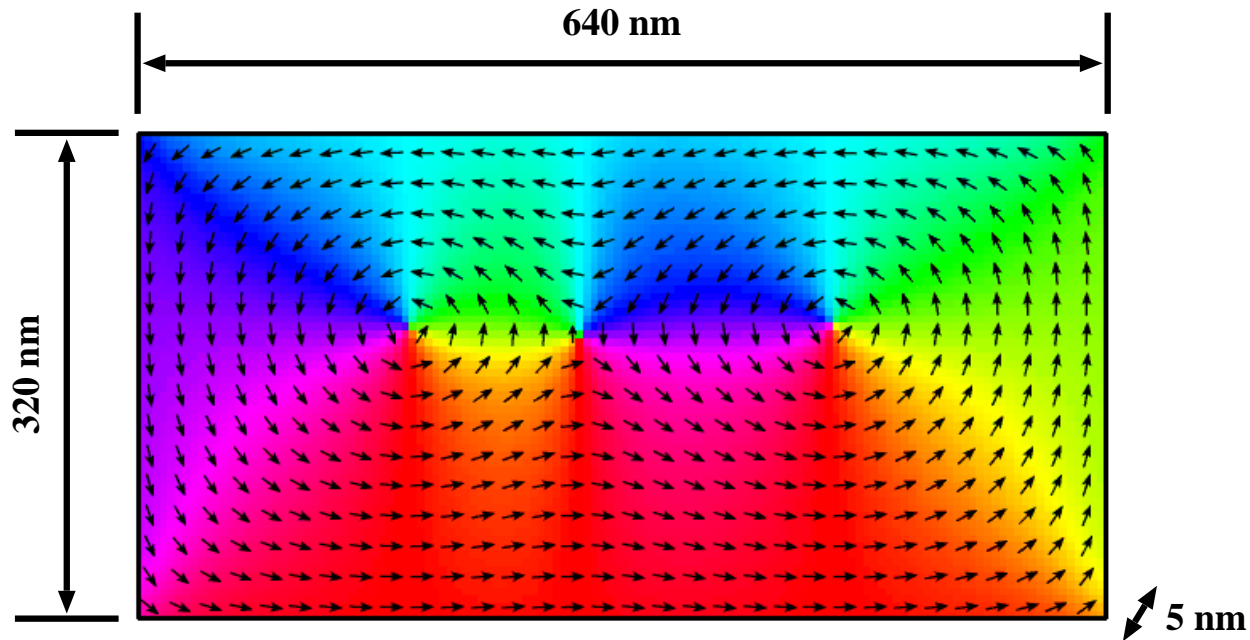
- Disk Drives
- Sensors
- Nonvolatile Memory
- Spintronics



# Magnetic Disk Storage



# Micromagnetics...



... is the study, modeling and simulation of magnetic materials and their behavior at the nanometer scale.

# Brown's Equations

## Energies:

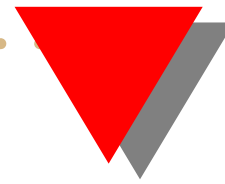
$$E_{\text{exchange}} = \frac{A}{M_s^2} (|\nabla M_x|^2 + |\nabla M_y|^2 + |\nabla M_z|^2)$$

$$E_{\text{anis}} = \frac{K_1}{M_s^2} (\mathbf{M} \cdot \mathbf{u})^2$$

$$E_{\text{demag}} = \frac{\mu_0}{8\pi} \mathbf{M}(r) \cdot \left[ \int_V \nabla \cdot \mathbf{M}(\mathbf{r}') \frac{\mathbf{r} - \mathbf{r}'}{|\mathbf{r} - \mathbf{r}'|^3} d^3 r' - \int_S \hat{\mathbf{n}} \cdot \mathbf{M}(\mathbf{r}') \frac{\mathbf{r} - \mathbf{r}'}{|\mathbf{r} - \mathbf{r}'|^3} d^2 r' \right]$$

$$E_{\text{Zeeman}} = -\mu_0 \mathbf{M} \cdot \mathbf{H}_{\text{ext}}$$

# Magnetization Dynamics



## Landau-Lifshitz-Gilbert:

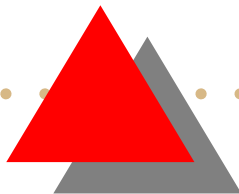
$$\frac{d\mathbf{M}}{dt} = \frac{-\omega}{1 + \lambda^2} \mathbf{M} \times \mathbf{H}_{\text{eff}} - \frac{\lambda \omega}{(1 + \lambda^2) M_s} \mathbf{M} \times (\mathbf{M} \times \mathbf{H}_{\text{eff}})$$

where

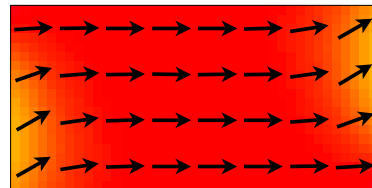
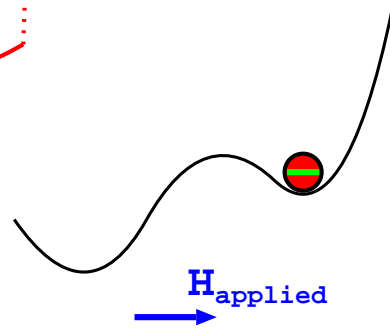
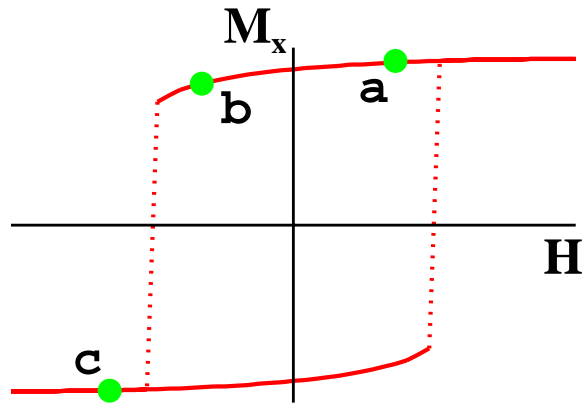
$$\mathbf{H}_{\text{eff}} = -\frac{1}{\mu_0} \frac{\partial E}{\partial \mathbf{M}}$$

$\omega$  = gyromagnetic ratio

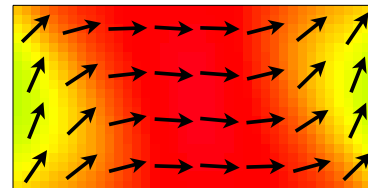
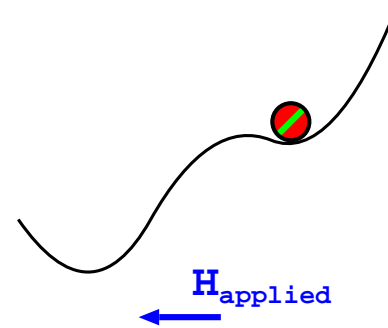
$\lambda$  = damping coefficient



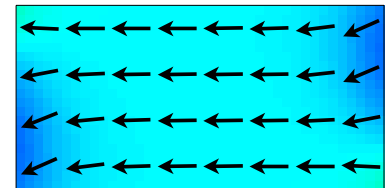
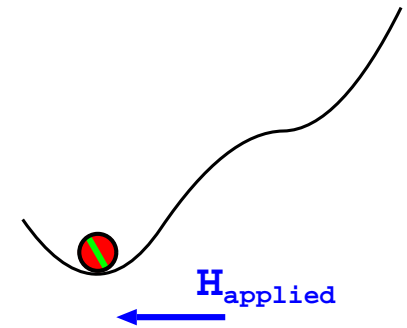
# Quasi-Static Micromagnetics



a



b




c

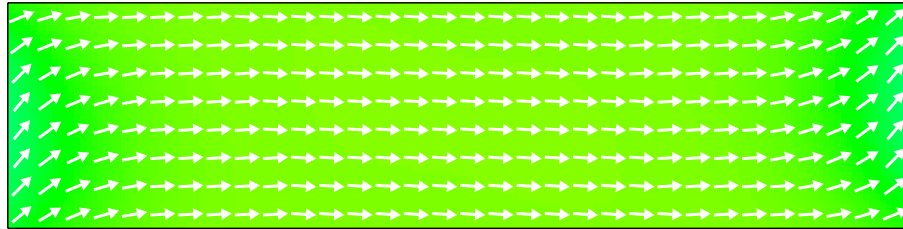


# Magnetization Dynamics

Time

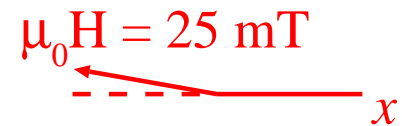
$\mu_0 H = 25 \text{ mT}$   


0 ps

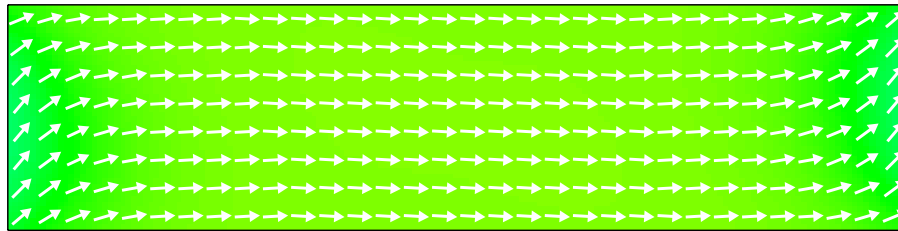


# Magnetization Dynamics

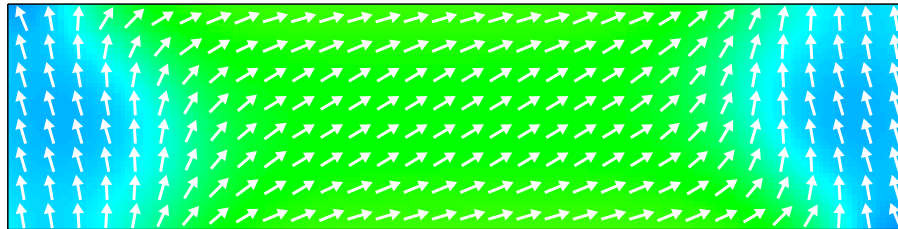
Time

$$\mu_0 H = 25 \text{ mT}$$


0 ps




100 ps

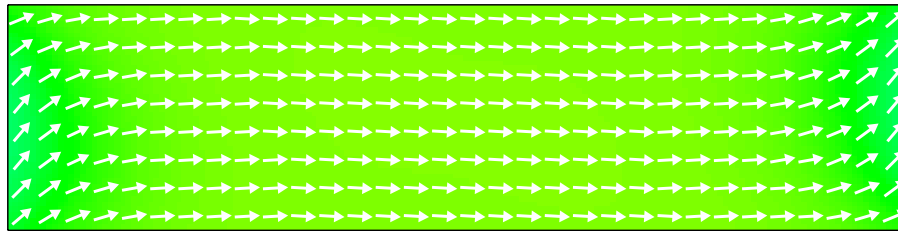


# Magnetization Dynamics

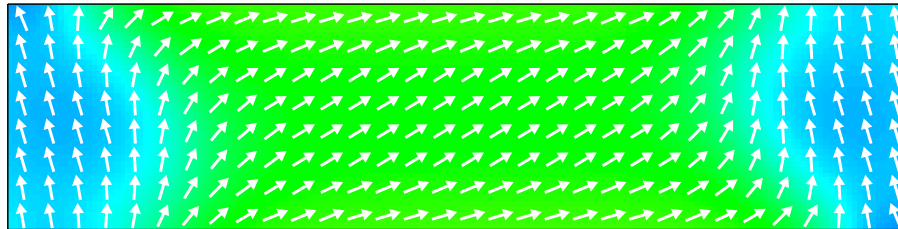
Time

$\mu_0 H = 25 \text{ mT}$   


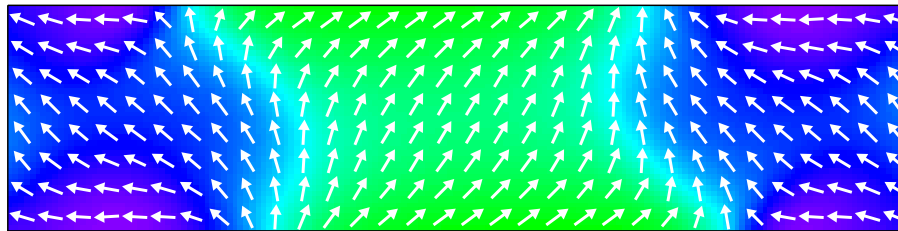
0 ps



100 ps




150 ps

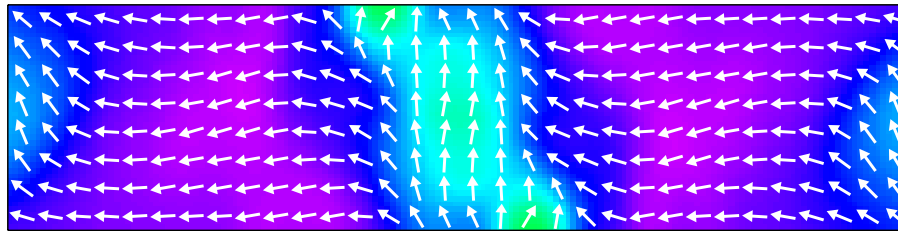


# Magnetization Dynamics

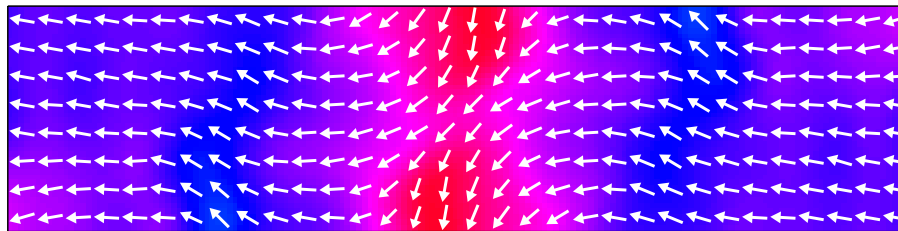
**Time**

$$\mu_0 H = 25 \text{ mT}$$


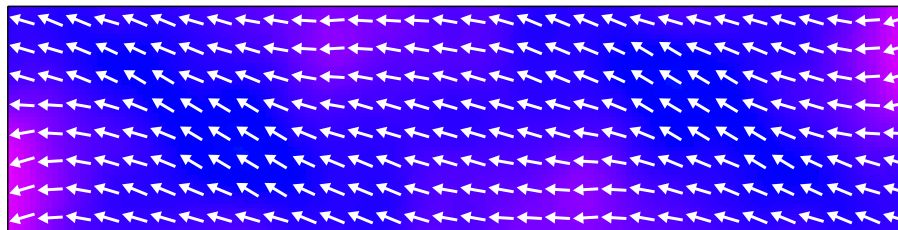
350 ps



450 ps



750 ps



# *Micromagnetics, ca 1995*

- No public or commercial codes

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- Problems and methods poorly specified

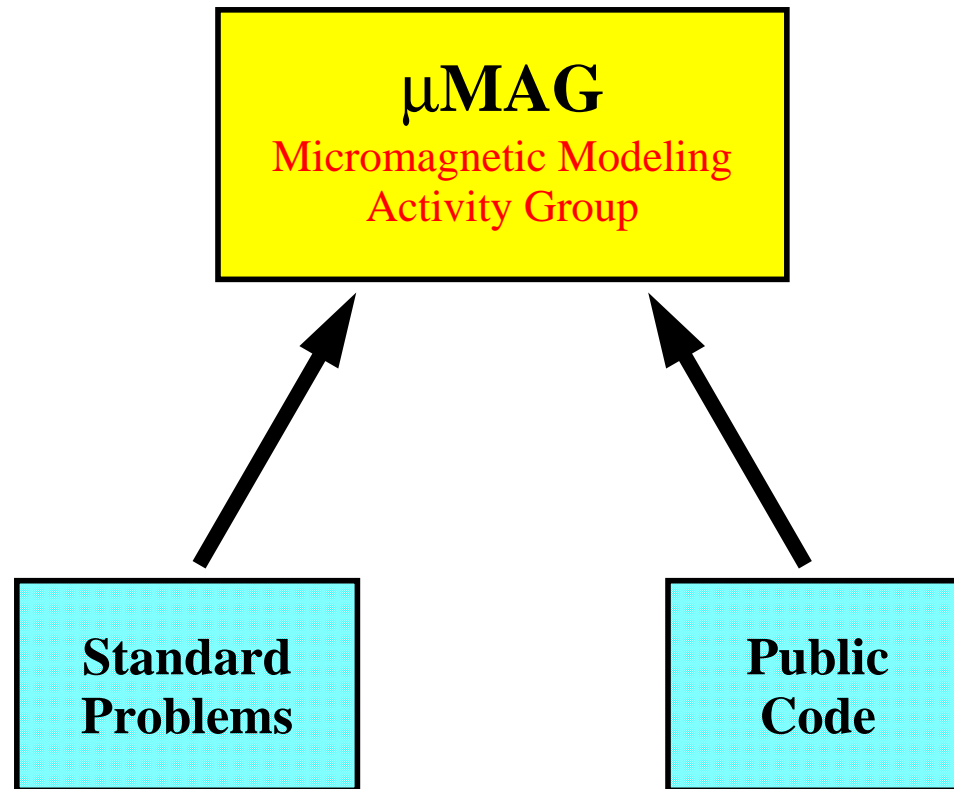


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⇒ Replication of results difficult

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- No public or commercial codes  
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- No two groups working on same problems
- Problems and methods poorly specified  
⇒ Replication of results difficult
- ★ Hard to judge quality of codes and techniques



Center for Theoretical and Computational Materials Science

<http://www.ctcms.nist.gov/>

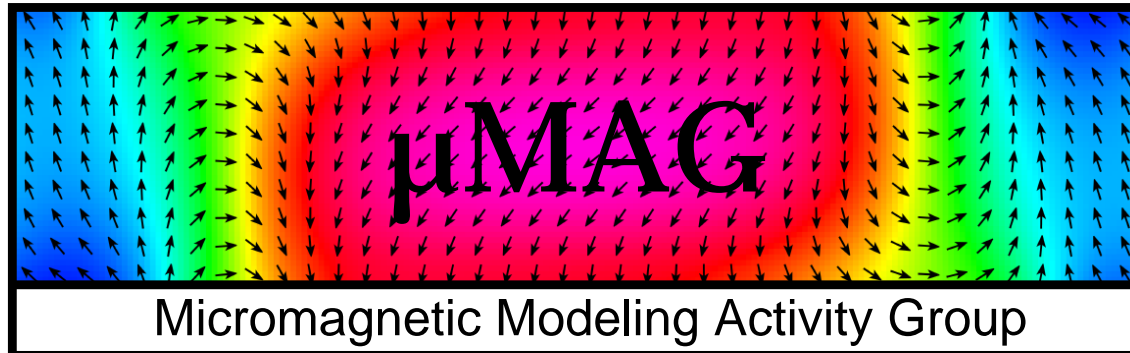
# *$\mu$ MAG Timeline*

- Jan-1995  $\mu$ MAG Steering Committee, Gaithersburg
- Apr-1995 First  $\mu$ MAG Workshop, San Antonio
- Nov-1995  $\mu$ MAG Workshop, Philadelphia
- May-1996 Standard Problem No. 1
- Nov-1996  $\mu$ MAG Workshop, Atlanta
- Mar-1997 Initial public release of mmDisp
- Jan-1998  $\mu$ MAG workshop, San Francisco
- Jan-1998 OOMMF v1.0a0
- Feb-1998 Standard Problem No. 2
- Mar-1998 Standard Problem No. 3
- Aug-1998 Micromagnetics workshop, Boulder
- Oct-1998 OOMMF v1.0b0

# $\mu$ MAG Timeline

- Nov-1998 Standard problem session, MMM/Miami
- Apr-1999 OOMMF v1.1a0
- Feb-2000 Standard Problem No. 4
- Apr-2000 OOMMF v1.1b0
- Aug-2000 OOMMF Workshop, Gaithersburg
- Nov-2000 OOMMF v1.2a0
- Jan-2001 OOMMF v1.2a1
- May-2001 OOMMF v1.2a2
- Oct-2001 OOMMF v1.1b1
- Oct-2002 OOMMF v1.2a3
- Jan-2004  $\mu$ MAG Workshop, Anaheim
- Jan-2004 OOMMF v1.1b2

# Standard Problems



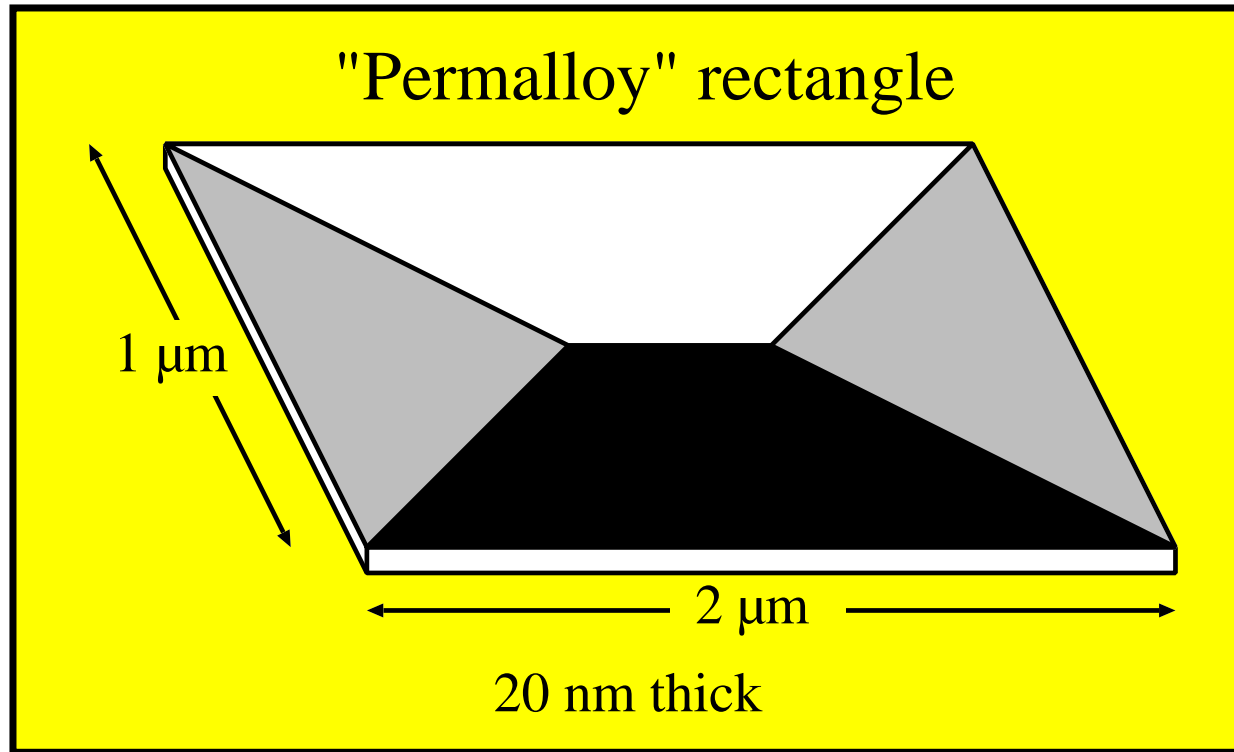
## Four Standard Problems for micromagnetics

<http://www.ctcms.nist.gov/~rdm/mumag.html>

Check computed outputs against contributed solutions:

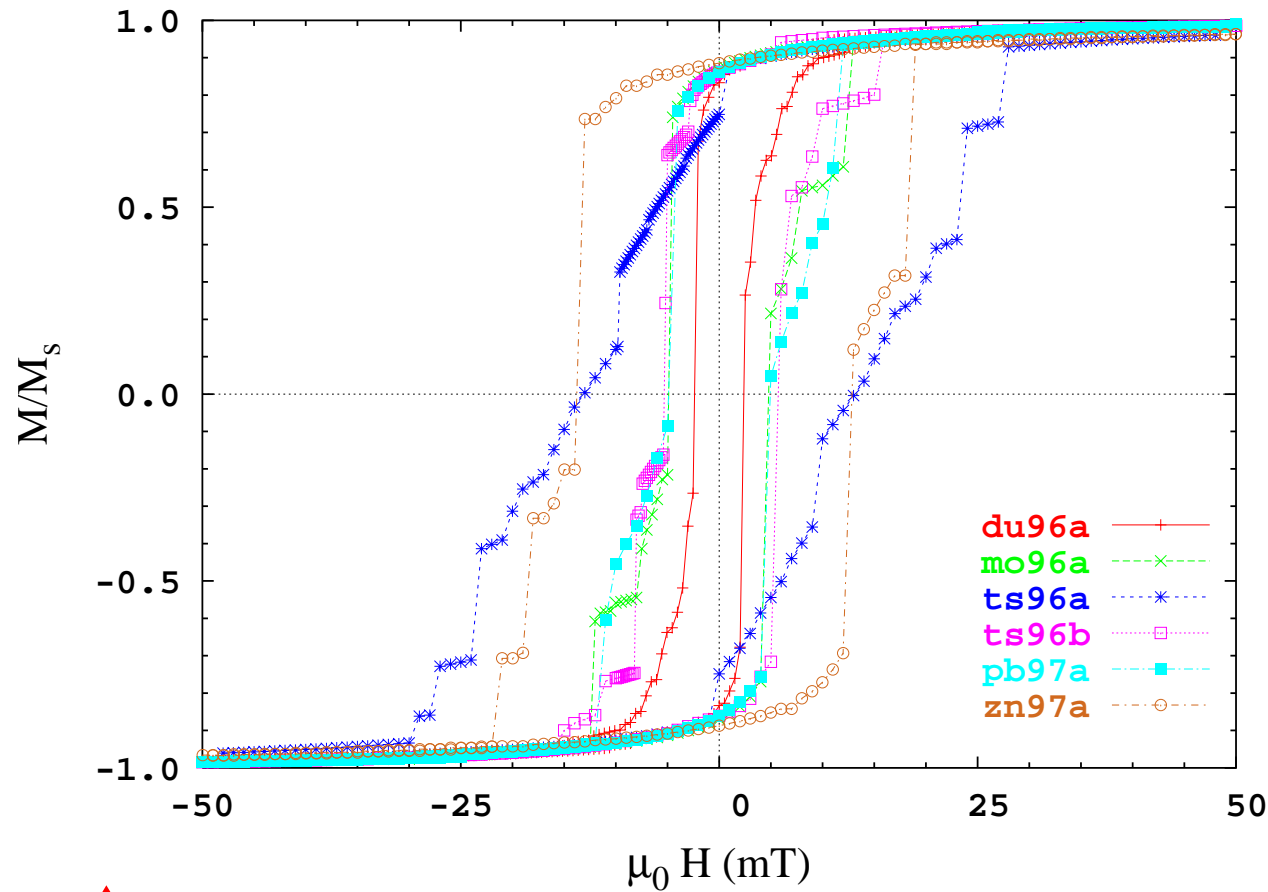
- Verify algorithms
- Compare methods
- Optimize parameters

# $\mu$ MAG Standard Problem #1



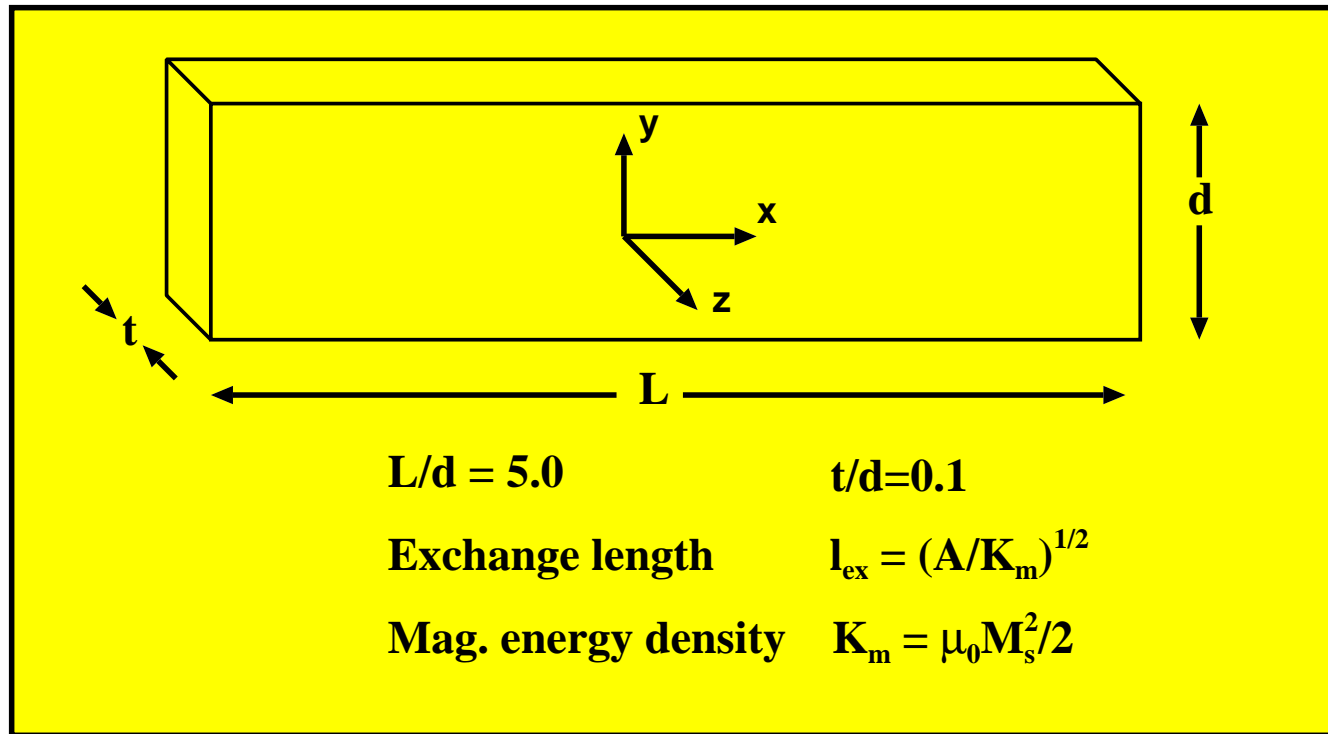
# $\mu$ MAG Standard Problem #1

## Long Axis Hysteresis Loops



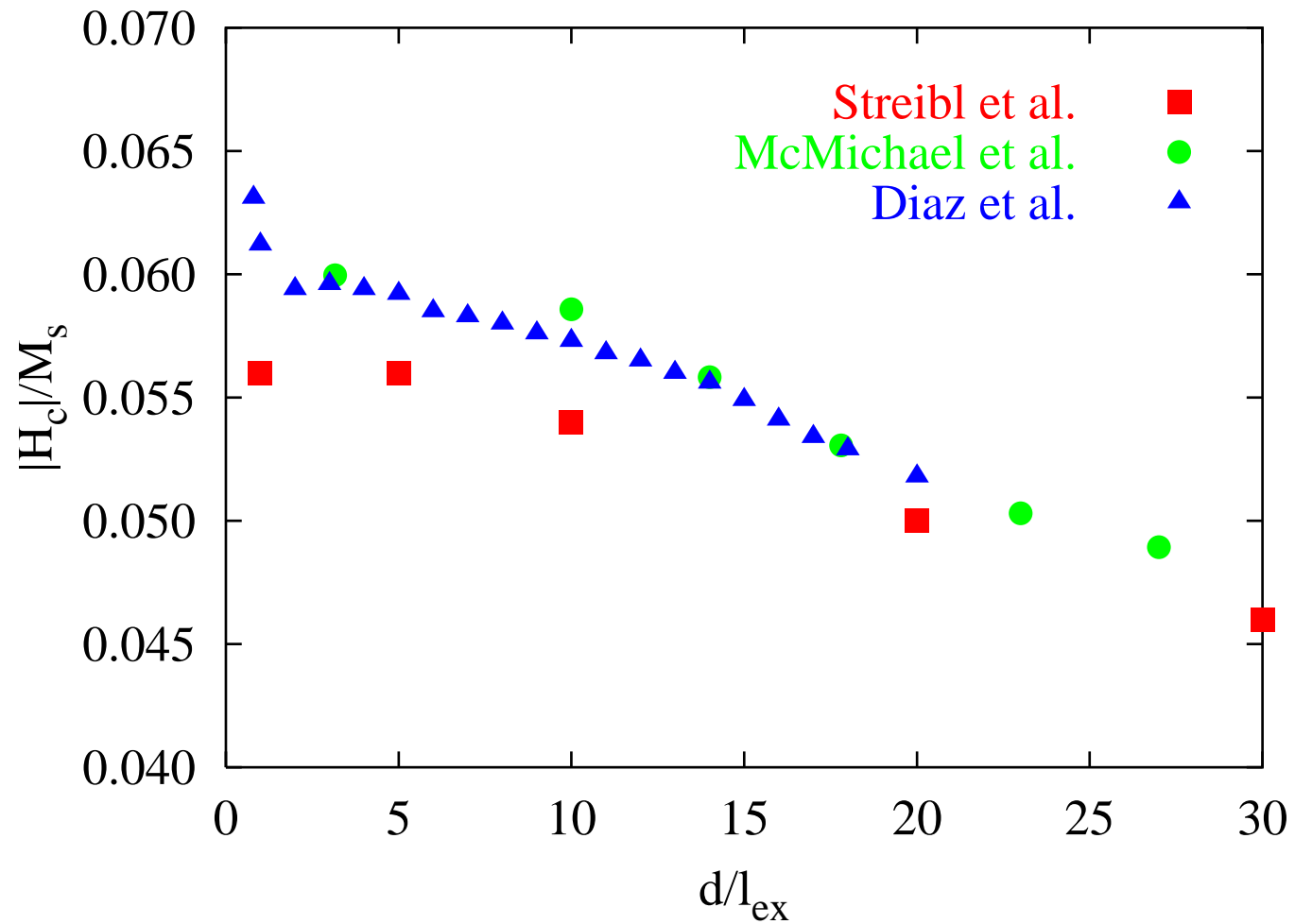


# $\mu$ MAG Problem #2

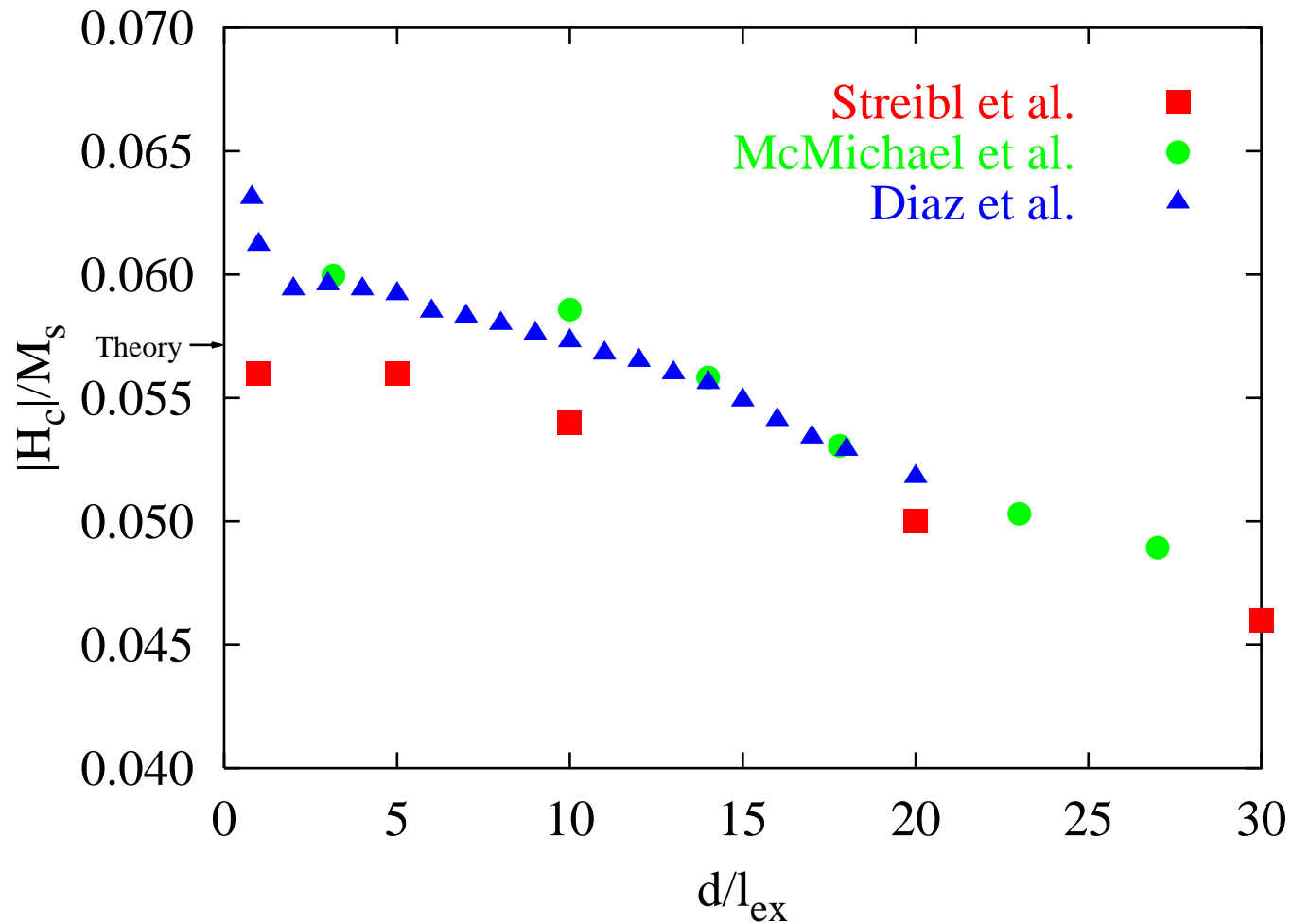


Find coercivity and remanence  
as function of  $d/l_{\text{ex}}$ .

# $\mu$ MAG Problem #2

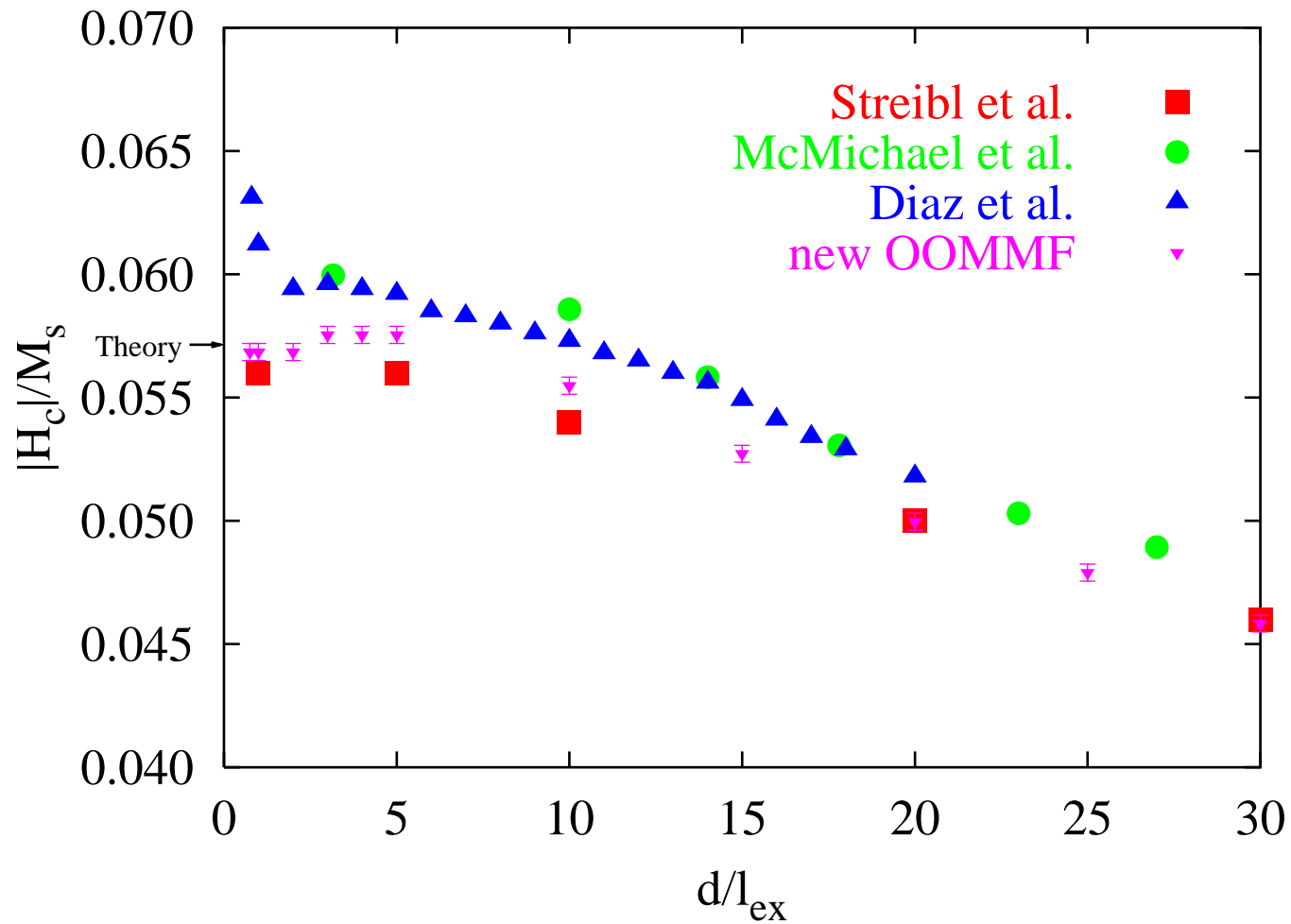


# $\mu$ MAG Problem #2

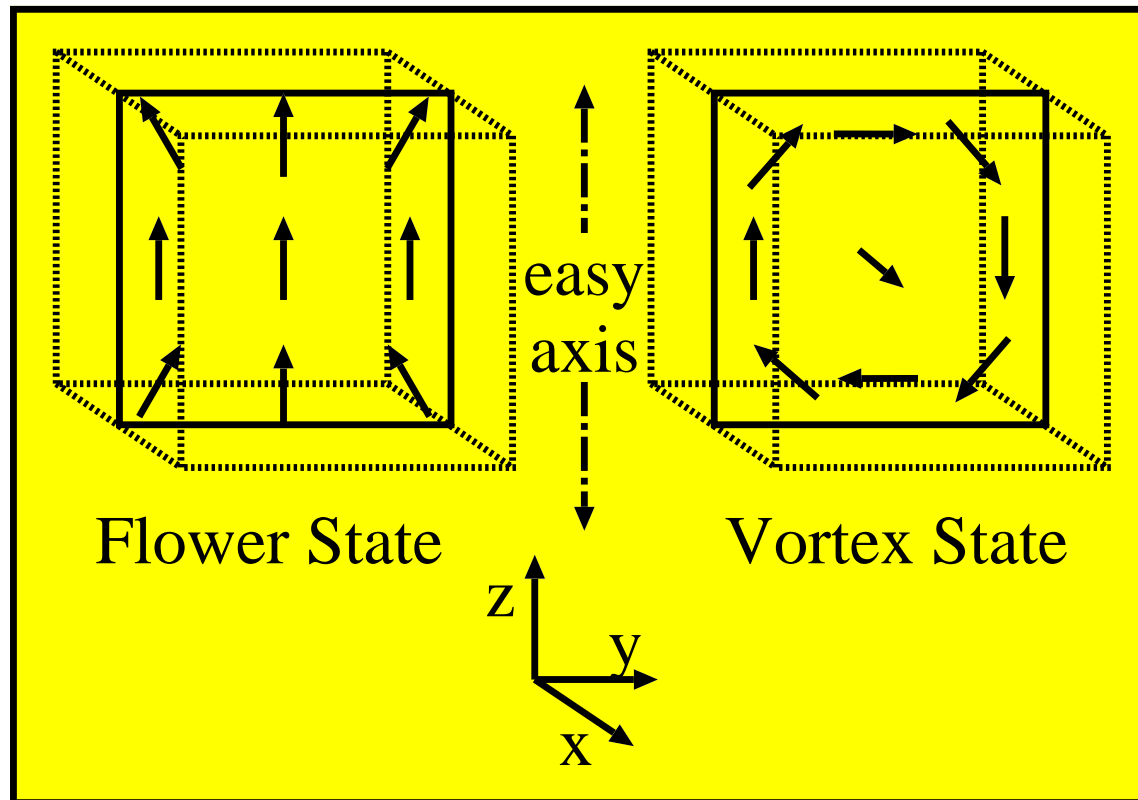


M. J. Donahue and D. G. Porter, *IEEE Trans. Magn.*, **38**, 2468 (2002).

# $\mu$ MAG Problem #2

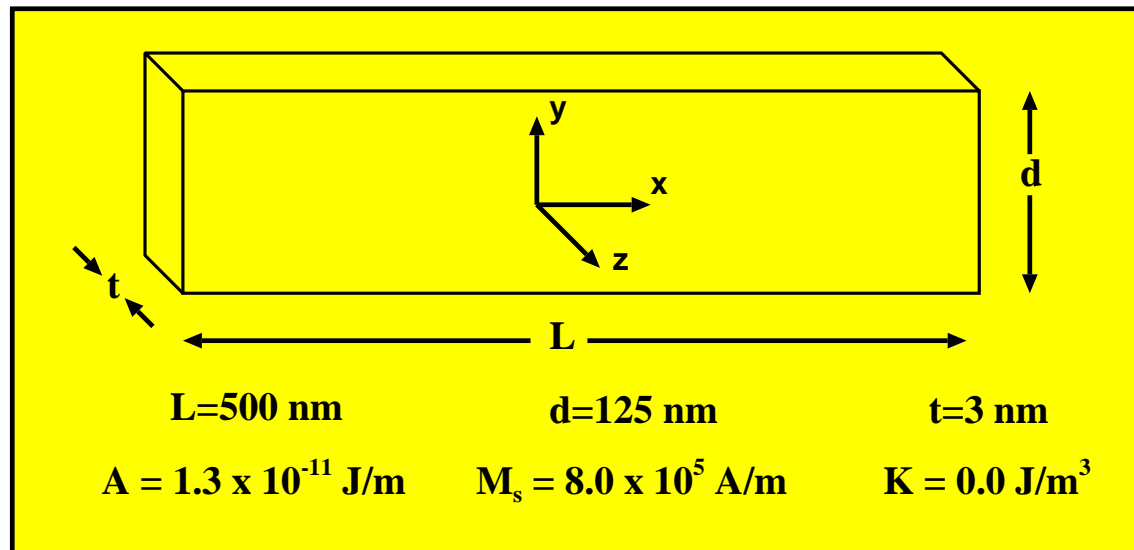


# $\mu$ MAG Problem #3



Compare energies for 2 (3?) states  
as function of cube size.

# $\mu$ MAG Problem #4




LLG Dynamics: plot  $M$  vs.  $t$  for two cases

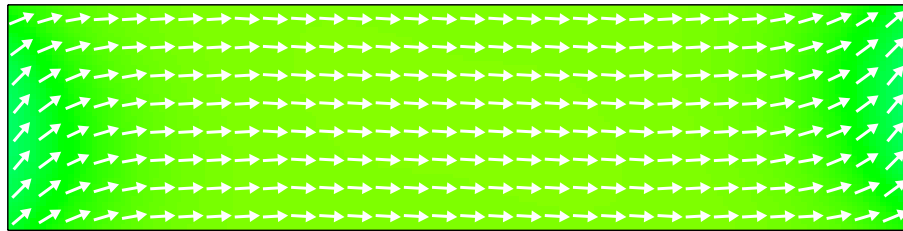
- Field 1: 25 mT,  $170^\circ$  from  $+x$  axis
- Field 2: 36 mT,  $190^\circ$  from  $+x$  axis

# Problem #4a

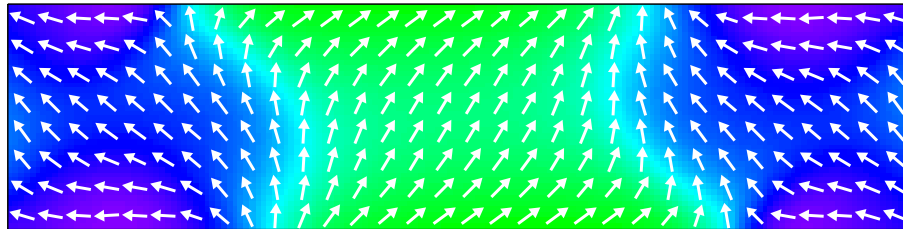
**Time**

$\mu_0 H = 25 \text{ mT}$   


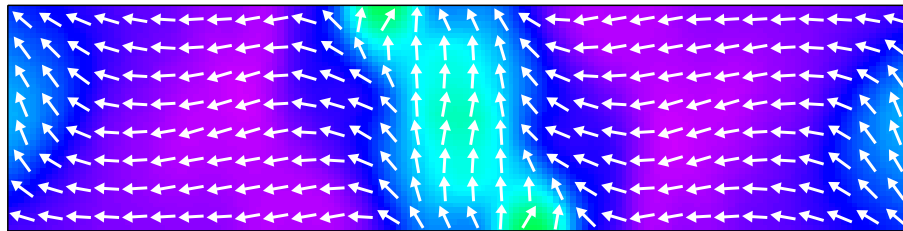
0 ps



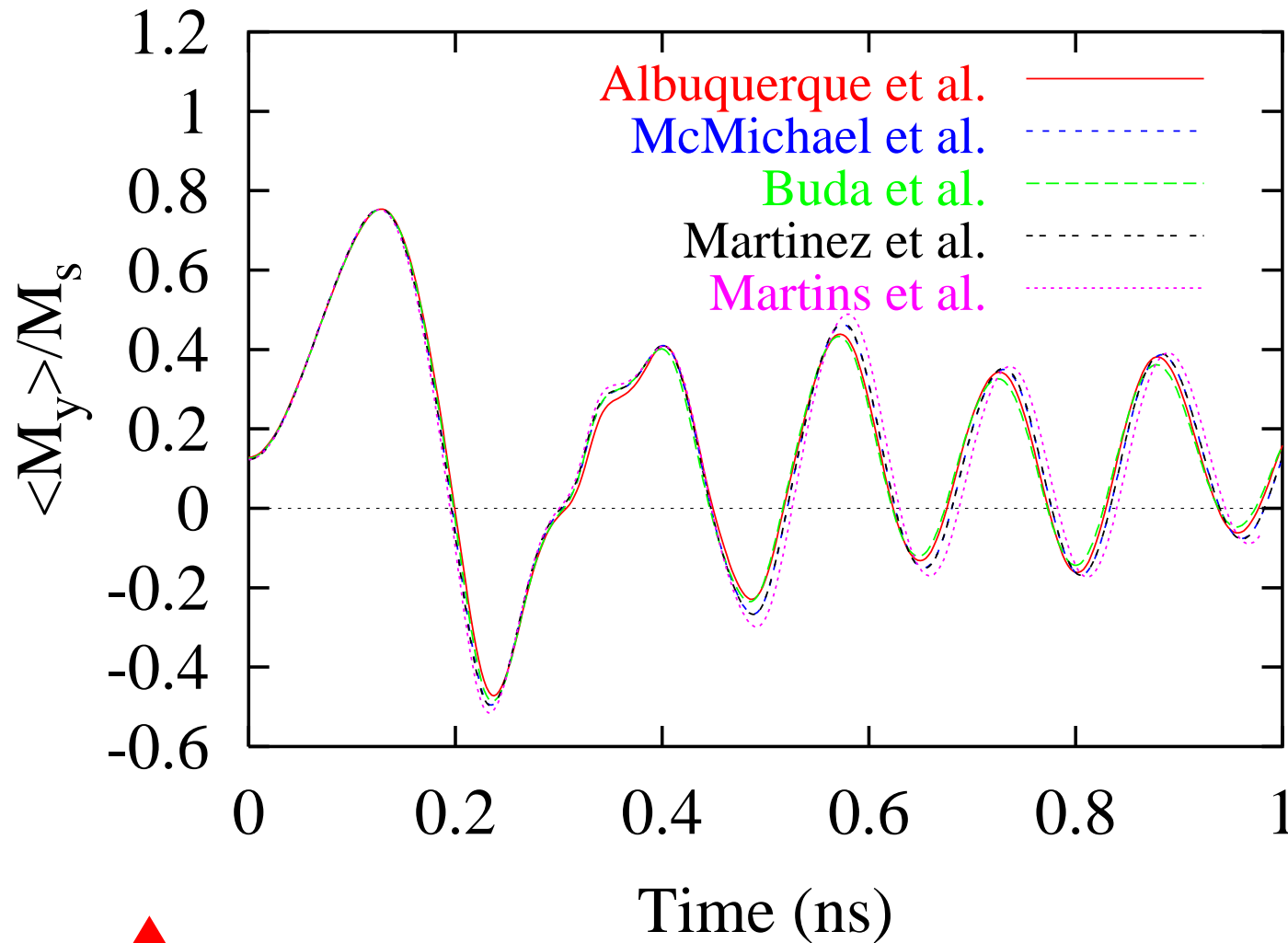
150 ps



350 ps



# Field 1, 170° from +x axis



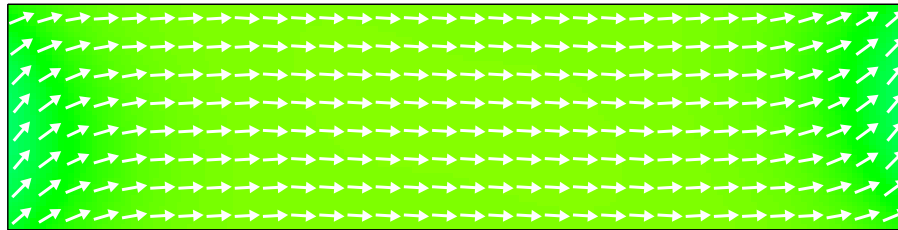


# Problem #4b

Time

0 ps

$\mu_0 H = 36 \text{ mT}$   $x$

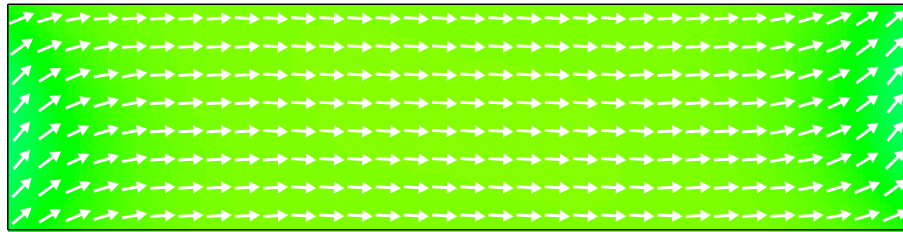


# Problem #4b

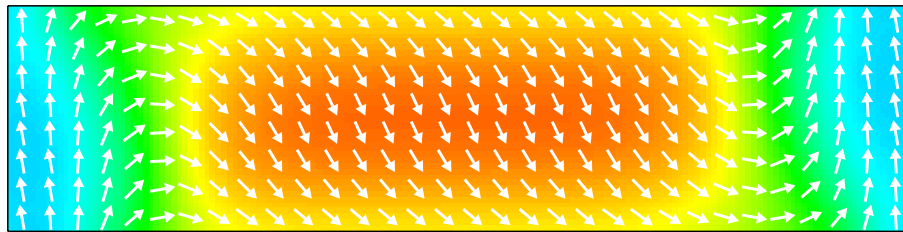
Time

$\mu_0 H = 36 \text{ mT}$   $x$

0 ps



100 ps

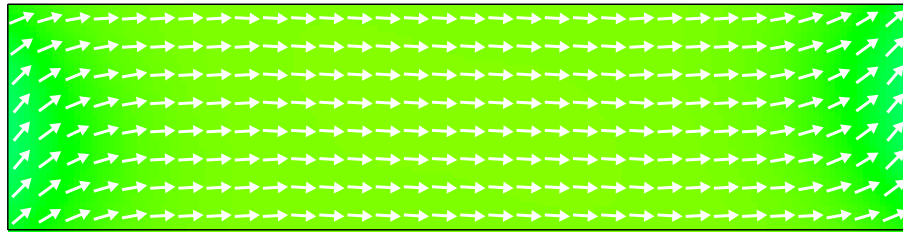


# Problem #4b

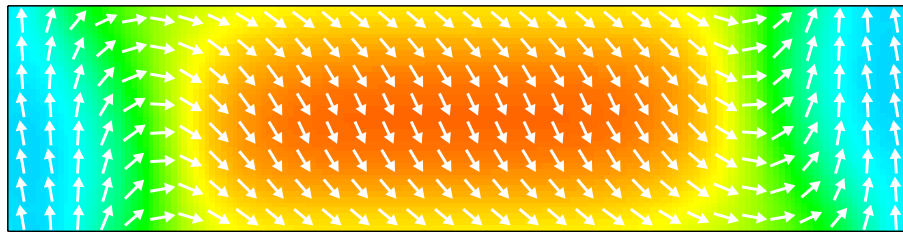
Time

$\mu_0 H = 36 \text{ mT}$   $x$

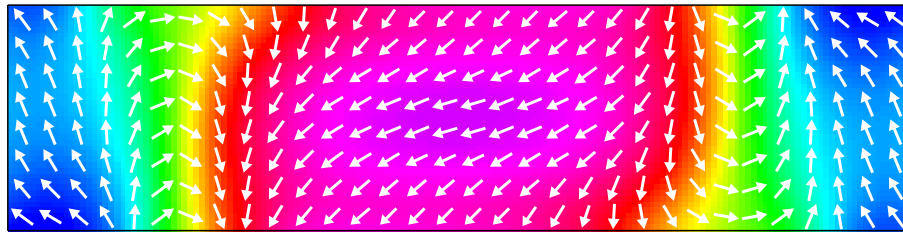
0 ps



100 ps



150 ps

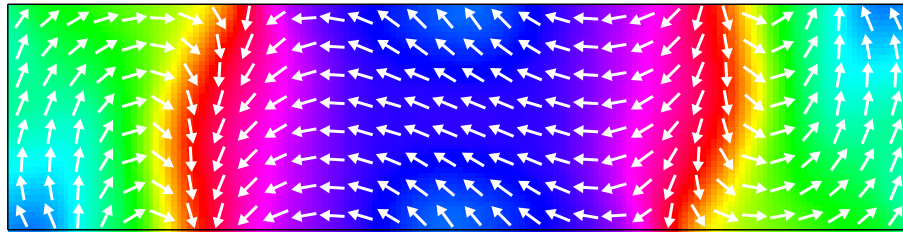


# Problem #4b

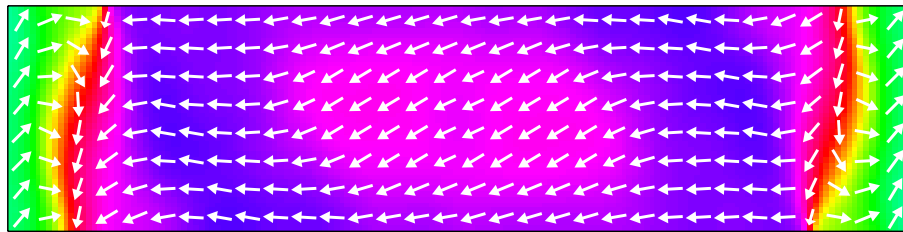
**Time**

$\mu_0 H = 36 \text{ mT}$   $x$

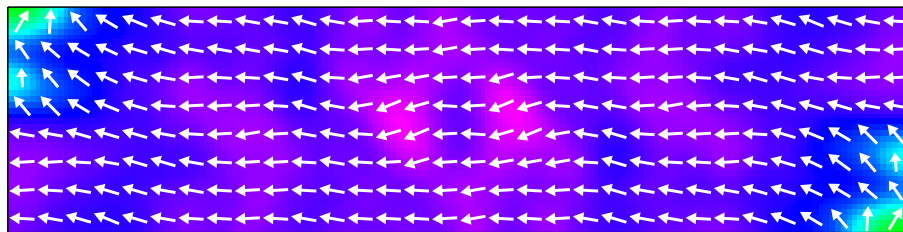
350 ps



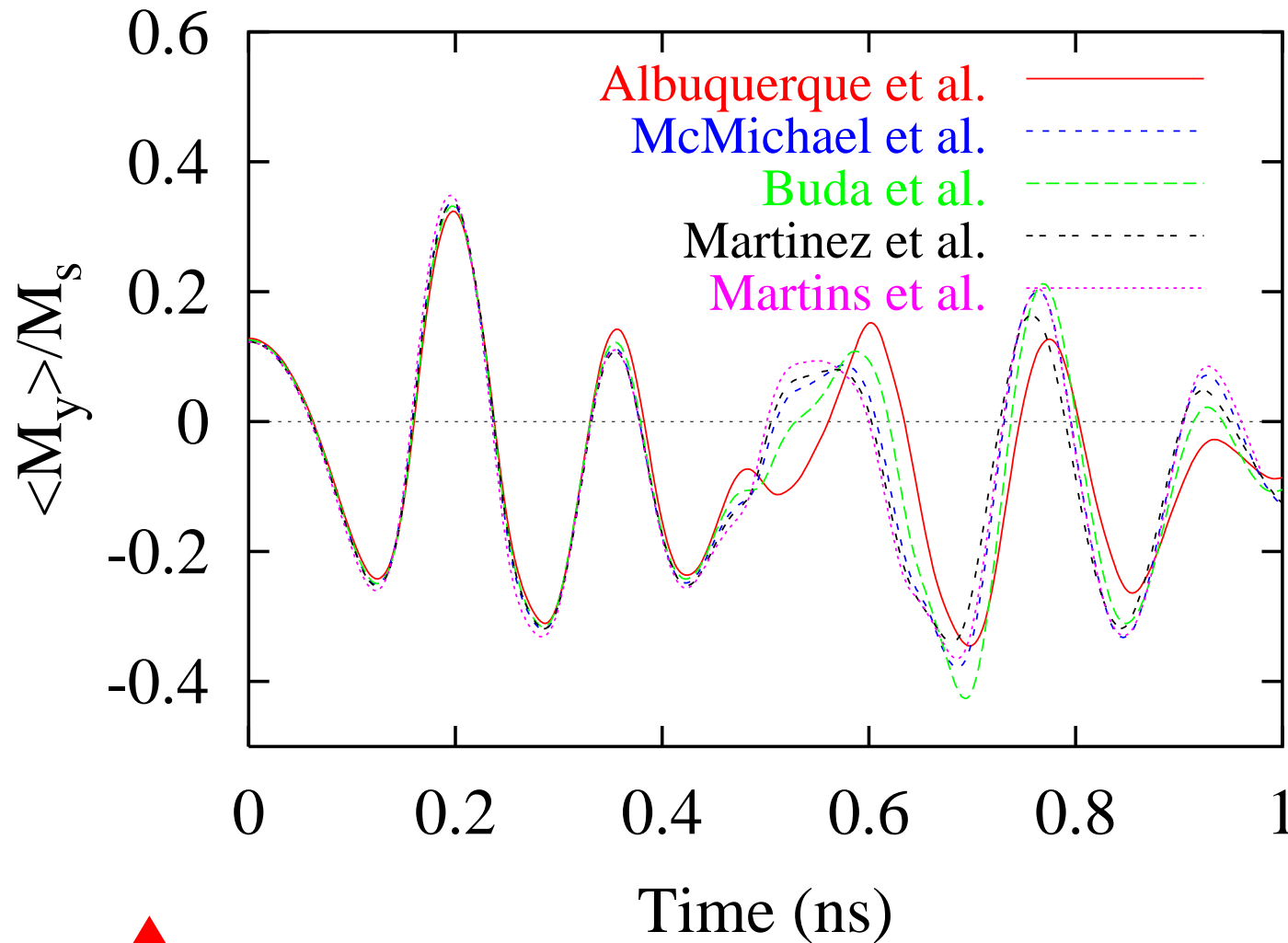
450 ps



750 ps



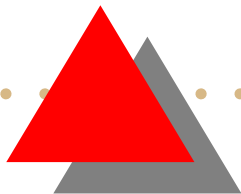
# Field 2, 190° from +x axis





# *Standard Problem Ideals*

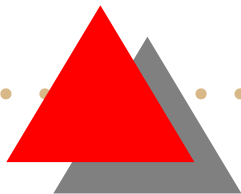
- Small and topical





# *Standard Problem Ideals*

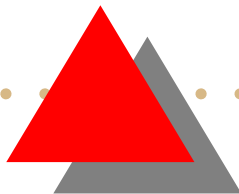
- Small and topical
- Tractable for majority of community





# *Standard Problem Ideals*

- Small and topical
- Tractable for majority of community
- Test single aspect







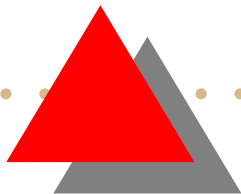
# *Standard Problem Ideals*

- Small and topical
- Tractable for majority of community
- Test single aspect
- Watch out for symmetry breaking and other instabilities



# *Standard Problem Ideals*

- Small and topical
- Tractable for majority of community
- Test single aspect
- Watch out for symmetry breaking and other instabilities
- One part easy (get agreement)



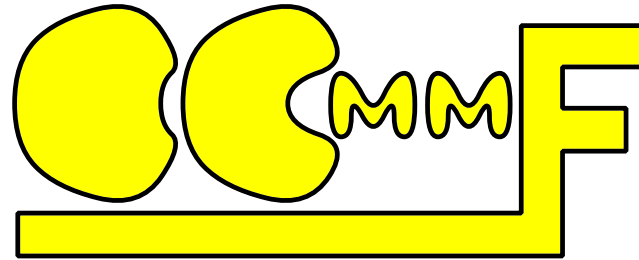


# *Future Standard Problems*

- Thermal effects
  - LLG + thermal field (ns)
  - Long term stability (seconds – years)
- Boundary effects

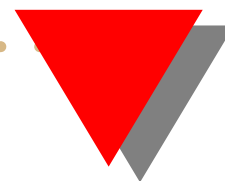
# Public Code

Portable, extensible,  
public domain  
programs & tools  
for micromagnetics



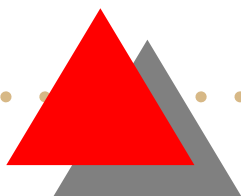
<http://math.nist.gov/oommf>

- Graphical User Interface
- Windows and Unix
- Binaries and source code
- Tcl/Tk and C++ based modular architecture
- 200 page user's manual
- 1000+ downloads in 2001
- 1500+ downloads in 2002
- 1800+ downloads in 2003
- 1200+ downloads through May 2004



## Publications using OOMMF in peer-reviewed journals:

<b>Year</b>	<b>Count</b>
$\leq 2000$	13
2001	14
2002	38
2003	36
<b>Total</b>	<b>101</b>





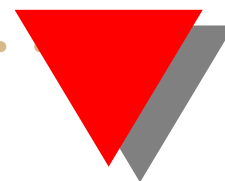
# Requirements

- Unix/X, Windows 95+, Mac OS X
- Tcl/Tk 7.6/4.2+ (8.0+ recommended)  
Tcl Developer Xchange: <http://www.tcl.tk>
- TCP/IP networking on localhost
- RAM: 32 MB (minimum)
- Disk space: 25/80 MB
- Modern C++ compiler to build from source

# Testbed Systems

Platform	Compilers
Alpha/Linux	Compaq C++, Gnu gcc
Alpha/Tru64	Compaq C++ (cxx)
HP-UX	aCC
Intel/Linux	Gnu gcc, Intel C++, Portland Group
Intel/Windows	Microsoft Visual C++, Intel C++, Cygwin gcc, Borland C++
MIPS/IRIX 6 (SGI)	MIPSpro C++, Gnu gcc
SPARC/Solaris	Sun Workshop C++, Gnu gcc

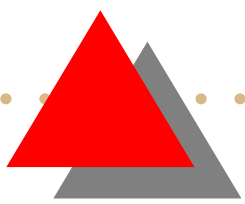
# Public Code



The screenshot displays the Oxsii 1.2.0.2 software interface with several windows open:

- <15972> mmDat**: Shows simulation parameters:
  - Stage : 107
  - Iteration : 5960
  - Bx (mT) : -35
  - Total energy (J) :  $6.47e-18$
  - Demag:Energy (J) :  $5.35e-18$
  - Exchange:Energy (J) :  $1.47e-18$
  - Max dm/dt (deg/ns) : 437.734
- <15971> Oxsii 1.2.0.2**: Main control window with buttons for Reload, Reset, Run, Relax, Step, and Pause. The problem path is `/home/donahue/mag/oommf/spinvalve.mif`. The stage is set to 107. The output table is as follows:

Output	Destination	Schedule
Oxs_Exchange6Ngr:Exchange:Field	mmArchive<15975:2>	Send
Oxs_FixedZeeman:Bias:Field	mmDisp<15974:0>	
Oxs_TimeDriver::Magnetization		
- <15973> mmGraph 1.2.0.2**: A line graph showing magnetization components over simulation time. The x-axis is "Simulation time (s)" from 0 to  $6e-10$ . The left y-axis is "A / m" from 500000 to 1000000. The right y-axis is "A / m" from -0.002 to 0.003. Three curves are plotted:
  - Red: Oxs\_TimeDriver::Mx
  - Green: Oxs\_TimeDriver::My
  - Blue: Oxs\_TimeDriver::Mz
- <15974> mmDisp 1.2.0.1: spinvalve-Oxs\_TimeDriver-Magnetization**: A vector field visualization window. It shows a grid of blue arrows representing magnetization directions. The data scale is 140000 A/m. The Y-slice is  $1.440e-9$  m. The zoom is 18.55.





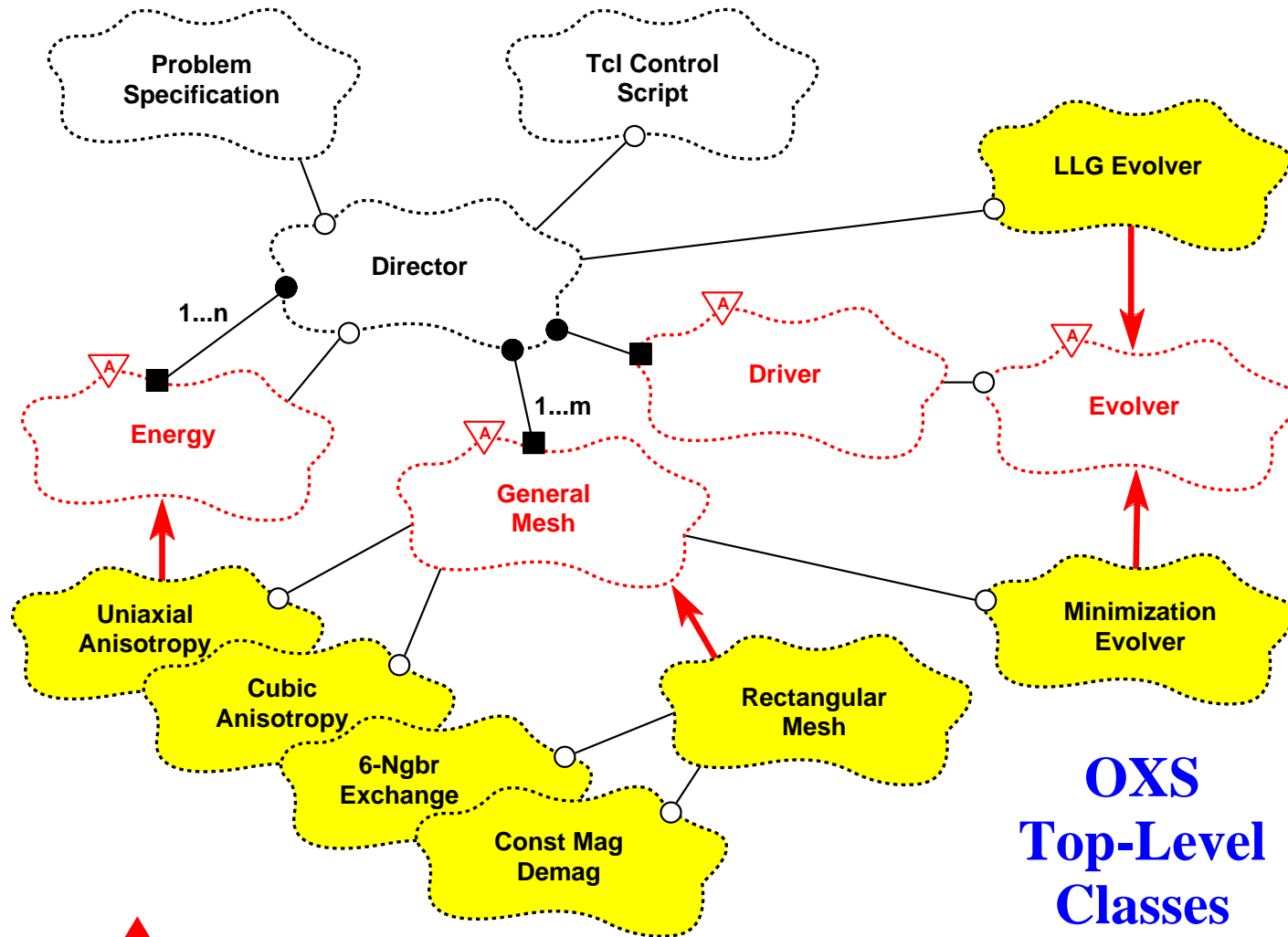
# *Extending OXS: Input scripts*

- Input problem specification (MIF) is Tcl code
- Adjust:
  - material parameters
  - part geometry
  - initial magnetization
  - applied fields (time & space)

# Sample MIF file

```
# MIF 2.1
Specify Oxs_BoxAtlas:atlas {
  xrange {0 300e-9}  yrange {0 200e-9}  zrange {0 16e-9}
}
Specify Oxs_RectangularMesh:mesh {
  cellsize {5e-9 5e-9 4e-9}
  atlas :atlas
}
Specify Oxs_UniformExchange { A 8E-12 }
proc Vortex { x y z } {
  set xrad [expr $x-0.5]
  set yrad [expr $y-0.5]
  set normsq [expr $xrad*$xrad+$yrad*$yrad]
  if {$normsq <= 0.0125} {return "0 0 1"}
  return [list [expr -1*$yrad] $xrad 0]
}
...
```

# OOMMF *eXtensible* Solver



# *OXS Extension Modules*

## **MESHES**

rectangularmesh

## **ENERGY OBJECTS**

uniaxialanisotropy

cubicanisotropy

demag

uzeeman

stagezeeman

transformzeeman

scriptuzeeman

uniformexchange

exchange6ngbr

exchangeptwise

randomsiteexchange

twosurfaceexchange

fixedzeeman



# *OXS Extension Modules*

## **DRIVERS**

timedriver

mindriver

## **EVOLVERS**

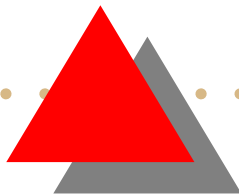
### **Time evolvers**

euler

rungekutta

### **Minimization evolvers**

conjugategradient



# *OXS Extension Modules*

## **INITIALIZERS**

### **Scalar fields**

atlas  
random  
uniform  
scriptorient  
affinetransform

linear  
script  
vecmag  
affineorient

### **Vector fields**

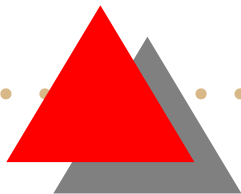
atlas  
planerandom  
script  
scriptorient  
affinetransform

file  
random  
uniform  
affineorient



# *External package support*

- CVODE (evolver)
- FFTW (demag)
- thetaevolve (thermal module)

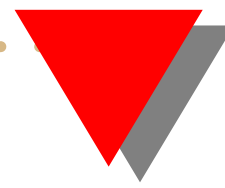


# *Extending OXS: New Ext classes*

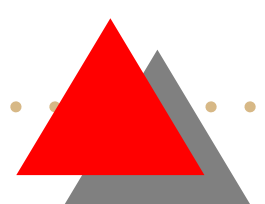
1. Create Oxs\_Ext class file
  - Initializer
  - Energy & field routine
2. Run pimake
3. Create input file



# *Oxs\_Ext initializer*



```
// Constructor
Oxs_HexAnisotropy::Oxs_HexAnisotropy(
    const char* name,      // Child instance id
    Oxs_Director* newdtr, // App director
    const char* argstr)   // MIF input block parameters
: Oxs_Energy(name,newdtr,argstr), mesh_id(0)
{
    // Process arguments
    OXS_GET_INIT_EXT_OBJECT("K1",Oxs_ScalarField,K1_init);
    OXS_GET_INIT_EXT_OBJECT("K2",Oxs_ScalarField,K2_init);
    OXS_GET_INIT_EXT_OBJECT("K3",Oxs_ScalarField,K3_init);
    OXS_GET_INIT_EXT_OBJECT("K4",Oxs_ScalarField,K4_init);
    OXS_GET_INIT_EXT_OBJECT("axis1",Oxs_VectorField,axis1_init);
    OXS_GET_INIT_EXT_OBJECT("axis2",Oxs_VectorField,axis2_init);
    VerifyAllInitArgsUsed();
}
```



# Oxs\_Ext energy

```
void Oxs_HexAnisotropy::GetEnergy
(const Oxs_SimState& state,Oxs_EnergyData& oed) const {
<SNIP: Boilerplate initialization>
  for(UINT4m i=0;i<size;++i) {
    const ThreeVector&  m = spin[i];
    const REAL8m k1 = K1[i];    const REAL8m k2 = K2[i];
    const REAL8m k3 = K3[i];    const REAL8m k4 = K4[i];
    const ThreeVector& u1 = axis1[i];
    const ThreeVector& u2 = axis2[i];
    ThreeVector mxu1 = m;    mxu1 ^= u1;
    REAL8m sintheta2 = mxu1.MagSq();
    REAL8m sintheta6 = sintheta2*sintheta2*sintheta2;
    REAL8m costheta = m*u1;
    REAL8m cosphi = m*u2;
    REAL8m cosphi2 = cosphi*cosphi;
    REAL8m cos6phi = ((32*cosphi2-48)*cosphi2+18)*cosphi2-1;
```

# *Oxs\_Ext (cont.)*

```
// Compute energy at cell i
energy[i] = (((k4*cos6phi+k3)*sintheta2+k2)*sintheta2+k1)
            *sintheta2;

// Compute field at cell i
REAL8m Hcoef1 = (((k4*cos6phi+k3)*3*sintheta2+2*k2)*sintheta2+k1)
                *2*costheta;
REAL8m Hcoef2 = -12*k4*cosphi*sintheta6
                *((cosphi2-1)*16*cosphi2+3);
field[i] = Hcoef1*u1;
field[i] += Hcoef2*u2;
field[i] *= field_mult;
}
}
```

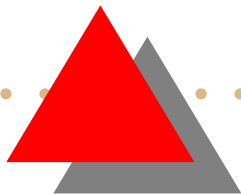
# *Sample input file*

```
...  
Specify Oxs_HexAnisotropy {  
  K1  -4.5e3  
  K2   100  
  K3   100  
  K4  1e4  
  axis1 {0 0 1}  
  axis2 {1 0 0}  
}  
...
```



# *Future work*

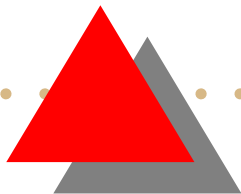
- Thermal effects
- Multiple grids
- Singular points





# Summary

- Standard problems:
  - Useful mainly to code developers
  - Encourage dialog
  - Identify problems
- Public code:
  - Reference implementation for developers
  - Starting point for new developers
  - Used by broad community for published research (transparency)





# References

- $\mu$ MAG:  
<http://www.ctcms.nist.gov/~rdm/mumag.org.html>
- OOMMF:  
<http://math.nist.gov/oommf/>
- OOMMF User's Guide, Version 1.0  
M. J. Donahue and D. G. Porter, **NISTIR 6376**,  
NIST, Gaithersburg, MD (Sept 1999).