OOMMF
User's Guide

October 2, 1998

Abstract

The Object Oriented Micromagnetic Framework (OOMMF) project in the Mathematical and Computational Sciences Division (MCSD) of ITL/NIST, is aimed at developing portable, extensible public domain micromagnetic programs and tools. The end goal is a completely functional, user-friendly micromagnetic code, with a well documented, flexible programmer's interface that will allow developers outside the OOMMF project to swap their own code in and out as desired. The code is written primarily in C++ with a Tcl/Tk (and in the future, possibly OpenGL) interface. Target systems include a wide range of Unix platforms, Windows NT, and Windows '95.

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1 Overview of OOMMF

The goal of the OOMMF[1] (Object Oriented Micromagnetic Framework) project in ITL/NIST is to develop a portable, extensible public domain micromagnetic program and associated tools. This code will form a completely functional micromagnetics package, but will also have a well documented, flexible programmer's interface so that people developing new code can swap their own code in and out as desired. The main contributors to OOMMF are Mike Donahue, and Don Porter.

In order to allow a programmer not familiar with the code as a whole to add modifications and new functionality, we feel that an object oriented approach is critical, and have settled on C++ as a good compromise with respect to availability, functionality, and portability. In order to allow the code to run on a wide variety of systems, we are writing the interface and glue code in Tcl/Tk[2]. This enables our code to operate across a wide range of Unix platforms, Windows NT, and Windows '95.

The code may actually be modified at 3 distinct levels. At the top level, individual programs interact via well-defined protocols across network sockets. One may connect these modules together in various ways from the user interface, and new modules speaking the same protocol can be transparently added. The second level of modification is at the Tcl/Tk script level. Some modules allow Tcl/Tk scripts to be imported and executed at run time, and the top level scripts are relatively easy to modify or replace. At the lowest level, the C++ source is provided and can be modified, although at present there is no documentation detailing this process.

The first portion of OOMMF released was a magnetization file display program called **mmDisp**. A working release[3] of the complete OOMMF project is now available. This includes a problem editor, a 2D micromagnetic solver, and several display widgets, including an updated version of mmDisp. The solver can be controlled by an interactive interface (Sec. 9), or through a sophisticated batch control system (Sec. 15).

The solver is based on a micromagnetic code that Mike Donahue and Bob McMichael had previously developed. It utilizes a heavily damped Landau-Lifshitz ODE solver to relax 3D spins on a 2D mesh of square cells, using FFT's to compute the self-magnetostatic (demag) field. Anisotropy, applied field, and initial magnetization can be varied pointwise, and arbitrarily shaped elements can be modeled. We are currently working on a full 3D version of this code suitable for modeling layered materials.

[1] http://math.nist.gov/oommf/

[2] http://www.scriptics.com/

[3] http://math.nist.gov/oommf/software.html

If you want to receive email notification of updates to this project, register your email address with the "μMag Announcement" mailing list:

http://www.ctcms.nist.gov/~rdm/email-list.html.

2 Installation

2.1 Requirements

OOMMF software is written in C++ and Tcl. It uses the Tcl-based Tk Windowing Toolkit to create graphical user interfaces that are portable to many varieties of Unix as well as Microsoft Windows 95/NT.

Tcl and Tk must be installed before installing OOMMF. Tcl and Tk are available for free download from Scriptics Corporation[4]. We recommend the latest stable versions of Tcl and Tk concurrent with this release of OOMMF. OOMMF requires at least Tcl version 7.5 and Tk version 4.1 on Unix platforms, and requires at least Tcl version 7.6 and Tk version 4.2 on Microsoft Windows platforms. OOMMF software does not support any alpha or beta versions of Tcl/Tk, and each release of OOMMF may not work with later releases of Tcl/Tk. Check the release dates of both OOMMF and Tcl/Tk to ensure compatibility.

A Tcl/Tk installation includes two shell programs. The names of these programs may vary depending on the Tcl/Tk version and the type of platform. The first shell program contains an interpreter for the base Tcl language. In the OOMMF documentation we refer to this program as `tclsh`. The second shell program contains an interpreter for the base Tcl language extended by the Tcl commands supplied by the Tk toolkit. In the OOMMF documentation we refer to this program as `wish`. Consult your Tcl/Tk documentation to determine the actual names of these programs on your platform (for example, `tclsh80.exe` or `wish4.2`).

OOMMF applications use TCP/IP network sockets to communicate. This means that OOMMF requires support for networking, even on a stand-alone machine. At a minimum, OOMMF must be able to access the loopback interface so that the host can talk to itself using TCP/IP.

To build the OOMMF software from source code, you will need a C++ compiler capable of handling C++ templates, as well as other software development utilities for your platform. We do development and test builds on the following platforms, although porting to others should not be difficult:

[4] http://www.scriptics.com/

Platform	Compilers
AIX	Gnu gcc
Alpha/Digital UNIX	Gnu gcc
Alpha/Linux	Gnu gcc/egcs
Alpha/Windows NT	Microsoft Visual C++
HP-UX	HP C++ (cfront)
Intel/Linux	Gnu gcc/egcs
Intel/Windows NT, 95	Microsoft Visual C++
MIPS/IRIX 6 (SGI)	MIPSpro C++
SPARC/Solaris	Sun Workshop C++, Gnu gcc
SPARC/SunOS 4	Sun Workshop C++, Gnu gcc

2.2 Basic Installation

Follow the instructions in the following sections, in order, to prepare OOMMF software for use on your computer.

2.2.1 Download

The latest release of the OOMMF software may be retrieved from the OOMMF download page[5]. Each release is available in two formats. The first format is a gzipped tar file containing an archive of all the OOMMF source code. The second format is a `.zip` compressed archive containing source code and pre-compiled executables for Microsoft Windows 95/NT running on an x86-based microprocessor system and compatible with Tcl/Tk version 8.0. Other release formats, including pre-compiled executables for Microsoft Windows 95/NT running on a Digital Alpha Systems RISC-based microprocessor system, and/or compatible with Tcl/Tk version 7.6/4.2 will be made available on request.

For the first format, unpack the distribution archive using gunzip and tar:

```
gunzip -c oommf10a980812.tar.gz | tar xvf -
```

For the other format(s), you will need a utility program to unpack the `.zip` archive. This program must preserve the directory structure of the files in the archive, and it must be able to generate files with names not limited to the traditional MSDOS 8.3 format. Some old versions of pkzip unpacking utility programs do not have these properties. One utility program which is known to work is UnZip[6]. Using your utility, unpack the `.zip` archive, e.g.

```
unzip oommf10a980812.zip
```

[5] http://math.nist.gov/oommf/software.html
[6] http://www.cdrom.com/pub/infozip/UnZip.html

2.2.2 Configuration

After downloading and unpacking the OOMMF software distribution, all the OOMMF software is contained in a subdirectory named `oommf`. Start a command line interface (a shell on Unix, or the MS-DOS Prompt on Microsoft Windows), and change the working directory to the directory `oommf`. Then run the Tcl script `platform.tcl`:

```
tclsh platform.tcl
```

(Remember, the Tcl shell program may not have the name `tclsh` on your platform. It may be something like `tclsh8.0` or `tclsh76.exe`. Consult your Tcl documentation, and use the name which works on your computer.)

The output of the script `platform.tcl` is the platform name which the OOMMF software uses to describe your computer. For example, when you run `platform.tcl` on a Silicon Graphics machine, the output is the string `sgi`. The platform name is used by OOMMF in index and configuration files and to name directories so that a single OOMMF installation can support multiple platform types.

Say the output of `platform.tcl` is `foo`. Then you must edit the file `config/cache/foo.tcl` to describe your computing environment to OOMMF. Follow the editing instructions found within the file.

If the output of `platform.tcl` indicates that multiple platform names are compatible with your computer, or if you wish for OOMMF software to use a different platform name for your computer and others like it, see "Managing OOMMF platform names" (Sec. 2.3.3) for further instructions.

2.2.3 Compiling and Linking

If you downloaded a distribution with pre-compiled executables, you may skip this section.

The compiling and linking of the C++ portions of the OOMMF software are guided by the application `pimake` ("Platform Independent Make") which is distributed as part of the OOMMF software (in the directory `app/pimake/`). `pimake` is similar in operation to the Unix utility program `make`, but it is written entirely in Tcl so that it will run anywhere Tcl is installed. Just as `make` is controlled by rules in files named `Makefile` or `makefile`, `pimake` is controlled by rules in files named `makerules.tcl`. `pimake` takes an optional argument on its command line which names the target to build. To build all the OOMMF software, run `pimake` in the root directory of the OOMMF distribution.

```
tclsh app/pimake/pimake.tcl
```

When `pimake` calls on a compiler or other software development utility, the command line is printed, so that you may monitor the build process. Assuming a proper configuration for your platform, `pimake` should be able to compile and link all the OOMMF software without error. If `pimake` reports errors, please send the output to the OOMMF developers.

2.2.4 Installing

The current release of the OOMMF software does not support an installation procedure. For now, simply run the executables from the directories in which they were unpacked/built.

2.2.5 Using OOMMF Software

To start using OOMMF software, run the OOMMF bootstrap application (Sec. 5). This may be launched from the command line interface:

```
tclsh app/oommf/oommf.tcl
```

Or if you prefer, you may now use whatever graphical "point and click" interface your operating system provides for launching programs to launch the OOMMF bootstrap application `./app/oommf/oommf.tcl`. By default, the OOMMF bootstrap application will start up a copy of the OOMMF application **mmLaunch** (Sec. 6) in a new window.

2.3 Advanced Installation Options

The following sections provide instructions for some additional installation options.

2.3.1 Reducing Disk Space Usage

To delete the intermediate files created when building the OOMMF software from source code, use `pimake` to build the target `objclean` in root directory of the OOMMF distribution.

```
tclsh app/pimake/pimake.tcl objclean
```

The `pimake` target `clean` will also remove the OOMMF executables. The `pimake` target `distclean` will remove all files created by the compile and link steps, leaving the OOMMF files as they were distributed, except for your configuration edits.

2.3.2 Local customizations

OOMMF software supports local customization of some of its features. All OOMMF programs load the file `config/options.tcl`, which contains customization commands as well as editing instructions. As it is distributed, `config/options.tcl` directs those programs which load it to also load the file `config/local/options.tcl`, if it exists. Because future OOMMF releases may overwrite the file `config/options.tcl`, permanent customizations should be made by copying `config/options.tcl` to `config/local/options.tcl` and editing the copy.

Notable available customizations include the choice of which network port the host service directory application (Sec. 4) uses, and the choice of what program is used for the display of HTML files. If Microsoft's Internet Explorer is selected for HTML display, further customization is needed for OOMMF to generate URLs in the non-standard format Internet Explorer insists on. See the instructions in the file `config/options.tcl` for details.

2.3.3 Managing OOMMF platform names

OOMMF software classifies computing platforms into different types using the scripts in the directory `config/names` relative to the root directory of the OOMMF distribution. Each type of computing platform is assigned a unique name. These names are used as directory names and in index and configuration files so that a single OOMMF installation may contain platform-dependent sections for many different types of computing platforms.

To learn what name OOMMF software uses to refer to your computing platform, run the Tcl script `platform.tcl` in the OOMMF root directory.

Changing the name OOMMF assigns to your platform To change the name OOMMF software uses to describe your platform from `foo` to `bar`, simply rename the file

`config/names/foo.tcl` to `config/names/bar.tcl`

and

`config/cache/foo.tcl` to `config/cache/bar.tcl`.

After renaming your platform type, you must recompile your executables.

Adding a new platform type If the script `platform.tcl` reports the platform name `unknown`, then none of the scripts in `config/names/` recognizes your platform type. To add the platform name `foo` to OOMMF's vocabulary of platform names, create the file

config/names/foo.tcl. The simplest way to proceed is to copy an existing file in the directory config/names and edit it to recognize your platform.

The files in config/names include Tcl code like this:

```
Oc_Config New _ [file rootname [file tail [info script]]] {
    # In this block place the body of a Tcl proc which returns 1
    # if the machine on which the proc is executed is of the
    # platform type identified by this file, and which returns 0
    # otherwise.
    #
    # The usual Tcl language mechanism for discovering details
    # about the machine on which the proc is running is to
    # consult the global Tcl variable 'tcl_platform'.  See the
    # existing files for examples, or contact the OOMMF developers
    # for further assistance.
}
```

After creating the new platform name file config/names/foo.tcl, you also need to create a new platform cache file config/cache/foo.tcl. A reasonable starting point is to copy the file config/cache/unknown.tcl for editing. Contact the OOMMF developers for assistance.

Please consider contributing your new platform recognition and configuration files to the OOMMF developers for inclusion in future releases of OOMMF software.

Resolving platform name conflicts If the script platform.tcl reports "Multiple platform names are compatible with your computer", then there are multiple files in the directory config/names/ that return 1 when run on your computer. For each compatible platform name reported, edit the corresponding file in config/names/, so that only one of them returns 1 on your computer. Experimenting using tclsh to probe the Tcl variable tcl_platform should assist you in this task. If that fails, you can explicitly assign a platform type corresponding to your computing platform by matching its hostname. For example, if your machine's host name is foo.bar.net:

```
Oc_Config New _ [file rootname [file tail [info script]]] {
    if {[string match foo.bar.net [info hostname]]} {
        return 1
    }
    # Continue with other tests...
}
```

Contact the OOMMF developers if you need further assistance.

2.3.4 Microsoft Windows Options

This section lists the installation options for Microsoft Windows only.

Adding an OOMMF shortcut to your desktop Right mouse click on the desktop to bring up the configuration dialog, and select **New|Shortcut**. Enter the command line necessary to bring up OOMMF, e.g.,

```
tclsh80 c:\oommf\app\oommf\oommf.tcl
```

Click **Next>** and enter `OOMMF` for the shortcut name. Select **Finish**.

At this point the shortcut will appear on your desktop with either the tclsh or wish icons. Right mouse click on the icon and select **Properties**. Select the **ShortCut** tab, and bring up **Change Icon...**. Under **File Name:** enter the OOMMF icon file, e.g.,

```
C:\oommf\app\oommf\oommf.ico
```

Click **OK**. Back on the **Shortcut** tab, change the **Run:** selection to Minimized. Click **OK** to exit the Properties dialog box. Double clicking on the OOMMF icon should now bring up the OOMMF application **mmLaunch**.

Setting the TCL_LIBRARY environment variable If you encounter difficulties during OOMMF start up, you may need to set the environment variable TCL_LIBRARY.

On Windows NT Bring up the Control Panel (for example, by selecting **Settings|Control Panel** off the Start menu), and select **System**. Go to the **Environment** tab, and enter TCL_LIBRARY as the Variable, and the name of the directory containing `init.tcl` for the Value, e.g.,

```
%SystemDrive%\Program Files\Tcl\lib\tcl8.0
```

Click **Set** and **OK** to finish.

On Windows 95 Edit the file `autoexec.bat`. Add a line such as the following:

```
set TCL_LIBRARY=C:\Program Files\Tcl\lib\tcl8.0
```

3 Quick Start: Example OOMMF Session

STEP 1: Start up the mmLaunch window.

- At the prompt, when you are in the OOMMF root directory, type

  `tclsh app/oommf/oommf.tcl`

- After a (possibly long) time, you will see a small window labeled **mmLaunch**. It will come up in background mode, so you will get another prompt in your original window, even before the **mmLaunch** window appears.

STEP 2: Gain access to other useful windows.

- On **mmLaunch** window, check the **localhost** box, causing a menu of user account boxes to appear. Then check the box corresponding to the account you want to compute on. This gives a menu of options:
  - **mmProbEd:** to grab/modify a problem
  - **mmSolve2D:** to control the solver
  - **mmDisp:** to display vector fields
  - **mmGraph:** to form x-y plots
  - **mmDataTable:** to display current values of variables
  - **mmArchive:** to save vector field data (primitive)
- Click on **mmDisp**, **mmGraph**, and/or **mmDataTable**, depending on what form of output you want.

STEP 3: Load a problem.

- On **mmLaunch** window, click on the **mmProbEd** button.
- On **mmProbEd** window, make menu selection **File|Open...**. A **Load MIF File** dialog window will appear.
- On this window:
  - Double click in the **Path** subwindow to change directories. Several sample problems can be found in the directory `oommf/app/mmpe/examples`.
  - To load a problem, double click on a `*.mif` file (e.g., prob1.mif) from the list under the **Filter:** subwindow.

- Modify the problem as desired by clicking on buttons from the main **mmProbEd** window (e.g., **Material Parameters**), and fill out the pop-up forms. A completely new problem may be defined this way.

STEP 4: Initialize the solver.

- On **mmLaunch** window, click on the **mmSolve2D** button to launch an instance of the program **mmSolve2D**.
- Wait for the new solver instance to appear in the **Threads** column in the **mmLaunch** window.
- Check the box next to the **mmSolve2D** entry in the **Threads** column. A window containing an **mmSolve2D** interface will appear.
- On **mmSolve2D** window:
  - Check **Problem Description** under **Inputs**.
  - Check **mmProbEd** under **Source Threads**.
  - Click **LoadProblem**.
  - Wait for more buttons to appear.
  - Check **Scheduled Outputs**.
  - For each desired output (**TotalField**, **Magnetization**, and/or **DataTable**), specify the frequency of update:
    - Check desired output. This will exhibit the possible output destinations in **Destination Threads**.
    - Check the box next to the desired Destination Thread. This will exhibit **Schedule** options.
    - Choose a schedule:
      - **Iteration:** fill in number and check the box.
      - **Equilibrium:** fill in number and check the box.
      - **Interactive:** whenever you click corresponding Interactive output button.

STEP 5: Start the calculation.

- On the **mmSolve2D** window, start the calculation with **Run** or **Relax**.
- If you requested mmDataTable output, check the boxes for the desired quantities on the **mmDataTable** window under the Data menu, so that they appear and are updated as requested in your schedule.

- Similarly, check the box for the desired X-Axis and Y-Axis variables on the **mmGraph** window(s) under the **X-Axis** and **Y-Axis** menus.

STEP 6: Perform midcourse controls as desired.

- On the **mmSolve2D** window, buttons can stop and restart the calculation:
  - **Reset:** Return to beginning of problem.
  - **LoadProblem:** Restart with a new problem.
  - **Run:** Apply a sequence of fields until all complete.
  - **Relax:** Apply a single field and run the ODE to equilibrium.
  - **Pause:** Click anytime to stop the solver. Restart with Run or Relax.
  - **Field-:** Apply the previous field again.
  - **Field+:** Apply the next field in the list.
- Output options can be changed and new output windows opened.

STEP 7: Exit OOMMF.

- On the **mmSolve2D** window, stop the simulation with **Pause** or **Exit**.
- Use the **File** menu on each window to exit.

4 OOMMF Architecture Overview

Before describing each of the applications which comprise the OOMMF software, it is helpful to understand how these applications work together. OOMMF is not structured as a single program. Instead it is a collection of programs, each specializing in some task needed as part of a micromagnetic simulation system. An advantage of this modular architecture is that each program may be improved or even replaced without a need to redesign the entire system. Because the state of the art in micromagnetic simulation is continuing to evolve, this flexibility is essential for the longevity of a micromagnetic simulation system.

The OOMMF programs work together by providing services to one another. The programs communicate with one another over Internet connections, even when the programs are running on a common host. An advantage of this design is that support for distributed operation of OOMMF over a networked collection of hosts is provided for in the basic design, and will be available in a future release.

When two OOMMF applications are in the relationship that one is requesting a service from the other, it is convenient to introduce some clarifying terminology. Let us refer to the application which is providing a service as the "server application" and the application requesting the service as the "client application." Note that a single application can be both a server application in one service relationship and a client application in another service relationship.

Each server application provides its services on a particular Internet port. Each server application needs to inform potential client applications how to obtain its service. Each client application needs to be able to look up possible providers of the service it needs. The intermediary which brings server applications and client applications together is another application called the "account service directory." There may be at most one account service directory application running under the user ID of each user account on a host. Each account service directory keeps track of all the services provided by OOMMF server applications running under its user account on its host and the corresponding Internet ports at which those services may be obtained. OOMMF server applications register their services with the corresponding account service directory application. OOMMF client applications look up service providers running under a particular user ID in the corresponding account server directory application.

The account service directory applications simplify the problem of matching servers and clients, but they do not completely solve it. OOMMF applications still need a mechanism to find out how to obtain the service of the account service directory applications! Another application, called the "host service directory" serves this function. Only one copy of the host service directory application runs on each host. Its sole purpose is to tell OOMMF applications where to obtain the services of account service directories on that host. Because

only one copy of this application runs per host, it can provide its service on a well-known port which is configured into the OOMMF software. By default, this is port 15136. OOMMF software can be customized (See Sec. 2.3.2) to use a different port number.

These service directory applications are vitally important to the operation of the total OOMMF micromagnetic simulation system. However, it would be easy to overlook them. They act entirely "behind the scenes" without a user interface window. Furthermore, they are never launched by the user. When any server application needs to register its service, if it finds that these service directory applications are not running, it launches new copies of them. In this way the user can be sure that if any OOMMF server applications are running, then so are the service directory applications needed to direct clients to its service.

In the sections which follow, the OOMMF applications are described in terms of the services they provide and the services they require.

5 Command Line Launching

Some of the OOMMF applications are platform-independent Tcl scripts. Some of them are Tcl scripts which require special platform-dependent interpreters. Others are platform-dependent, compiled C applications. It is likely that some of them will change status in later releases of OOMMF. Each of these types of application requires a different command line for launching. Rather than require all OOMMF users to manage this complexity, we provide a pair of programs which provide simplified interfaces for launching OOMMF applications.

The first of these is used to launch OOMMF applications from the command line. Because its function is only to start another program, we refer to this program as the "bootstrap application." The bootstrap application is the Tcl script `app/oommf/oommf.tcl`. In its simplest usage, it takes a single argument on the command line, the name of the application to launch. For example, to launch **mmGraph** (Sec. 11), the command line is:

```
tclsh app/oommf/oommf.tcl mmGraph
```

If no command line arguments are passed to the bootstrap application, by default it will launch the application **mmLaunch** (Sec. 6).

Some of the OOMMF applications take optional arguments when launched from the command line. Any command line arguments to the bootstrap application after the application name will be passed as command line arguments to the named application.

The bootstrap application also supports some more complicated, more rarely used processing of its command line arguments. By default, the bootstrap application launches the named application and exits. If the first argument to the bootstrap program is the option `-nofork`, however, the bootstrap program will block until the application it launches (now named in the second command line argument) exits.

If the argument following the application name looks like a version number (containing only digits and dots), then the bootstrap application will interpret it as the minimum version of the named application to launch. If no application satisfying the version requirement can be found, the bootstrap application will report an error.

The bootstrap application should be infrequently used by most users. The application **mmLaunch** (Sec. 6) provides a more convenient graphical interface for launching applications. The main uses for the bootstrap application are launching **mmLaunch**, launching programs which make up the OOMMF Batch System(Sec. 15) and other programs which are inherently command line driven, and in circumstances where the users wishes to precisely control the command line arguments passed to an OOMMF application.

Platform Issues

The Tcl script `app/oommf/oommf.tcl` begins with the lines:

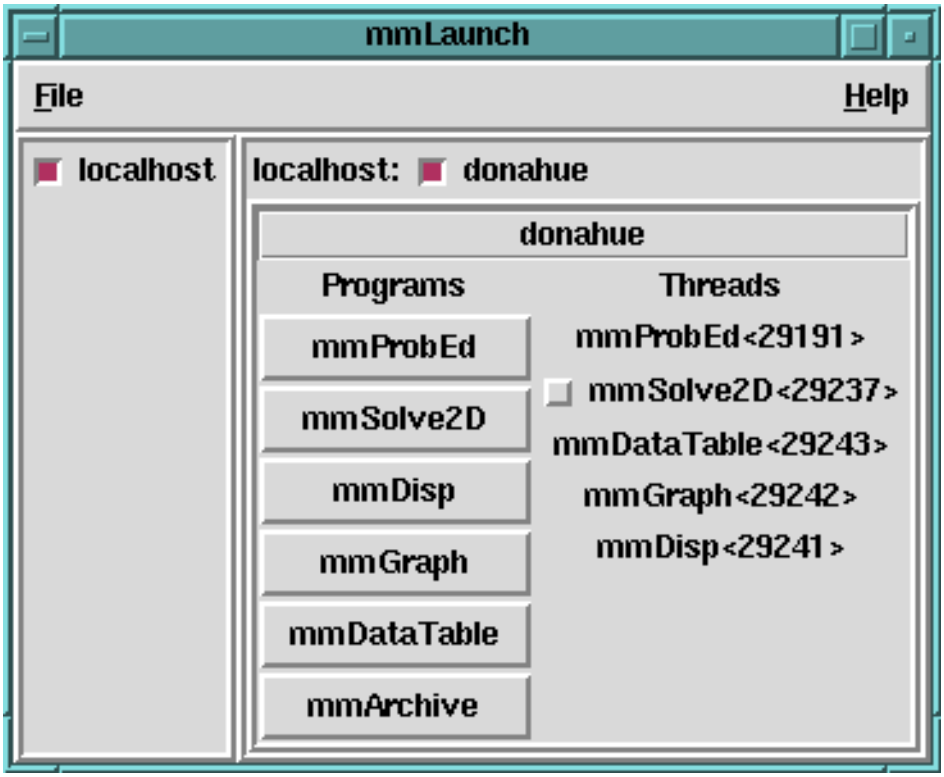
```
#!/bin/sh
# \
exec tclsh "$0" ${1+"$@"}
```

On most Unix platforms, if `app/oommf/oommf.tcl` is executable, the interpreter `tclsh` (on the execution path) will be invoked to interpret the script. If in addition, the directory `.../app/oommf` is in the execution path, the command line can be as simple as:

```
oommf.tcl <appName>
```

On Windows platforms, because `app/oommf/oommf.tcl` has the file extension `.tcl`, it is associated by Windows with the `wish` interpreter. The script `app/oommf/oommf.tcl` has been specially written so that either `tclsh` or `wish` is a suitable interpreter. This means that simply double-clicking on an icon associated with the file `app/oommf/oommf.tcl` (say, in Windows Explorer) will launch the bootstrap application with no arguments. This will result in the default behavior of launching the application **mmLaunch**, which is suitable for launching other OOMMF applications.

6 OOMMF Launcher/Control Interface: mmLaunch



Overview

The application **mmLaunch** launches, monitors, and controls other OOMMF applications. It is the OOMMF application which is most closely connected to the account service directory and host service directory applications which run behind the scenes. It also provides user interfaces to any applications, notably **mmSolve2D** (Sec. 9), which do not have their own user interface window.

Launching

mmLaunch should be launched using the bootstrap application (Sec. 5). The command line is

```
tclsh app/oommf/oommf.tcl mmLaunch [-console]
```

Controls

Upon startup, **mmLaunch** displays a panel of checkbuttons, one for each host service directory to which it is connected. In the current release of OOMMF there is only one checkbutton labeled **localhost**. Future releases of **mmLaunch** will be able to connect to remote hosts as well. If there is no host service directory running on the localhost when **mmLaunch** is launched, **mmLaunch** will start one. In that circumstance, there may be some delay before the **localhost** check button appears.

Toggling the **localhost** checkbutton toggles the display of an interface to the host service directory. The host service directory interface consists of a row of checkbuttons, one for each account service directory registered with the host service directory. Each checkbutton is labeled with the user ID of the corresponding account service directory. For most users, there will be only one checkbutton, labeled with user's own account ID. On platforms which do not support multiple user accounts (Windows 95), the fake account ID **oommf** is displayed. If there is no account service directory running for the account under which **mmLaunch** was launched, **mmLaunch** will start one. In that circumstance, there may be some delay before the account checkbutton appears.

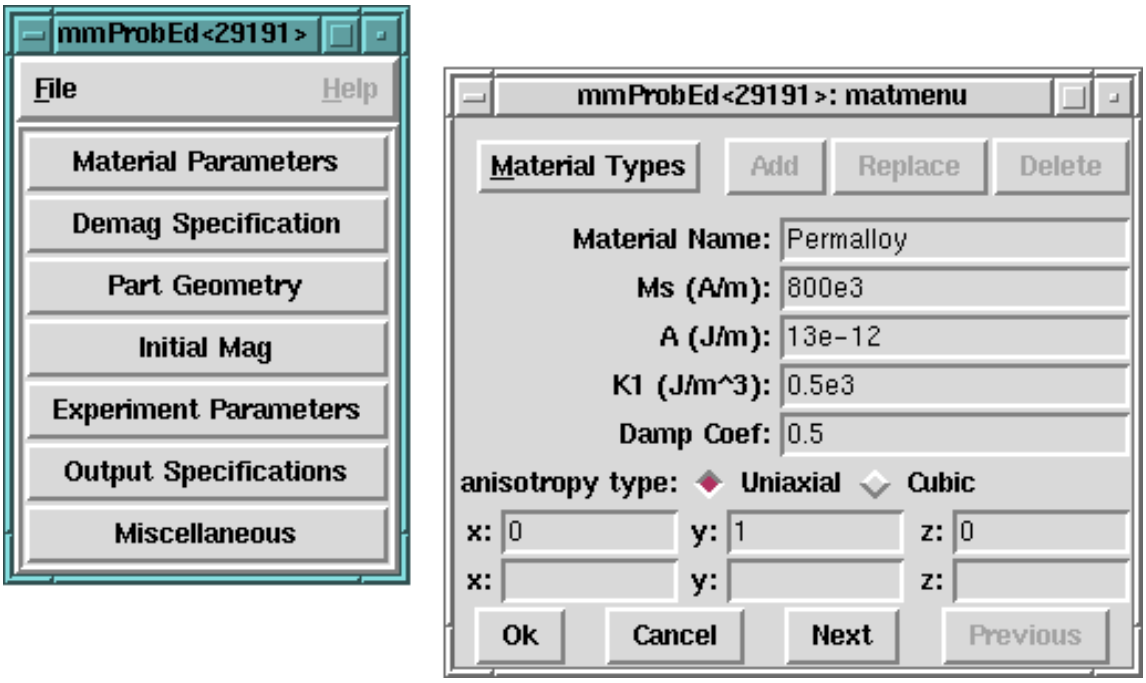
Toggling an account checkbutton toggles the display of an interface to the corresponding account service directory. The account service directory interface consists of two columns. The **Programs** column contains buttons labeled with the names of OOMMF applications which may be launched under the account served by this account service directory. Clicking on one of these buttons launches the corresponding application. Only one click is needed, though there will be some delay before the launched application displays a window to the user. Multiple clicks will launch multiple copies of the application.

The **Threads** column is a list of all the OOMMF applications currently running under the account which are registered with the account service directory. The list includes both the application name and an ID number by which multiple copies of the same application may be distinguished. Applications which provide a user interface window display the same ID number in the title bar of their window. When an application exits, its entry will automatically disappear from this list.

Any of the running applications which do not provide their own interface window will be displayed in the **Threads** list with a checkbutton. Toggling the checkbutton toggles the display of an interface which **mmLaunch** provides on behalf of that application. The only OOMMF application to currently use this service of **mmLaunch** is the application **mmSolve2D** (Sec. 9). These interfaces are described in the documentation for the corresponding applications.

The menu selection **File|Exit** terminates the **mmLaunch** application. The menu **Help** provides the usual help facilities.

7 Micromagnetic Problem Editor: mmProbEd



Overview

The application **mmProbEd** provides the service of supplying the description of a micromagnetic problem to a solver. The problem descriptions are stored and transmitted in the *Micromagnetic Input Format* (MIF)(Sec. 16.1). **mmProbEd** also provides a user interface through which the contents of a micromagnetic problem description may be edited and then saved to a file or transmitted to a solver.

Launching

mmProbEd may be started either by selecting the **mmProbEd** button on **mmLaunch**, or from the command line via

```
tclsh app/oommf/oommf.tcl mmProbEd [-console]
```

Inputs

The menu selection **File|Open...** displays a dialog box for selecting a file from which to load a MIF problem description from a file. Several example files are included in the OOMMF release in the directory `app/mmpe/examples`. At startup, **mmProbEd** loads the problem contained in `app/mmpe/init.mif` as an initial problem.

Outputs

The menu selection **File|Save as...** displays a dialog box for selecting/entering a file in which the problem description currently held by **mmProbEd** is to be saved. When saving a problem description to a file, **mmProbEd** does not include comments. This means that a simple operation of reading in a MIF file and then saving it will not preserve (often useful) comments in the output file.

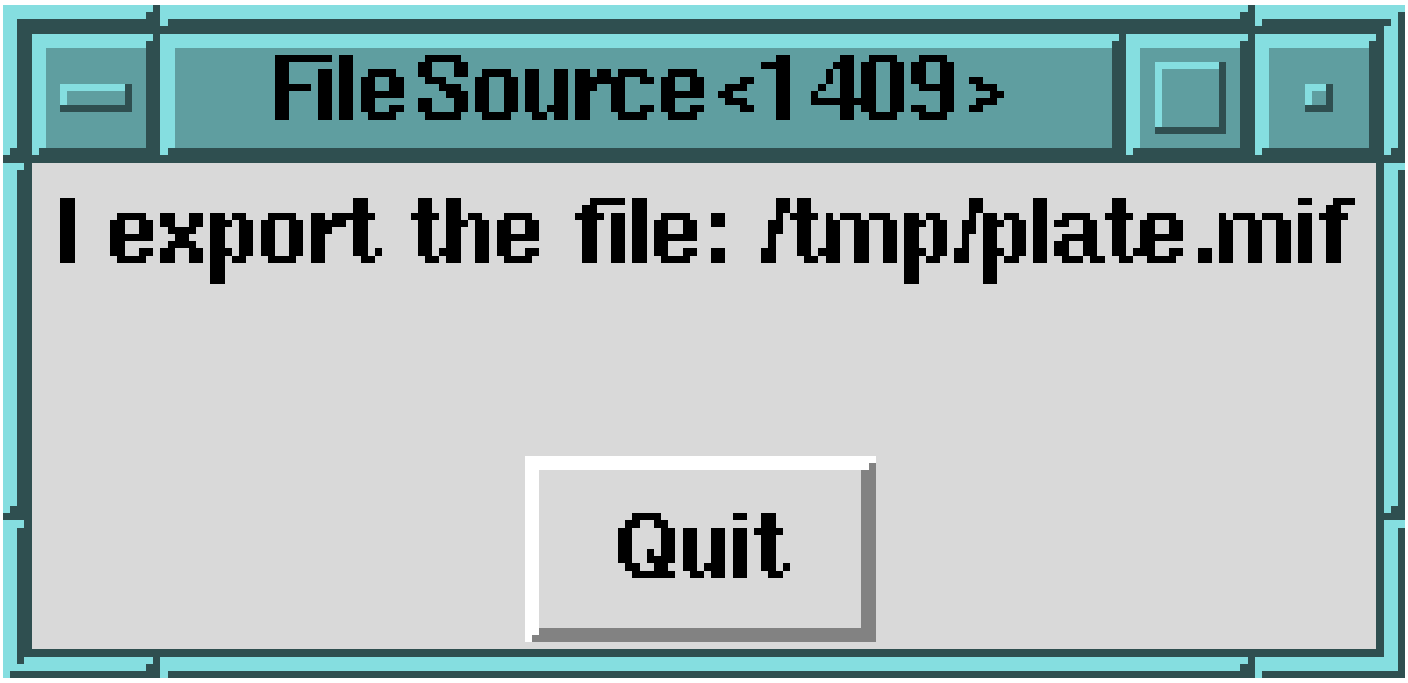
Each instance of **mmProbEd** contains exactly one problem description at once. Each also accepts and services requests from client applications (typically solvers) for the problem description it contains.

Controls

The main panel in the **mmProbEd** window contains buttons corresponding to the sections in a MIF problem description. Selecting a button brings up another window through which the contents of that section of a problem description may be edited. The MIF sections and the elements they contain are described in detail in the MIF(Sec. 16.1) documentation. Only one editing window is displayed at a time. The windows may be navigated in order using their **Next** or **Previous** buttons.

The menu selection **File|Exit** terminates the **mmProbEd** application. The menu **Help** provides the usual help facilities.

8 Micromagnetic Problem File Source: FileSource



Overview

The application **FileSource** provides the same service as **mmProbEd** (Sec. 7), supplying a MIF description of a micromagnetic problem to a solver. As the MIF specification evolves, **mmProbEd** lags behind. There are often new fields in the MIF specification which **mmProbEd** is not capable of editing, and which **mmProbEd** may not pass on to solvers after loading them in from a file. To make use of such fields, a MIF file may need to be edited "by hand" using a general purpose text editor. **FileSource** may then be used to supply the MIF problem description contained in a file to a solver without danger of corrupting its contents.

Ideally, **mmProbEd** would stay current with the MIF specification, and there would be no need for **FileSource**. It is a crude surrender to the vagaries of development.

Launching

FileSource must be launched from the command line, since it requires a command line argument, the name of the file containing the MIF problem description it should serve to

client applications. The command line is

```
tclsh app/oommf/oommf.tcl FileSource <filename>
```

Although **FileSource** does not appear on the list of **Programs** which **mmLaunch** offers to launch, running copies do appear on the list of **Threads** since they do provide a service registered with the account service directory.

Inputs

FileSource takes its MIF problem description from the file named on the command line. No checking of the file contents against the MIF specification is performed. The file contents are passed uncritically to any client application requesting a problem description. Those client applications should raise errors when presented with invalid problem descriptions.

Outputs

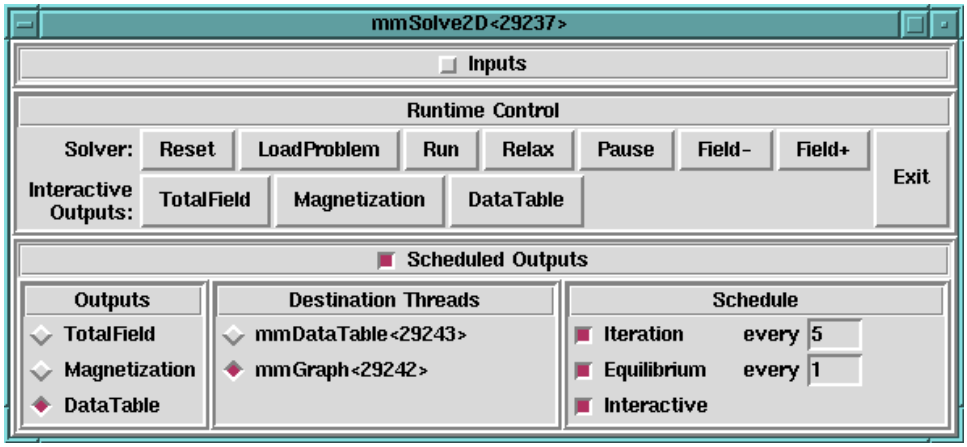
Each instance of **FileSource** provides the contents of exactly one file. The file name is displayed in the **FileSource** window to help the user associate each instance of **FileSource** with the data file it provides. Each instance of **FileSource** accepts and services requests from client applications (typically solvers) for the contents of the file it exports.

The contents of the file are read at the time of each client's request, so if the contents of a file change between the startup of **FileSource** and the arrival of a request from a client, the new contents will be served to the client application.

Controls

A **Quit** button terminates the **FileSource** application.

9 The 2D Micromagnetic Solver: mmSolve2D



Overview

The application **mmSolve2D** is a micromagnetic computation engine capable of solving problems defined on two-dimensional square grids of three-dimensional spins. Within the OOMMF architecture (see Sec. 4), **mmSolve2D** is both a server and a client application. **mmSolve2D** is a client of server applications providing the services of problem description supply, data table display and storage, and vector field display and storage. **mmSolve2D** is the server of a solver control service for which the only client is **mmLaunch** (Sec. 6). It is through this service that **mmLaunch** provides a user interface window (shown above) on behalf of **mmSolve2D**.

Launching

mmSolve2D may be started either by selecting the **mmSolve2D** button on mmLaunch, or from the command line via

```
tclsh oommf/app/oommf.tcl mmSolve2D [-console] [-tk|-notk]
```

The command line options `-tk` and `-notk` determine whether or not **mmSolve2D** has its own window. By default it does not (`-notk`). With no window, an instance of **mmSolve2D** may keep running while a window system goes down and comes back up again (on some platforms). This is useful since a single instance of **mmSolve2D** may need to run for hours or days at a time to solve one problem. When **mmSolve2D** does have a window (`-tk`), it does not place anything in its window. The only effects of the presence of the window are

that any error messages will be displayed in pop-up windows, and that the `-console` option becomes available for displaying a console window in which interactive Tcl commands may be typed. Both features are useful only for debugging.

Since **mmSolve2D** does not present any user interface window of its own, it depends on **mmLaunch** to provide an interface on its behalf. The entry for an instance of **mmSolve2D** in the **Threads** column of any running copy of **mmLaunch** has a checkbutton next to it. This button toggles the presence of a user interface window through which the user may control that instance of **mmSolve2D**. The user interface window is divided into three panels, providing interfaces to the **Inputs**, **Scheduled Outputs**, and **Runtime Control** of **mmSolve2D**.

Inputs

The top panel of the user interface window may be opened and closed by toggling the **Inputs** checkbutton. When open, the **Inputs** panel reveals two subpanels. The left subpanel contains a list of the inputs required by **mmSolve2D**. There is only one item in the list: **ProblemDescription**. When **ProblemDescription** is selected, the right subpanel (labeled **Source Threads**) displays a list of applications that can provide a problem description. The user selects from among the listed applications the one from which **mmSolve2D** should request a problem description.

Outputs

The bottom panel of the user interface window may be opened and closed by toggling the **Scheduled Outputs** button. When open, the **Scheduled Outputs** panel contains three subpanels. Initially each of these subpanels is empty. Once a problem is loaded into **mmSolve2D** and its controls become active (see below), the **Outputs** subpanel is filled with a list of the types of output **mmSolve2D** can generate while solving the loaded problem. The three elements in this list are **TotalField**, for the output of a vector field representing the total effective field, **Magnetization**, for the output of a vector field representing the current magnetization state of the grid of spins, and **DataTable**, for the output of a table of data values describing other quantities of interest calculated by **mmSolve2D**.

Upon selecting one of the output types from the **Outputs** subpanel, a list of applications appears in the **Destination Threads** subpanel which provide a display or storage service for the type of output selected. The user may select from this list those applications to which the selected type of output should be sent.

For each application selected, a final interface is displayed in the **Schedule** subpanel. Through this interface the user may select the timing according to which the selected type

of data is sent to the selected application for display or storage. The timing schedule is described relative to events in **mmSolve2D**. An **Iteration** event occurs at every step in the solution of the ODE. An **Equilibrium** event occurs whenever the solver determines that an equilibrium magnetization state has been reached. An **Interactive** event occurs for a particular output type whenever the corresponding "Interactive Outputs" button is clicked in the **Runtime Control** panel. The **Interactive** schedule gives the user the ability to interactively force data to be delivered to selected display and storage applications. For the **Iteration** and **Equilibrium** events, the granularity of the output delivery schedule is under user control. For example, the user may elect to send vector field data describing the current magnetization state to an **mmDisp** (Sec. 12) instance for display every 25 iterations of the ODE, rather than every iteration.

The quantities included in **DataTable** output produced by **mmSolve2D** include:

- **Iteration:** The iteration count of the ODE solver.
- **Field Updates:** The number of times the ODE solver has calculated the effective field.
- **Sim Time (ns):** The elapsed simulated time.
- **Time Step (ns):** The interval of simulated time spanned by the last step taken in the ODE solver.
- **Step Size:** The magnitude of the last step taken by the ODE solver as a normalized value. (This is currently the time step in seconds, multiplied by the gyromagnetic ratio times the damping coefficient times M_s.)
- **Bx, By, Bz (mT):** The x, y, and z components of the nominal applied field (see Sec. 16.1, Experimental parameters paragraph).
- **B:** The magnitude of the nominal applied field (always non-negative).
- **|m x h|:** The maximum of the point-wise quantity $\|\mathbf{M} \times \mathbf{H}_{\text{eff}}\|/M_s^2$ over all the spins. This "torque" value is used to test convergence to an equilibrium state.
- **Mx/Ms, My/Ms, Mz/Ms:** The x, y, and z components of the average magnetization of the magnetically active elements of the part being simulated.
- **Total Energy:** The total average energy density for the magnetically active elements of the part under simulation, in J/m^3.

- **Exchange Energy:** The component of the average energy density for the magnetically active elements of the part under simulation due to exchange interactions.
- **Anisotropy Energy:** The component of the average energy density for the magnetically active elements of the part under simulation due to crystalline anisotropy.
- **Demag Energy:** The component of the average energy density for the magnetically active elements of the part under simulation due to self-demagnetizing fields.
- **Zeeman Energy:** The component of average energy density for the magnetically active elements of the part under simulation due to interaction with the applied field.
- **Max Angle:** The maximum angle (in degrees) between the magnetization orientation of any pair of neighboring spins in the grid.

Controls

The middle section of the user interface window provides a series of buttons allowing user interaction with the solver. After a problem description server application has been selected, the **LoadProblem** button triggers a fetch of a problem description from the selected server. The **LoadProblem** button may be selected at any time to (re-)load a problem description from the currently selected server. After loading a new problem the solver goes automatically into a paused state. Be warned that selecting the **LoadProblem** button before selecting a problem description server will cause an error. The **Reset** button operates similarly, except that the current problem specifications are used.

Once a problem is loaded, the solver can be put into any of three states: run, relax and pause. Selecting **Relax** puts the solver into the "relax" state, where it runs until an equilibrium is reached, after which the solver pauses. The **Run** selection differs in that when equilibrium is reached, the solver automatically steps the nominal applied field to the next value, and continues. In "run" mode the solver will continue to process until there are no more applied field states in the problem description. (Field state schedules are discussed below.) At any time the **Pause** button may be selected to pause the solver. The solver will stay in this state until the user reselects either **Run** or **Relax**. There is presently no feedback to the user to indicate which state the solver is in.

The problem description (in MIF format) specifies a fixed applied field schedule (see Sec. 16.1, Experimental parameters paragraph). This schedule defines an ordered list of applied fields, which the solver in "run" mode steps through in sequence. The **Field-** and **Field+** buttons allow the user to interactively adjust the applied field sequence. Each click on the **Field+** button advances forward one step through the specified schedule, while

Field- reverses that process. In general, the step direction is *not* related to the magnitude of the applied field. Also note that hitting these buttons does not generate an "equilibrium" event. For example, if you are manually accelerating the progress of the solver through a hysteresis loop, and want to send non-equilibrium data to a display or archive widget before advancing the field, then you must use the appropriate "Interactive Output" button.

The second row of buttons in the solver interaction region, **TotalField**, **Magnetization** and **DataTable**, allow the user to view the current state of the solver at any time. These buttons cause the solver to send out data of the corresponding type to all applications connected to the solver for which the "Interactive" schedule button for that data type has been selected, as discussed in the Outputs section above.

At the far right of the solver controls is the **Exit** button, which terminates **mmSolve2D** (with extreme prejudice). Keep in mind that simply closing the user interface window will not terminate **mmSolve2D**. The **Exit** button must be pressed.

Details

Given a problem description, **mmSolve2D** integrates the Landau-Lifschitz equation

$$\frac{d\mathbf{M}}{dt} = -\gamma\,\mathbf{M}\times\mathbf{H}_{\text{eff}} - \frac{\gamma\alpha}{M_s}\,\mathbf{M}\times(\mathbf{M}\times\mathbf{H}_{\text{eff}})\,, \tag{1}$$

where

$\mathbf{M}$	is the pointwise magnetization (A/m),
$\mathbf{H}_{\text{eff}}$	is the pointwise effective field (A/m),
γ	is the gyromagnetic ratio (m/(A.s)),
α	is the damping coefficient (dimensionless).

The effective field is defined as

$$\mathbf{H}_{\text{eff}} = -\mu_0^{-1}\frac{\partial E}{\partial \mathbf{M}}.$$

The average energy density E is a function of $\mathbf{M}$ specified by Brown's equations, including crystalline anisotropy, exchange, self-magnetostatic (demagnetization) and applied field (Zeeman) terms.

The problem is impressed upon a regular square 2D grid, with 3D magnetization spins positioned at the centers of the grid cells. At present, Neumann boundary conditions are assumed.

The crystalline anisotropy and applied field energy terms are calculated assuming constant magnetization in each cell. The exchange energy is calculated using the eight-neighbor

bilinear interpolation described in [2]. The more usual four-neighbor scheme is available as a compile-time option. See the file `oommf/app/mmsolve/magelt.cc` for details.

The self-magnetostatic field is calculated using fast Fourier transform (FFT) techniques. Inside each cell, the magnetization is assumed constant along the z-axis. In the xy-plane, two models are supported: constant magnetization and constant charge. The model is selected as part of the problem description in MIF format; see Sec. 16.1, Demag specification paragraph, for details.

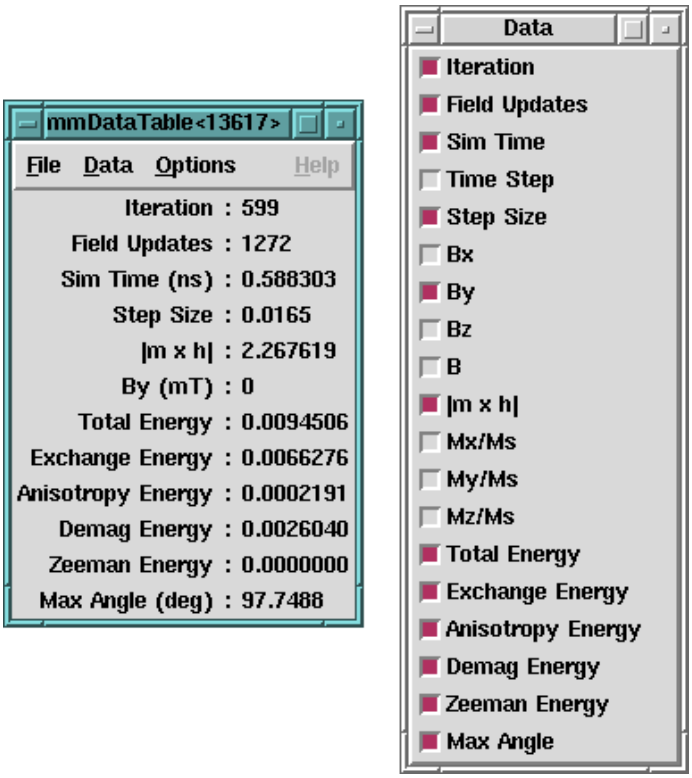
The Landau-Lifschitz ODE (1) is integrated using a second order predictor-corrector technique of the Adams type. The right side of (1) at the current and previous step is extrapolated forward in a linear fashion, and is integrated across the new time interval to obtain a quadratic prediction for $\mathbf{M}$ at the next time step. (At each stage the spins are renormalized to M_s before evaluating the energy and effective fields.) The right side of (1) is evaluated at the predicted $\mathbf{M}$, which is then combined with the value at the current step to produce a linear interpolation of $d\mathbf{M}/dt$ across the new interval. This is then integrated to obtain the final estimate of $\mathbf{M}$ at the new step. The local (one step) error of this procedure should be $O(\Delta t^3)$.

The step is accepted if the total energy of the system decreases, and the maximum error between the predicted and final $\mathbf{M}$ is smaller than a nominal value. If the step is rejected, then the step size is reduced and the integration procedure is repeated. If the step is accepted, then the error between the predicted and final $\mathbf{M}$ is used to adjust the size of the next step. No fixed ratio between the previous and current time step is assumed.

A first order Euler step is used to prime the predictor-corrector solver. A fourth order Runge-Kutta solver is included in the code, and is used as a backup in case the predictor-corrector fails to find a valid step. The Runge-Kutta solver is not selectable as the primary solver at runtime, but may be so selected at compile time by defining the `RUNGE_KUTTA_ODE` macro. See the file `oommf/app/mmsolve/grid.cc` for all details of the integration procedure.

The integration is stopped and equilibrium is assumed when the maximum value of $\|\mathbf{M} \times \mathbf{H}_{\text{eff}}\|/M_s^2$ drops below the value specified for "Converge |mxh| Value" in the problem description.

10 Data Table Display: mmDataTable



Overview

The application **mmDataTable** provides a data display service to its client applications. It accepts data from clients and displays it in a window. Its typical use is to display the evolving values of quantities computed by a micromagnetic solver program.

Launching

mmDataTable may be started either by selecting the **mmDataTable** button on **mmLaunch**, or from the command line via

```
tclsh app/oommf/oommf.tcl mmDataTable [-console]
```

Inputs

The client application(s) that send data to **mmDataTable** for display control the flow of data. The user, interacting with the **mmDataTable** window, controls how the data is displayed. Upon launch, **mmDataTable** displays only a menu bar. Upon user request, a display window below the menubar displays data values.

Each message from a client contains a list of (name, value, units) triples containing data for display. For example, one element in the list might be {`Magnetization 800000 A/m`}. **mmDataTable** stores the latest value it receives for each name. Earlier values are discarded when new data arrives from a client.

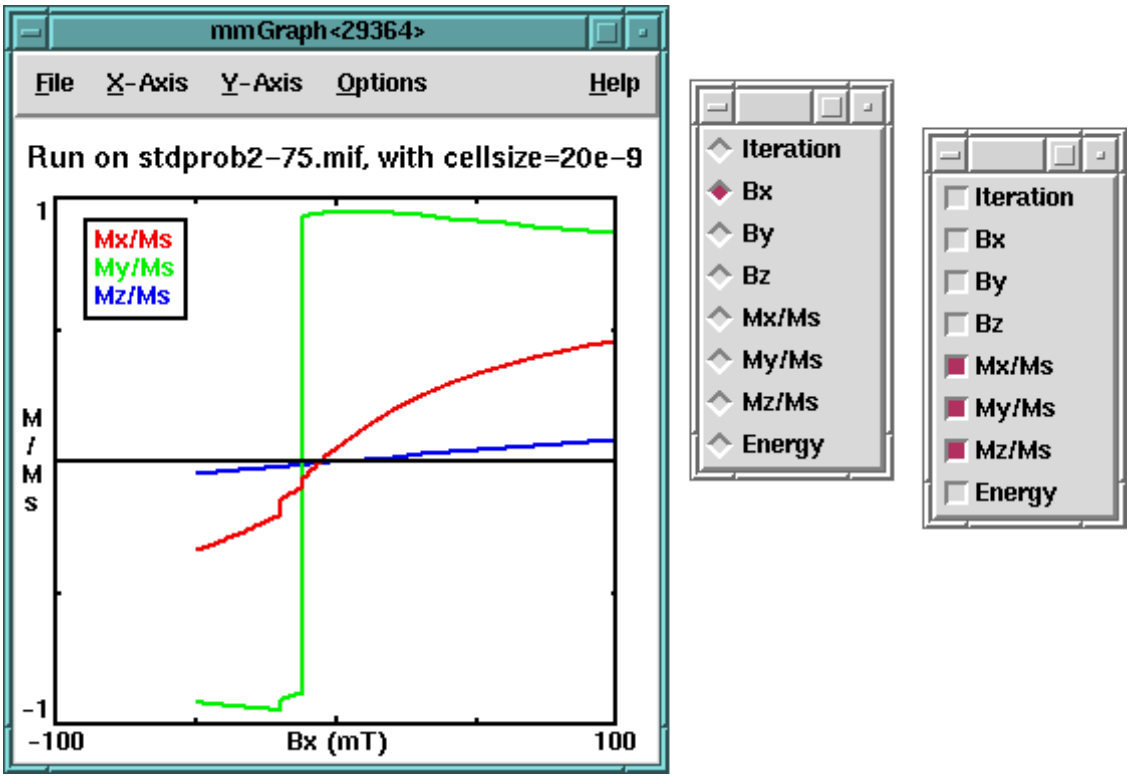
Controls

The **Data** menu holds a list of all the data names for which **mmDataTable** has received data. Each data name on the list lies next to a checkbutton. When the checkbutton is toggled from off to on, the corresponding data name and its value and units are displayed at the bottom of the display window. When the checkbutton is toggled from off to on, the corresponding data name is removed from the display window. In this way, the user selects from all the data received what is to be displayed. The **Data** menu is detachable so the user may easily click multiple checkbuttons.

In addition to selecting what data names are displayed, the user may also control the format in which the data values are displayed. A mouse click on a displayed data value brings up a dialog box in which the user may specify the formatting the value undergoes (by the Tcl command `format`) prior to display. The **Options** menu includes a **Format** menu item which lets the user set the default formatting for data values.

The menu selection **File|Exit** terminates the **mmDataTable** application. The menu **Help** provides the usual help facilities.

11 Data Graph Display: mmGraph



Overview

The application **mmGraph** provides a data display service similar to that of **mmDataTable** (Sec. 10). The usual data source is a running solver, but rather than the textual output provided by **mmDataTable**, **mmGraph** produces 2D line plots. **mmGraph** also stores the data it receives, so it can produce multiple views of the data and can save the data to disk. Postscript output is also supported.

Launching

mmGraph may be started either by selecting the **mmGraph** button on mmLaunch, or from the command line via

```
tclsh app/oommf/oommf.tcl mmGraph [-console]
```

Inputs

Input to **mmGraph** may come from either a file in the ODT format (Sec. 16.2), or from a client application (typically a running solver). File input is initiated through the **File|Open...** dialog box. Receipt of data from client applications is the same as for **mmDataTable** (Sec. 10).

Outputs

Unlike **mmDataTable**, **mmGraph** stores the data sent to it. This data may be written to disk via the **File|Save As...** dialog box. If the file specified already exists, then **mmGraph** output is appended to that file. The output is in the tabular ODT format described in Sec. 16.2. By default, all data currently held by **mmGraph** is written, but the **Save: Selected Data** option presented in the **File|Save As...** dialog box causes the output to be restricted to those curves currently selected for display. In either case, the graph display limits do *not* affect the output.

After the first time a file has been selected for output, the **File|Save** menu option becomes active. Selecting this causes **mmGraph** to append its data to the last selected file. The **Save: All Data/Selected Data** option is preserved. **mmGraph** does not keep track of what data has already been written to disk, so typically the **File|Save** option is used in conjunction with the **Options|clear Data** control.

The **File|Print...** dialog is used to produce a Postscript file of the current graph. On Unix systems, the output may be sent directly to a printer by filling the **Print to:** entry with the appropriate pipe command, e.g., `|lpr`. (The exact form is system dependent.)

Controls

Graphs are constructed by selecting any one item off the **X-Axis** menu, and any number of items off the **Y-Axis** menu. Either of these menus may be detached by selecting the dashed rule at the top of the list. Sample results are shown in the figure at the start of this section.

When **mmGraph** is first launched, the axis menus are both empty. They are dynamically built based on the data received by **mmGraph**. By default, the graph limits and labels are automatically set based on the data. The x-axis label is set using the data label and measurement unit, if any. The y-axis label is the measurement unit of the first y-axis item selected. To change the default y-axis label, deselect all y-axis items and select a different first item.

The **Options|Configure...** dialog box allows the user to override the default settings. To set the axis labels, deselect the **Auto Label** option in this dialog box, and fill in the **X**

Label and **Y Label** fields as desired. The axis limits can be set in a similar fashion. In addition, if an axis limit is left empty, a default value (based on all selected data) will be used.

As mentioned earlier, **mmGraph** stores all data it receives. Over the course of a long run, the amount of data stored can grow to many megabytes. This storage can be limited by specifying a positive value for the **Point buffer size** entry in the **Options|Configure...** dialog box. The oldest records are removed as necessary to keep the total number of records stored under the specified limit. A zero value for **Point buffer size** is interpreted as no limit. (The storage size of an individual record depends upon several factors, including the number of items in the record and the version of Tcl being used.) Data erasures may not be immediately reflected in the graph display.

At any time, the point buffer storage can be completely emptied with the **Options|clear Data** command. Also on this menu is **Options|Rescale**, which autoscales the graph axis limits from the selected data. This command ignores but does not reset the "Auto Scale" settings in the **Options|Configure...** dialog box.

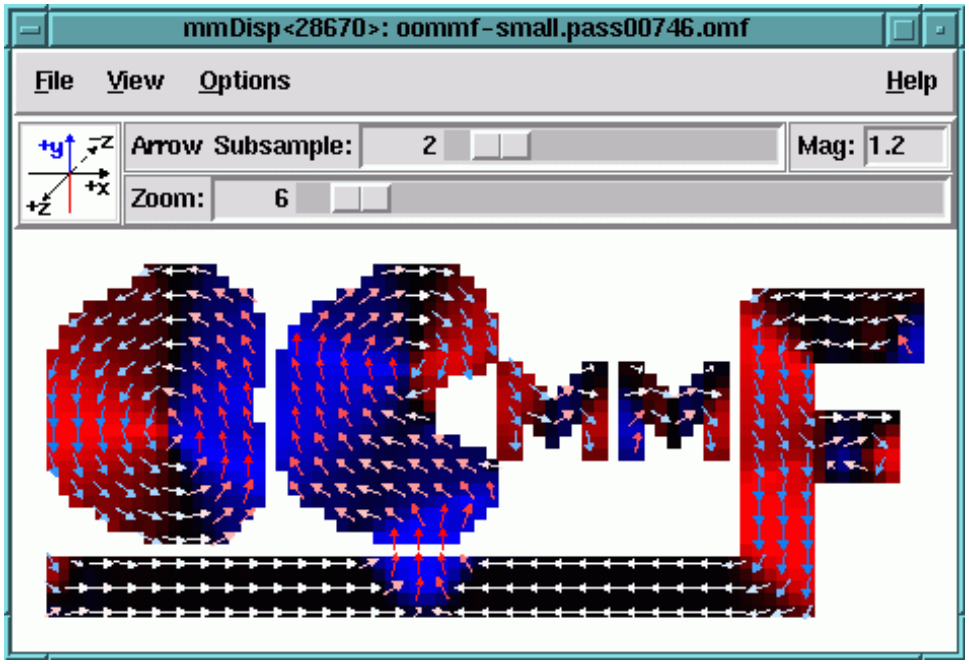
The last command on the options menu is **Options|Key**, which toggles the key (legend) display on and off. The key may also be repositioned by dragging with the first mouse button.

Two other controls are also available only through the mouse. If the mouse pointer is positioned over a drawn item in the graph, holding down any mouse button will bring up the coordinates of that point. The coordinates displayed are the coordinates of a point on a drawn line, which are not necessarily the coordinates of a plotted data point. (The data points are plotted at the endpoints of each line segment.) The coordinate display is cleared when the mouse button is released.

One vertical and one horizontal rule (line) are also available. Initially, these rules are tucked and hidden against the left and bottom graph axes, respectively. Either may be repositioned by dragging with the first mouse button.

The menu selection **File|Exit** terminates the **mmGraph** application. The menu **Help** provides the usual help facilities.

12 Vector Field Display: mmDisp



Overview

mmDisp displays a two-dimensional spatial distribution of three-dimensional vectors (i.e., a vector field). It can load vector fields from files in a variety of formats, or it can accept vector field data from a client application, typically a running solver. **mmDisp** offers to the user a rich interface for controlling the display of vector field data, and can also save the data to a file and produce Postscript print output.

Launching

mmDisp may be started either by selecting the **mmDisp** button on **mmLaunch**, or from the command line via

```
tclsh app/oommf/oommf.tcl mmDisp [-server] [-version] \
       [-console] [--] [<fileName>]
```

The command line option `-server` makes mmDisp a server supplying vector field display services to other applications. Without that option **mmDisp** only displays vector field data

loaded from files. The `-server` option is automatically included when **mmDisp** is launched by **mmLaunch**.

If the option `-version` is present on the command line, version information is printed, and **mmDisp** exits immediately.

If a filename is supplied on the command line, **mmDisp** takes it to be the name of a file containing vector field data for display. That file will be opened on startup.

Inputs

Input to **mmDisp** may come from either a file or from a client application (typically a running solver), in any of the vector field formats (Sec. 16.3).

File input is initiated through the **File|Open...** dialog box. Several example files are included in the OOMMF release directory `app/mmdisp/examples`. When the **Browse** button is enabled, the "Open File" dialog box will remain open after loading a file, so that multiple files may be displayed in sequence. The **Auto** configuration box determines whether the arrow subsampling or the zoom factor of the display should be determined automatically based on the data in the file to be loaded and the current display window size, or whether their values should be held constant while loading the file.

The client application(s) that send data to **mmDisp** for display control the flow of data. The user, interacting with the **mmDisp** window, controls how the vector field data are displayed.

Outputs

The vector field displayed by **mmDisp** may be saved to disk via the **File|Save As...** dialog box. The output is in the OVF format (Sec. 16.3.1). The OVF file options may be set by selecting the appropriate radio buttons in the OVF File Options panel. The **Title** and **Desc** fields may be edited before saving. Enabling the **Browse** button allows for saving multiple files without closing the "Save File" dialog box.

The **File|Print...** dialog is used to produce a Postscript file of the current display. On Unix systems, the output may be sent directly to a printer by filling the **Print to:** entry with the appropriate pipe command, e.g., `|lpr`. (The exact form is system dependent.)

Controls

The **View** menu provides to the user high-level control over how the vector field is placed in the display window. The menu selection **View|Wrap Display** resizes the display window so that it just contains the entire vector field surrounded by a margin. **View|Fill Display**

resizes the vector field until it fills the current size of the display window. If the aspect ratio of the display window does not match the aspect ratio of the vector field, a larger than requested margin appears along one edge to make up the difference. **View|Rotate ccw** and **View|Rotate cw** rotate the display one quarter turn counter-clockwise and clockwise respectively. The display window also rotates, so that the portion of the vector field seen and any margins are preserved (unless the display of the control bar forces the display window to be wider). **View|reDraw** allows the user to invoke a redrawing of the display window.

The vector field may be rescaled ("zoomed") and moved so that only a portion of it is visible in the display window. When a portion of the vector field lies outside the display window, scrollbars appear that may be used to translate the vector field so that different portions are visible in the display window. On systems which have a middle mouse button, clicking the middle button on a point in the display window adjusts the display so that the selected location is centered within the display window.

The mouse may also be used within the display window to rescale the display. A click and drag with the left mouse button displays a red rectangle which changes size as the mouse is dragged. When the left mouse button is released, the vector field is rescaled so that the portion of the display window within the red rectangle expands until it reaches the edges of the display window. Both dimensions are scaled by the same amount so there is no distortion of the vector field. Small red arrows on the sides of the red rectangle indicate which dimension will expand to meet the display window boundaries upon release of the left mouse button. After the rescaling, the red rectangle remains in the display window briefly, surrounding the same region of the vector field, but at the new scale.

A click and drag with the right mouse button displays a blue rectangle which changes size as the mouse is dragged. When the right mouse button is released, the vector field is rescaled so that all of the vector field currently visible in the display window fits in the size of the blue rectangle. Both dimensions are scaled by the same amount so there is no distortion of the vector field. Small blue arrows on the sides of the blue rectangle indicate the dimension in which the vector field will shrink to exactly transform the display window size to the blue rectangle size. After the rescaling, the blue rectangle remains in the display window briefly, surrounding the same region of the vector field, now centered in the display window, and at the new scale.

mmDisp remembers the previous display scale. To revert to the previous scale, the user may hit the `ESC` key. This is a limited "Undo" feature.

The menu selection **Options|Configure...** brings up a dialog box through which the user may control many features of the vector field display. Vectors in the vector field may be displayed as arrows, pixels, or both. The **Arrow** and **Pixel** buttons in the **Plot type** column on the left of the dialog box enable each type of display.

Both arrows and pixels may be colored to indicate some quantity. Columns 2-4 in the

Configure dialog box control the use of color. **Colormap**s are labeled by three colors, those which are used to display one extreme value, the middle value, and the other extreme value of a range in which the quantity represented by color takes its value. The **#of Colors** controls the number of levels to which **mmDisp** quantizes the displayed quantity when representing it with color, controlling how much use **mmDisp** makes of potentially limited color resources. The **Color Quantity** selects which scalar quantity the color of the arrow or pixel represents. The x, y, or z components of the vector may be selected. On regularly gridded data the vector field divergence is also available for display.

When there are many vectors in a vector field, a display of all of them can be more confusing than helpful. The **Subsample Rate** column allows the user to request that only a sampling of vectors from the vector field be displayed. The **Subsample Rate** value is roughly the number of vectors along one dimension of the vector field which map to a single displayed vector (arrow or pixel). Each vector displayed is an actual vector in the vector field—the selection of vectors for display is a sampling process, not an averaging or interpolation process. The subsample rates for arrows and pixels may be set independently. A subsample rate of 0 is interpreted specially to display all data. (This is typically much quicker than subsampling at a small rate, e.g., 0.1.)

An arrow or pixel which represents a vector is by default displayed at a size which covers the portion of the vector field which that displayed vector is intended to represent, given the current subsample rate. Following this default, arrows do not significantly overlap each other, yet all portions of the vector field which are magnetically active have a representation in the display. The **Magnification** column allows the user to modify the size of the displayed arrows or pixels (independently). A **Magnification** of 1 is the default size. By changing to a larger or smaller **Magnification** value, the user may request arrows or pixels larger or smaller than the default size.

Lower in the **Option|Configure...** dialog box, the user may also select whether or not a rectangle representing the boundary of the vector field is displayed, what margin (in pixels) should be maintained around the vector field, and what background color the display window should use.

None of the changes made by the user in the **Options|Configure...** dialog box affect the display window until either the **Apply** or **OK** button is selected. If the **OK** button is selected, the dialog box is dismissed. The **Cancel** button dismisses the dialog.

The other item under the **Options** menu is a checkbutton which toggles the display of a control bar. The control bar offers alternative interfaces to some of the operations available from the **Options|Configure...** dialog box and the **View** menu. To the left of the control bar is a display of coordinate axes. These axes rotate along with the vector field in the display window to identify the coordinate system of the display, and are color coded to agree with the pixel (if active) or arrow coloring. A click of the left mouse button on the coordinate

axes causes a counter-clockwise rotation. A click of the right mouse button on the coordinate axes causes a clockwise rotation.

To the right of the coordinate axes, are two rows of controls. The top row allows the user to control the subsample rate and magnification of the arrow display. The subsample rate may be modified either by direct entry of a new rate, or by manipulation of the slider.

The lower row offers an alternative means to control the rescaling of the vector field in the display. The **Zoom** value roughly corresponds to the number of pixels per vector in the vector field. This value may be entered directly, or modified by manipulation of the slider. This alternative interface provides a more precise control over the rescaling of the vector field display than mouse operations provide.

Several keyboard shortcuts are available as alternatives to menu- or mouse-based operations. The effect of a key combination depends on which subwindow of **mmDisp** is active. The `TAB` key may be used to change the active subwindow. The `SHIFT-TAB` key combination also changes the active subwindow, in reverse order.

When the active subwindow is the display window, the following key combinations are active:

- `CTRL-o` – same as menu selection **File|Open...**
- `CTRL-s` – same as menu selection **File|Save as...**
- `CTRL-p` – same as menu selection **File|Print...**
- `CTRL-w` – same as menu selection **View|Wrap Display**
- `CTRL-f` – same as menu selection **View|Fill Display**
- `HOME` – First fill, then wrap the display.
- `CTRL-r` – same as menu selection **View|Rotate ccw**
- `SHIFT-CTRL-r` – same as menu selection **View|Rotate cw**
- `INSERT` – increase arrow subsample by 1
- `DEL` – decrease arrow subsample by 1
- `SHIFT-INSERT` – increase arrow subsample by factor of 2
- `SHIFT-DEL` – decrease arrow subsample by factor of 2
- `PAGEUP` – increase the zoom value by a factor of 1.149

- `PAGEDOWN` – decrease the zoom value by a factor of 1.149
- `SHIFT-PAGEUP` – increase the zoom value by factor of 2
- `SHIFT-PAGEDOWN` – decrease the zoom value by factor of 2

When the active subwindow is the control bar's coordinate axes display, the following key combinations are active:

- `LEFT` – same as menu selection **View|Rotate ccw**
- `RIGHT` – same as menu selection **View|Rotate cw**

When the active subwindow is any of the control bar's value entry windows – arrow subsample, magnification, or zoom, the following key combinations are active:

- `ESC` – undo uncommitted value (displayed in red)
- `RETURN` – commit entered value

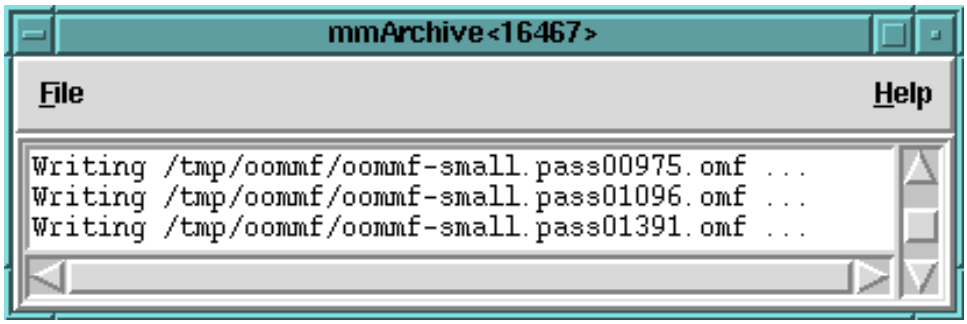
When the active subwindow is wither of the control bar's sliders – arrow subsample or zoom, the following key combinations are active:

- `LEFT` – slide left (decrease value)
- `RIGHT` – slide right (increase value)
- `ESC` – undo uncommitted value (displayed in red)
- `RETURN` – commit current value

Of course the usual keyboard access to the menu items is also available.

The menu selection **File|Clear** clears the display window. The menu selection **File|Exit** terminates the **mmDisp** application. The menu **Help** provides the usual help facilities.

13 Data Archive: mmArchive



Overview

The application **mmArchive** provides a vector field data storage service. Although **mmDisp** (Sec. 12) is able to save vector field data under the direction of the user, there are situations where it is more convenient to direct the archiving of vector field data without continual action by the user. **mmArchive** accepts vector field data from its clients and saves it. In some ways, **mmArchive** performs the inverse function of **FileSource** (Sec. 8).

Launching

mmArchive may only be started by selecting the **mmArchive** button on **mmLaunch**. In the current release of OOMMF it is not visible to the bootstrap application.

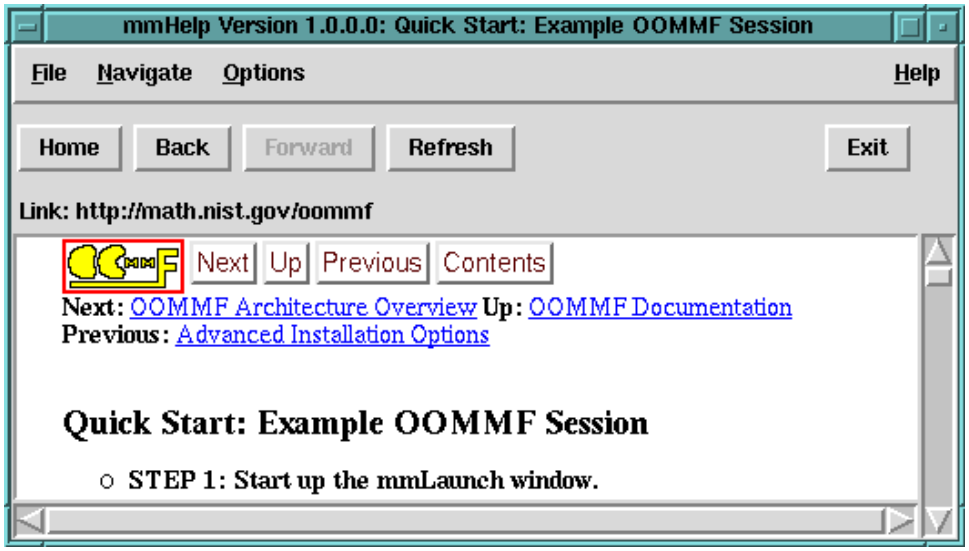
Inputs

The client application(s) that send data to **mmArchive** for storage control the flow of data. **mmArchive** receives vector field data from its clients (really the name of a temporary file which holds the data) and copies the data to a file named by the client. The **mmArchive** window displays messages reporting its actions. Other than that, **mmArchive** provides no means for the user to interact with its functioning.

Controls

The menu selection **File|Exit** terminates the **mmArchive** application. The menu **Help** provides the usual help facilities.

14 Documentation Viewer: mmHelp



Overview

The application **mmHelp** manages the display and navigation of hypertext (HTML) help files. It presents an interface similar to that of World Wide Web browsers.

Although **mmHelp** is patterned after World Wide Web browsers, it does not have all of their capabilities. **mmHelp** displays only a simplified form of hypertext required to display the OOMMF help pages. It is not able to display many of the advanced hypertext features provided by modern World Wide Web browsers. In the current release, **mmHelp** is not able to follow `http:` URLs. It only follows `file:` URLs.

OOMMF software can be customized (See Sec. 2.3.2) to use another program to display HTML files.

Launching

mmHelp may be launched from the command line via

```
tclsh app/oommf/oommf.tcl mmHelp [<URL>] [-console]
```

The command line argument `<URL>` is the URL of the first page (or home page) to be displayed. If no URL is specified, **mmHelp** displays the Table of Contents of the OOMMF User's Guide by default.

Controls

Each page of hypertext is displayed in the main **mmHelp** window. Words which are underlined and colored blue are hyperlinks which **mmHelp** knows how to follow. Words which are underlined and colored red are hyperlinks which **mmHelp** does not know how to follow. Moving the mouse over one of these hyperlinks displays the target URL of the hyperlink in the **Link:** line above the display window. Clicking on a blue hyperlink will follow the hyperlink and display a new page of hypertext.

mmHelp keeps a list of the viewed pages in order of view. Using the **Back** and **Forward** buttons, the user may move backward and forward through this list of pages. The **Home** button causes the first page to be displayed, allowing the user to start again from the beginning. These three buttons have corresponding entries in the **Navigate** menu.

The menu selection **File|Refresh**, or the **Refresh** button causes **mmHelp** to reload and redisplay the current page. This may be useful if the display becomes corrupted, or for repeatedly loading a hypertext file which is being edited.

When **mmHelp** encounters hypertext elements it does not recognize, it will attempt to work around the problem. However, in some cases it will not be able to make sense of the hypertext, and will display an error message. Documentation authors should take care to use only the hypertext elements supported by **mmHelp** in their documentation files. Users should never see such an error message.

mmHelp displays error messages in one of two ways: within the display window, or in a separate window. Errors reported in the display window replace the display of the page of hypertext. They usually indicate that the hypertext page could not be retrieved, or that its contents are not hypertext. File permission errors are also reported in this way.

Errors reported in a separate window are usually due to a formatting error within the page of hypertext. Selecting the **Continue** button of the error window instructs **mmHelp** to attempt to resume display of the hypertext page beyond the error. Selecting **Abort** abandons further display.

The menu selection **Options|Font scale...** brings up a dialog box through which the user may select the scale of the fonts to use in the display window, relative to their initial size.

The menu selection **File|Exit** or the **Exit** button terminates the **mmHelp** application. The menu **Help** provides the usual help facilities.

15 OOMMF Batch System

The OOMMF Batch System (OBS) provides a scriptable interface (`batchsolve.tcl`) to the same micromagnetic solver engine used by **mmSolve2D** (Sec. 9), and several Tcl scripts (`batchmaster.tcl`, `batchslave.tcl`, and `batchtask.tcl`) that provide support for complex job scheduling. All OBS script files are in the OOMMF distribution directory `app/mmsolve/scripts`.

Unlike most of the OOMMF package, the OBS is meant to be driven primarily from the command line or shell (batch) script. OBS applications are launched from the command line using the bootstrap application (Sec. 5).

15.1 Batch solver

Overview

The batch solver script `batchsolve.tcl` provides a simple command line interface to the OOMMF micromagnetic solver engine.

Launching

The batch solver is launched by the command line:

```
tclsh app/oommf/oommf.tcl batchsolve [[-file] <filename.mif>] \
     [-no_interface] [-start_paused] [-end_paused] [-end_exit]
```

where

[**-file**] <**filename.mif**> Immediately load and run the specified MIF file. The `[-file]` tag may be omitted if the first character of `filename` is not a hyphen.

-no_interface Do not register with the account service directory application. This means **mmLaunch** (Sec. 6) doesn't learn from `batchsolve.tcl` how to provide an interactive interface on its behalf. (However, if `batchsolve.tcl` is invoked from inside another script (e.g., `batchslave.tcl`), the calling script could provide an interface to the batch-controlled solver.)

-start_paused Pause solver after loading problem.

-end_paused Pause solver and enter event loop at bottom of `batchsolve.tcl` rather than just falling off the end (the effect of which will depend on whether or not Tk is loaded).

-end_exit Explicitly call exit at bottom of `batchsolve.tcl`.

The input `filename.mif` file contains a Micromagnetic Input Format (Sec. 16.1) (MIF) problem description, such as produced by **mmProbEd** (Sec. 7). The batch solver searches several directories for this file, including the current working directory, the `data` and `scripts` subdirectories, and parallel directories relative to the directories `app/mmsolve` and `app/mmpe` in the OOMMF distribution. Refer to the `mif_path` variable in `batchsolve.tcl` for the complete list.

If `batchsolve.tcl` registers itself with the account service directory application, it will appear in the **Threads** list of any running copy of **mmLaunch**, and **mmLaunch** will provide an interactive interface on behalf of `batchsolve.tcl`. Using this interface, `batchsolve.tcl` may be controlled in a manner similar to **mmSolve2D** (Sec. 9). The interface allows you to pause, un-pause, and terminate the current simulation, as well as attach data display and storage applications to monitor the solver's progress. If more interactive control is needed, **mmSolve2D** should be used.

Use the `-start_paused` switch to monitor the progress of `batchsolve.tcl` from the very start of a simulation. With this switch the solver will be paused immediately after loading the specified MIF file, so you can bring up the interactive interface and connect display applications before the simulation begins. Start the simulation by selecting the **Run** command from the interactive interface.

The `-end_paused` switch insures that the solver does not automatically terminate after completing the specified simulation. This is not generally useful, but may find application when `batchsolve.tcl` is called from inside a Tcl-only wrapper script.

Output

The output may be changed by a Tcl wrapper script (see Sec. 15.1), but the default output behavior of `batchsolve.tcl` is to write tabular text data and the magnetization state at equilibrium for each field step. The tabular data are appended to the file *basename*`.odt`, where *basename* is specified in the input MIF file. See the routine `GetTextData` in `batchsolve.tcl` for current details, but at present the output consists of solver iteration count, nominal applied field **B**, reduced magnetization **m**, and total energy. This output is in the ODT file format.

The magnetization data are written to a series of OVF (OOMMF Vector Field) files, *basename*`.field`*nnnn*`.omf`, where *nnnn* starts at `0000` and is incremented at each field step. (The ASCII header inside each file records the nominal applied field at that step.) These files are viewable using **mmDisp** (Sec. 12).

Programmer's interface

In addition to directly launching `batchsolve.tcl` from the command line, it may also be sourced from inside another Tcl script, e.g., `batchslave.tcl`, that provides additional control structures. There are several variables and routines inside `batchsolve.tcl` that may be accessed and redefined from such a wrapper script to provide enhanced functionality.

Global variables

mif This is a Tcl handle to a global `mms_mif` object that is used to initialize and reset the solver by the default `batchsolver.tcl` routines.

solver Handle to the `mms_solver` object.

search_path Directory search path use by the `FindFile` proc (cf. Sec. 15.1).

Refer to the documentation on these objects for details on their manipulation.

Batchsolve procs

The following Tcl procedures are designed for external use and/or redefinition:

SolverTaskInit Called at the start of each task.

BatchTaskRelaxCallback Called at each equilibrium state reached in the simulation.

SolverTaskCleanup Called at the conclusion of each task.

FindFile Finds a file using the directory search path specified by the global variable `search_path`. The default `SolverTaskInit` proc uses this routine to locate the requested input MIF file.

The first and third of these accept an arbitrary argument list (`args`), which is copied over from the `args` argument to `BatchTaskRun` and `BatchTaskLaunch`. Typically one copies the default procs (as needed) into a task script, and makes appropriate modifications. You may (re-) define these procs either before or after sourcing `batchsolve.tcl`. See Sec. 15.2.3 for example scripts.

15.2 Batch scheduler

Overview

The OBS provides support for complex scheduling of multiple batch jobs, via the two files `batchmaster.tcl` and `batchslave.tcl`, plus a user defined task script. The task script may be modeled after the included `simpletask.tcl` or `multtask.tcl` sample scripts.

The OBS has been designed to control multiple sequential and concurrent micromagnetic simulations, but the scheduling scripts `batchmaster.tcl` and `batchslave.tcl` are completely general and may be used to schedule other types of jobs as well.

When `batchmaster.tcl` is run, it sources a task script which should modify the global object `$TaskInfo` to inform the master what tasks to perform and optionally how to launch slaves to perform those tasks. This is detailed in Sec. 15.2.2. After this, `batchmaster.tcl` launches all the specified slaves, initializes each with a slave initialization script, and then feeds tasks sequentially from the task list to the slaves. When a slave completes a task it reports back to the master and is given the next unclaimed task. If there are no more tasks, the slave is shut down. When all the tasks are complete, the master prints a summary of the tasks and exits.

Launching

The batch scheduler is launched by the command line:

```
tclsh app/oommf/oommf.tcl batchmaster <task_script.tcl> \
                      [server_host [server_port]]
```

where

<**task_script.tcl**> is the user defined task (job) definition file,

server_host specifies the network address for the master to use (default is *localhost*),

server_port is the port address for the master (default is *0*, which selects an arbitrary open port).

The required <`task_script.tcl`> should be based on the example scripts in Sec. 15.2.3. If slaves are to be run on remote machines, then `server_host` **must** be set to the local machine's network name, and the `$TaskInfo` methods `AppendSlave` and `ModifyHostList` will need to be called from inside the task script. See Sec. 15.2.2 for details.

15.2.1 Batch master and slave specifics

The communication protocol between `batchmaster.tcl` and `batchslave.tcl` is currently evolving and is not described here. Check the source code for the latest details.

The command line to start the master script is shown in Sec. 15.2 above. The slave will be launched by the master using instructions specified in the task script, which should take the form

```
oommf.tcl batchslave $server(host) $server(port) $slaveid \
          $passwd [aux_script [aux_args]]
```

The arguments (`$server(host)` through `$passwd`) are provided by the master and should be specified in the task script using the `%connect_info` percent substitution token. The `aux_script` is a script for the slave to source before processing any commands from the master. Typically this will be the micromagnetic batch mode script, `batchsolve.tcl`. The `aux_args` are additional arguments that will be passed to `aux_script`.

15.2.2 Batch task scripts

The master script creates an instance of a `BatchTaskObj` object with the name `$TaskInfo`. The task script uses method calls to this object to set up tasks to be performed. The only required call is to the `AppendTask` method, e.g.,

```
$TaskInfo AppendTask A "BatchTaskRun taskA.mif"
```

This method expects two arguments, a label for the task (here "A") and a script to accomplish the task. The script will be passed across a network socket from the master to the slave, and then the script will be interpreted by the slave. (In particular, keep in mind that the file system seen by the script will be that of the machine on which the slave process is running.)

This example uses the default `batchsolve.tcl` procs to run the simulation defined by the `taskA.mif` MIF file. If you want to make changes to the MIF problem specifications on the fly, you will need to modify the default procs. This is done by creating a slave initialization script, via the call

```
$TaskInfo SetSlaveInitScript { <insert script here> }
```

The slave initialization script does global initializations, and usually redefines the `SolverTaskInit` proc, and optionally the `BatchTaskRelaxCallback` and `SolverTaskCleanup` procs as well. `SolverTaskInit` is called by `BatchTaskRun` (inside `batchsolve.tcl`) at the start of each task, `BatchTaskRelaxCallback` is executed when each equilibrium is reached, and `SolverTaskCleanup`

is called at the end of each task. The first and third are passed the arguments that were passed to `BatchTaskRun`. A simple `SolverTaskInit` proc could be

```
proc SolverTaskInit { args } {
   global mif basename outtextfile
   set A [lindex $args 0]
   set outbasename "$basename-A$A"
   $mif SetA $A
   $mif SetOutBaseName $outbasename
   set outtextfile [open "$outbasename.odt" "a+"]
   puts $outtextfile [GetTextData header \
  "Run on $basename.mif, with A=[$mif GetA]"]
}
```

This proc receives the exchange constant `A` for this task on the argument list, and makes use of the global variables `mif` and `basename`. (Both should be initialized in the slave initialization script outside the `SolverTaskInit` proc.) It then stores the requested value of `A` in the `mif` object, sets up the base filename to use for output, and opens a text file to which tabular will be appended. The handle to this text file is stored in the global `outtextfile`, which is closed by the default `SolverTaskCleanup` proc. A corresponding task script could be

```
$TaskInfo AppendTask "A=13e-12 J/m" "BatchTaskRun 13e-12"
```

which runs a simulation with `A` set to 13×10^{-12} J/m. This example is taken from the `multitask.tcl` script in Sec. 15.2.3.

If you want to run more than one task at a time, then the `$TaskInfo` method `AppendSlave` will have to be invoked. This takes the form

```
$TaskInfo AppendSlave <spawn count> <spawn command>
```

where <`spawn command`> is the command to exec to launch the slave process, and <`spawn count`> is the number of slaves to launch with this command. (Typically <`spawn count`> should not be larger than the number of processors on the system.) The default value for this item (which gets overwritten with the first call to `$TaskInfo AppendSlave`) is

```
1 {exec %oommf batchslave -notk %connect_info batchsolve.tcl}
```

This uses the OOMMF bootstrap program to launch the `batchslave` application, with connection information provided by the master, and using the auxiliary script `batchsolve.tcl`. The `batchmaster` script provides several percent-style substitutions useful in slave launch scripts: %oommf, %connect_info, %oommf_root, and %%. The first is an absolute path to

the OOMMF bootstrap program on the master machine, the second is connection information needed by the `batchslave` application, the third is the path to the OOMMF root directory on the master machine, and the last is interpreted as a single percent.

To launch slaves on a remote host, use `rsh` in the spawn command, e.g.,

```
1 {exec rsh foo oommf.tcl batchslave -notk %connect_info \
     batchsolve.tcl}
```

This example assumes `oommf.tcl` is in the execution path on the remote machine `foo`. In addition, you will have to add the machine `foo` to the host connect list with

```
$TaskInfo ModifyHostList +foo
```

and `batchmaster` must be run with the network interface specified as the server host (instead of the default `localhost`), e.g.,

```
oommf.tcl batchmaster multitask.tcl bar
```

where `bar` is the name of the local machine.

This may seem a bit complicated, but the examples in the next section should make things clearer.

15.2.3 Sample task scripts

The first sample task script (Fig. 1) is a simple example that runs the 3 micromagnetic simulations described by the MIF files `taskA.mif`, `taskB.mif` and `taskC.mif`. The example uses the default slave launch script, so a single slave is launched on the current machine, and the 3 simulations will be run sequentially. Also, no slave init script is given, so the default procs in `batchsolve.tcl` are used. Output will be magnetization states and tabular data for each equilibrium state, stored in files on the local machine with base names as specified in the MIF files.

The second task script (Fig. 2) is a more complicated example running concurrent processes on two machines. This script should be run with the command

```
oommf.tcl batchmaster multitask.tcl foo
```

where `foo` is the name of the local machine.

Several Tcl variables (`RMT_MACHINE` through `A_list`) are setup at the top of the `multitask.tcl` script; these are used farther down in the script. The remote machine is specified as `bar`, which is used in the `$TaskInfo AppendSlave` and `$TaskInfo ModifyHostList` commands.

```
# FILE: simpletask.tcl
#
# This is a sample batch task file.  Usage example:
#
#        oommf.tcl batchmaster simpletask.tcl

# Form task list
$TaskInfo AppendTask A "BatchTaskRun taskA.mif"
$TaskInfo AppendTask B "BatchTaskRun taskB.mif"
$TaskInfo AppendTask C "BatchTaskRun taskC.mif"
```

Figure 1: Sample task script `simpletask.tcl`.

There are two `AppendSlave` commands, one to run two slaves on the local machine, and one to run a single slave on the remote machine (`bar`). The latter changes to a specified working directory before launching the `batchslave` application on the remote machine. (For this to work you must have `rsh` configured properly. In the future it will be possible to launch remote commands using the OOMMF account server application, thereby lessening the reliance on system commands like `rsh`.)

After this the slave init script is defined. The Tcl `regsub` command is used to place the task script defined value of `BASEMIF` into the init script template. The init script is run on the slave when the slave is first brought up. It first reads the base MIF file into a newly created `mms_mif` instance. (The MIF file needs to be accessible by the slave process, irrespective of which machine it is running on.) Then replacement `SolverTaskInit` and `SolverTaskCleanup` procs are defined. The new `SolverTaskInit` interprets its first argument as a value for the exchange constant `A`. Note that this is different from the default `SolverTaskInit` proc, which interprets its first argument as the name of a MIF file to load. But with this task script, a MIF file is read once when the slave is brought up, and then each task redefines only the value of `A` for the simulation (and corresponding changes to the output filenames and data table header).

Finally, the Tcl loop structure

```
foreach A $A_list {
    $TaskInfo AppendTask "A=$A" "BatchTaskRun $A"
}
```

is used to build up a task list consisting of one task for each value of `A` in `A_list` (defined at the top of the task script). For example, the first value of `A` is 10e-13, so the first task

will have the label `A=10e-13` and the corresponding script is `BatchTaskRun 10e-13`. The value 10e-13 is passed on by `BatchTaskRun` to the `SolverTaskInit` proc, which has been redefined to process this argument as the value for `A`, as described above.

There are 6 tasks in all, and 3 slave processes, so the first three tasks will run concurrently in the 3 slaves. As each slave finishes it will be given the next task, until all the tasks are complete.

```
# FILE: multitask.tcl
#
# This is a sample batch task file.  Usage example:
#
#        oommf.tcl batchmaster multitask.tcl hostname [port]
#
# Task script configuration
set RMT_MACHINE    bar
set RMT_OOMMF      "~/mag/oommf/app/oommf/oommf.tcl"
set RMT_WORK_DIR   "~/mag/oommf/app/mmsolve/data"
set BASEMIF taskA
set A_list { 10e-13 10e-14 10e-15 10e-16 10e-17 10e-18 }

# Slave launch commands
$TaskInfo ModifyHostList +$RMT_MACHINE
$TaskInfo AppendSlave 1 "exec %oommf batchslave -notk \
        %connect_info batchsolve.tcl"
$TaskInfo AppendSlave 1 "exec rsh $RMT_MACHINE \
        cd $RMT_WORK_DIR \\\;\
        $RMT_OOMMF batchslave -notk %connect_info batchsolve.tcl"

# Slave initialization script (with batchsolve.tcl proc
# redefinitions)
set init_script {
    # Initialize solver. This is run at global scope
    set basename __BASEMIF__      ;# Base mif filename (global)
    mms_mif New mif
    $mif Read [FindFile ${basename}.mif]
    # Redefine TaskInit and TaskCleanup proc's
    proc SolverTaskInit { args } {
        global mif outtextfile basename
```

```
        set A [lindex $args 0]
        set outbasename "$basename-A$A"
        $mif SetA $A
        $mif SetOutBaseName $outbasename
        set outtextfile [open "$outbasename.odt" "a+"]
puts $outtextfile [GetTextData header \
"Run on $basename.mif, with A=[$mif GetA]"]
        flush $outtextfile
    }
    proc SolverTaskCleanup { args } {
        global outtextfile
        close $outtextfile
    }
}
# Substitute $BASEMIF in for __BASEMIF__ in above script
regsub -all -- __BASEMIF__ $init_script $BASEMIF init_script
$TaskInfo SetSlaveInitScript $init_script

# Create task list
foreach A $A_list {
    $TaskInfo AppendTask "A=$A" "BatchTaskRun $A"
}
```

Figure 2: Advanced sample task script `multitask.tcl`.

16 File Formats

16.1 Problem specification format (MIF)

Micromagnetic simulations are specified to the OOMMF solver using files conforming to the OOMMF *Micromagnetic Input Format* (MIF). This is also the native file type for the OOMMF problem editor, `mmProbEd` (Sec. 7). All values in this file are in SI units.

A sample MIF file is presented in Fig. 3. The first line of a MIF file must be of the form "`#` MIF x.y", where x.y represents the format revision number. After this, any line ending in a backslash, '\', is joined to the succeeding line before any other processing is performed. Lines beginning with a '`#`' character are comments and are ignored. Blank lines are also ignored.

All other lines must consist of a *Record Identifier* followed by a parameter list. The Record Identifier is separated from the parameter list by one or more ':' and/or '=' characters. Whitespace and case is ignored in the Record Identifier field.

The parameter list must be a proper Tcl list. The parameters are parsed (broken into separate elements) following normal Tcl rules; in short, items are separated by whitespace, except as grouped by double quotes and curly braces. The grouping characters are removed during parsing. Any '`#`' character that is found outside of any grouping mechanism is interpreted as a comment start character. The '`#`' and all following characters on that line are interpreted as a comment.

Order of the records in a MIF file is unimportant, except as explicitly stated below. If two or more lines contain the same Record Identifier, then the last one takes precedence (except for Field Range records, of which there may be several active). All records are required unless listed as optional. Some of these record types are not yet available from `mmProbEd`, however your may edit a MIF file by hand and feed it to `mmSolve2D` with the `filesource.tcl` application.

For convenience, the Record Identifier tags are organized into several groups; these groups correspond to the buttons presented by `mmProbEd`. We follow this convention below.

Material parameters

- **# Material Name:** This is a convenience entry in `mmProbEd`; inside the MIF file it is a comment line. It relates a symbolic name (e.g., Iron) to specific values to the next 4 items. Ignored by `mmSolve` applications.
- **Ms:** Saturation magnetization in A/m.
- **A:** Exchange stiffness in J/m.

- **K1:** Crystalline anisotropy constant in J/m^3.
- **Anisotropy Type:** Crystalline anisotropy type; One of < uniaxial | cubic >.
- **Anisotropy Dir1:** Directional cosines of first crystalline anisotropy axis, taken with respect to the coordinate axes (3 numbers). Optional; Default is 1 0 0.
- **Anisotropy Dir2:** Directional cosines of second crystalline anisotropy axis, taken with respect to the coordinate axes (3 numbers). Optional; Default is 0 1 0.

  For uniaxial materials it suffices to specify only Anisotropy Dir1. For cubic materials one should also specify Anisotropy Dir2; the third axis direction will be calculated as the cross product of the first two. The anisotropy directions will be automatically normalized if necessary, so for example 1 1 1 is valid input (it will be modified to .5774 .5774 .5774). For cubic materials, Dir2 will be adjusted to be perpendicular to Dir1 (by subtracting out the component parallel to Dir1).
- **Anisotropy Initialization:** Method to use to set up directions of anisotropy axes, as a function of spatial location; This is a generalization of the Anisotropy Dir1/2 records. The value for this record should be one of < Constant | UniformXY | UniformS2 >. Constant uses the values specified for Anisotropy Dir1 and Dir2, with no dispersion. UniformXY ignores the values given for Anisotropy Dir1 and Dir2, and randomly varies the anisotropy directions uniformly in the xy-plane. UniformS2 is similar, but randomly varies the anisotropy directions uniformly on the unit sphere (S^2). This record is optional; the default value is Constant.
- **Do Precess:** If 1, then enable the precession term in the Landau-Lifschitz ODE. If 0, then do pure damping only. (Optional; default value is 1.)
- **Gyratio:** The gyromagnetic ratio, in m/(A.s). This is optional, with default value of 2.21e5. See the discussion of the Landau-Lifschitz ODE under the Damp Coef record identifier description.
- **Damp Coef:** The ODE solver in OOMMF integrates the Landau-Lifschitz equation, written as

$$\frac{d\mathbf{M}}{dt} = -\gamma\,\mathbf{M}\times\mathbf{H}_{\text{eff}} - \frac{\gamma\alpha}{M_s}\,\mathbf{M}\times(\mathbf{M}\times\mathbf{H}_{\text{eff}})\,,$$

  where

  γ is the gyromagnetic ratio (in m/(A.s)),

  α is the damping coefficient (dimensionless).

The last is specified by the "Damp Coef" entry in the input MIF file. If not specified, a default value of 0.5 is used, which allows the solver to converge in a reasonable number of iterations. Physical materials will typically have a damping coefficient in the range 0.004 to 0.15.

Demag specification

- **Demag Type:** Specify algorithm used to calculate self-magnetostatic (demagnetization) field. Must be one of
  - **3dSlab:** Calculate the in-plane field components using offset blocks of constant (volume) charge. Details are given in [1]. Fields components parallel to the z-axis are calculated using squares of constant (surface) charge on the upper and lower surfaces of the sample.
  - **3dCharge:** Calculate the in-plane field component using rectangles of constant (surface) charge on each cell. This is equivalent to assuming constant magnetization in each cell. The z-components of the field are calculated in the same manner as for the 3dSlab approach.
  - **FastPipe:** Algorithm suitable for simulations that have infinite extent in the z-direction. This is a 2D version of the 3dSlab algorithm.
  - **None:** No demagnetization. Fastest but least accurate method.

  The 3dSlab and 3dCharge methods require the Part Thickness (cf. the Part Geometry section) be set. All algorithms use Fast Fourier Transform (FFT) techniques to accelerate the calculations.

Part geometry

- **Part Width:** Nominal part width (x-dimension) in meters. Will be adjusted to an integral multiple of Cell Size.
- **Part Height:** Nominal part height (y-dimension) in meters. Will be adjusted to an integral multiple of Cell Size.
- **Part Thickness:** Part thickness (z-dimension) in meters. Required for 3d models.
- **Cell Size:** In-plane (xy-plane) dimension of base calculation cell. This cell is a rectangular brick, with square cross-section and thickness given by Part Thickness.

- **Part Shape:** Optional. In-plane part shape, which must be one of the following:
  - **Rectangle:** The sample completely fills the area specified by Part Width and Part Height. (Default.)
  - **Ellipse:** The sample (or the magnetically active portion thereof) is an ellipse inscribed into the rectangular area specified by Part Width and Part Height.
  - **Oval:** Shape is a rounded rectangle, where each corner is replaced by a quarter circle with radius r, where r is given by a required second parameter.
  - **Mask:** Shape is determined by a 2-color bitmap file, the name of which is specified as a second parameter. The given filename must be accessible to the `mmSolve` application. At present the bitmap file must be in either the PPM (portable pixmap) or GIF format. The bitmap will be scaled as necessary to fit the simulation. The magnetically active cells are the ones that are black in the bitmap.

Initial magnetization

- **Init Mag:** Name of routine to use initial the simulation magnetization directions (as a function of position), and routine parameters, if any. Optional, with default Random. The list of routines is long, and it is easy to add new ones. See the file `maginit.cc` for details. A few of the more useful routines are:
  - **Random**: Random directions on the unit sphere. This is somewhat like a quenched thermal demagnetized state.
  - **Uniform**: Uniform magnetization in the direction indicated by the two additional parameters, θ and ϕ, where the first is the angle from the z-axis (in degrees), and the second is the angle from the x-axis (in degrees) of the projection onto the xy-plane.
  - **Vortex**: Fits an idealized vortex about the center of the sample.
  - **avfFile**: One additional parameter required, specifying the name of a OVF/SVF/VIO (i.e., "any" vector field) file to use to initialize the magnetization. The grid in the input file will be scaled as necessary to fit the grid in the current simulation. The file must be accessible to the intended `mmSolve` application.

Experiment parameters

The following records specify the applied field schedule:

- **Field Range Count:** Number of Field Ranges specified (integer). Optional, with default value 1. If used, this record should precede all Field Range records.

- **Field Range:** Specifies a range of applied fields that are stepped though in a linear manner. The parameter value is a list of 7 numbers, the starting field Bx By Bz in Tesla, the stopping field Bx By Bz in Tesla, and an integer number of steps to take between the starting and stopping fields (inclusive). There should be as many of these records as specified by the Field Range Count record. They will be stepped through in order of appearance. This record is optional, with a default value of 0 0 0 0 0 0 1.

- **Field Type:** External field routine and parameters, if any. This is optional, with default Uniform. At most one record of this type is allowed, but the Multi type may be used to apply a collection of fields. The nominal applied field (NAF) is stepped through the Field Ranges as describe above, and made available to the external field routines which use or ignore it as appropriate.

  The following routines are available:

  - **Uniform**
    Applied field is uniform with value specified by the NAF.
  - **Ribbon relcharge x0 y0 x1 y1 height**
    Charge "Ribbon," lying perpendicular to the xy-plane. Here relcharge is the charge strength relative to Ms, and (x0,z0), (x1,z1) are the endpoints of the ribbon (in meters). The ribbon extends height/2 above and below the calculation plane. This routine ignores the NAF.
  - **Tie rfx rfy rfz x0 y0 x1 y1 ribwidth**
    The points (x0,y0) and (x1,y1) define (in meters) the endpoints of the center spine of a rectangular ribbon of width ribwidth lying in the xy-plane. The cells with sample point inside this rectangle see an applied field of (rf0,rf1,rf2), in units relative to Ms. (If the field is large, then the magnetizations in the rectangle will be "tied" to the direction of that field.)
  - **OneFile filename multiplier**
    Read B field in from a file. Each value in the file is multiplied by the "multiplier" value on input. This makes it simple to reverse field direction (use -1 for the multiplier), or to convert H fields to B fields (use 1.256637e-6). The input file may be any of the vector field file types recognized by mmDisp. The input dimensions will be scaled as necessary to exactly match the simulation grid, with zeroth order interpolation as necessary. This routine ignores the NAF.
  - **FileSeq filename procname multiplier**
    This is a generalization of the OneFile routine that reads in fields from a sequence of files. Here "filename" is the name of a file containing Tcl code to be sourced

during problem initialization, and "procname" is the name of a Tcl procedure defined in filename, which takes the nominal B field value and field step values as imports (4 values total), and returns the name of the vector field file that should be used as the applied B field for that field step.

– **Multi routinecount **
**param1count name1 param1 param2 ... **
**param2count name2 param1 param2 ... **
...
Allows a conglomeration of several field type routines. All entries must be on the same logical line, i.e., end physical lines with '\' continuation characters as necessary. Here routinecount is the number of routines, and param1count is the number parameters (including name1) needed by the first routine, etc.

Note that all dimensions are in meters. The coordinates in the simulation run from (0,0,0) to (Part Width, Part Height, Part Thickness).

Output specification

- **Base Output Filename:** Default base name used to construct output filenames.

Miscellaneous

- **Converge |mxh| Value:** Nominal value to use as a stopping criterion: When $\|\mathbf{m}\times\mathbf{h}\|$ at all spins in the simulation is smaller than this value, it is assumed that a relaxed (equilibrium) state has been reached for the current applied field. This is a dimensionless value, relative to Ms. Optional; default value is 10^{-4}.
- **Randomizer seed:** Value with which to seed random number generator. Optional. Default value is 0, which uses the system clock to generate a semi-random seed.

```
# MIF 1.1
#
# All units are SI.
#
######################## MATERIAL PARAMETERS ############################
Ms:  800e3                 # Saturation magnetization in A/m.
A:   13e-12                # Exchange stiffness in J/m.
K1:  0.5e3                 # Anisotropy constant in J/m^3.
Anisotropy Type: uniaxial  # One of <uniaxial|cubic>.
```

```
Anisotropy Dir1: 1 0 0     # Directional cosines wrt to coordinate axes

######################## DEMAG SPECIFICATION ############################
Demag Type: 3dSlab   # One of <3dSlab|2dSlab|3dCharge|FastPipe|None>.

########################### PART GEOMETRY ################################
Part Width:     0.25e-6    # Nominal part width in m
Part Height:    1.0e-6     # Nominal part height in m
Part Thickness: 1e-9       # Part thickness in m.
Cell Size:      8.1e-9     # Cell size in m.
#Part Shape:    # One of <Rectangle|Ellipse|Oval|Mask>.  Optional.

######################## INITIAL MAGNETIZATION ###########################
Init Mag: Uniform 90 45 # Initial magnetization routine and parameters

######################## EXPERIMENT PARAMETERS ###########################
Field Range Count: 2  # Number of Field Range lines.
Field Range: -.05 -.01 0. .05 .01 0. 100 # Start_field Stop_field Steps
Field Range: .05 .01 0. -.05 -.01 0. 100
Field Type: Multi 4 \
 7 Ribbon 1 0 1.0e-6 0.25e-6 1.0e-6 1e-9 \
 7 Ribbon 1 0 0     0.25e-6 0     1e-9 \
 9 Tie 100 0 0 0.12e-6 0.5e-6 0.13e-6 0.5e-6 8.1e-9
 1 Uniform \
# The above positions ribbons of positive charge along the upper
# and lower edges with strength Ms, applies a large (100 Ms) field
# to the center cell, and also applies a uniform field across the
# sample stepped from (-.05,-.01,0.) to (.05,.01,0.) (Tesla), and
# back, in approximately 0.001 T steps.

######################## OUTPUT SPECIFICATIONS ###########################
Base Output Filename: samplerun

########################### MISCELLANEOUS ################################
Randomizer seed: 1   # Value to seed random number generator with.
Converge Torque Value: 1e-5  # Stopping criterion, relative to Ms.
```

Figure 3: Example MIF file.

16.2 Data table format (ODT)

Textual output from `mmSolve` applications that is not of the vector field variety is output in the *OOMMF Data Table* (ODT) format. This is an ASCII file format, with column information in the header and one line of data per record. Any line ending in a '\' character is joined to the succeeding line before any other processing is performed. Any leading '#' characters on the second line are removed.

As with the OVF format (Sec. 16.3.1), all non-data lines begin with a '#' character, comments with two '#' characters. (This makes it easier to import the data into external programs, for example, plotting packages.) An example is shown in Fig. 4.

The first line should be the file type descriptor

```
# ODT 1.0
```

This is followed by comments and any of the following 5 recognized descriptor tag lines:

- **Table Start:** Optional, used to segment a file containing multiple data table blocks. Anything after the colon is taken as an optional label for the corresponding data table block.
- **Title:** Optional; everything after the colon is interpreted as a title for the table.
- **Columns:** Required. One parameter per column, designating the label for that column. Spaces may be embedded in a column label by using the normal Tcl grouping mechanisms (i.e., double-quotes and braces).
- **Units:** Optional. If given, it should have one parameter for each column, giving a unit label for the corresponding column.
- **Table End**: Optional, no parameters. Should be used in conjunction with a corresponding Table Start record.

Data may appear anywhere after its Columns descriptor record and before any Table End line, with one record per line. The data should be numeric values separated by whitespace.

```
# ODT 1.0
# Table Start
# Title: This is a small sample ODT file.
#
## This is a sample comment.  You can put anything you want
## on comment lines.
#
# Columns: Iteration "Applied Field"  {Total Energy}    Mx
# Units:       {}          "mT"           "J/m^3"       "A/m"
               103          50            0.00636      787840
              1000          32            0.00603      781120
             10300       -5000            0.00640     -800e3
# Table End
```

Figure 4: Sample ODT file.

16.3 Vector field formats (OVF and SVF)

Vector field files specify vector quantities (e.g., magnetization or magnetic flux density) as a function of spatial position. This type of file is produced by the micromagnetic solver program (Section 9) when "Total Field" or "Magnetization" output is selected. It is also the input data type read by the vector field display program, mmDisp (Section 12). OOMMF currently supports two vector field formats: the *OOMMF Vector Field* (OVF) format and the *Simple Vector Field* (SVF) format. The OVF format is the preferred format used by all OOMMF code. It supports both rectangular and irregular meshes, in binary and ASCII. The SVF format is provided to supply a simple interface to outside programs. (A third format, the *Vector Input/Output* (VIO) format, is used by some precursors to the OOMMF code. Its use is deprecated, and should not be used for new code.)

The recommended file extensions for OVF files are .omf for magnetization files, .ohf for magnetic field (**H**) files, .obf for magnetic flux density (**B**) files, or .ovf for generic files. SVF files should be given a .svf extension.

16.3.1 The OVF format

A commented sample OVF file is provided in Fig. 5. These files have an ASCII header and trailer, and a data block that may be either ASCII or binary. All non-data lines begin with a '`#`' character; the double '`##`' marks the start of a comment, which continues until the end of the line. There is no line continuation character. Lines starting with a '`#`' but containing

only whitespace characters are ignored.

All non-empty non-comment lines in the file header are structured as field+value pairs. The field tag consists of all characters after the initial '#' up to the first colon (':') character. Case is ignored, and all space and tab characters are eliminated. The value consists of all characters after the first colon, continuing up to a '##' comment designator or the end of the line.

The first line of a OVF file should be a file type identification line, having the form

```
# OOMMF: rectangular mesh v1.00
```

where the value "rectangular mesh v1.00" identifies subformat type and revision. Only the field tag "OOMMF" is used at present.

After this the file is conceptually broken into Segment blocks, and each Segment block is composed of a (Segment) Header block and a Data block. Every block begins with "# Begin: <block type>" line, and ends with a corresponding "# End: <block type>" line. The number of Segment blocks is specified in the

```
# Segment count: 1
```

line. Currently only 1 segment is allowed. This may be changed in the future to allow for multiple images per file. This is followed by

```
# Begin: Segment
```

to start the first segment.

Segment Header block The Segment Header block start is marked by the line "# Begin: Header" and the end by "# End: Header". Everything between these lines should be either comments or one of the following file descriptor lines. They are order independent. All are required unless otherwise stated. Numeric values are floating point values unless "integer" is explicitly stated.

- **title:** Long file name or title.
- **desc:** Description line. Use as many as desired. Description lines may be displayed by postprocessing programs, unlike comment lines which are ignored by all automated processing.
- **meshunit:** Fundamental mesh spatial unit, treated as a label. The comment marker '##' is not allowed in this label. Example value: "nm".

- **valueunit:** Fundamental field value unit, treated as a label. The comment marker '`##`' is not allowed in this label. Example: "kA/m."
- **valuemultiplier:** File data values are multiplied by this to get true values in units of "valueunit." This simplifies the use of normalized values in the data block.
- **xmin, ymin, zmin, xmax, ymax, zmax:** Six separate lines, specifying the bounding box for the mesh, in units of "meshunit." This may be used by display programs to limit the display area, and may be used for drawing a boundary frame if "boundary" is not specified.
- **boundary:** List of *(x,y,z)* triples specifying the vertices of a boundary frame.
- **ValueRangeMaxMag, ValueRangeMinMag:** The maximum and non-zero minimum field magnitudes in the data block, in the same units as used in the data block. These are for optional use as hints by postprocessing programs; for example, mmDisp will not display any vector with magnitude smaller than ValueRangeMinMag.
- **meshtype:** Grid structure; should be either "rectangular" or "irregular." Irregular grid files should specify "pointcount" in the header; rectangular grid files should specify instead "xbase, ybase, zbase," "xstepsize, ystepsize, zstepsize," and "xnodes, ynodes, znodes."
- **pointcount:** Number of data sample points/locations, i.e., nodes (integer). For irregular grids only.
- **xbase, ybase, zbase:** Three separate lines, denoting the position of the first point in the data section, in units of "meshunit." For rectangular grids only.
- **xstepsize, ystepsize, zstepsize:** Three separate lines, specifying the distance between adjacent grid points, in units of "meshunit." For rectangular grids only.
- **xnodes, ynodes, znodes:** Three separate lines, specifying the number of nodes along each axis (integers only). For rectangular grids only.

Data block The data block start is marked by a line of the form

```
# Begin: data <representation>
```

where <representation> is one of "text", "binary 4", or "binary 8". Text mode uses the ASCII specification, with individual data items separated by an arbitrary amount of whitespace (spaces, tabs and newlines). Comments are not allowed inside binary mode data blocks, but are permitted inside text data blocks.

The binary representations are IEEE floating point in network byte order (MSB). To insure that the byte order is correct, and to provide a partial check that the file hasn't been sent through a non 8-bit clean channel, the first datum is a predefined value: 1234567.0 (Hex: 49 96 B4 38) for 4-byte mode, and 123456789012345.0 (Hex: 42 DC 12 21 83 77 DE 40) for 8-byte mode. The data immediately follow the check value.

The structure of the data depends on whether the "meshtype" declared in the header is "irregular" or "rectangular". For irregular meshes, each data element is a 6-tuple, consisting of the x, y and z components of the node position, followed by the x, y and z components of the field at that position. Ordering among the nodes is not relevant. The number of nodes is specified in the "pointcount" line in the segment header.

For rectangular meshes, data input is field values only, in x, y, z component triples. These are ordered with the x index incremented first, then the y index, and the z index last. This is nominally Fortran order, and is adopted here because commonly x will be the longest dimension, and z the shortest, so this order is more memory-access efficient than the normal C array indexing of z, y, x. The size of each dimension is specified in the "xnodes, ynodes, znodes" lines in the segment header.

In any case, the first character after the last data item should be a newline, followed by

```
# End: data <representation>
```

where <representation> must match the value in the "Begin: data" line. This is followed by a

```
# End: segment
```

line that ends the segment, and hence the file.

```
# OOMMF: rectangular mesh v1.00
#
## This is a comment.
## No comments allowed in the first line.
#
# Segment count: 1   ## Number of segments.  Should be 1 for now.
#
# Begin: Segment
```

```
# Begin: Header
#
# Title: Long file name or title goes here
#
# Desc: 'Description' tag, which may be used or ignored by postprocessing
# Desc: programs. You can put anything you want here, and can have as many
# Desc: 'Desc' lines as you want.  The ## comment marker is disabled in
# Desc: description lines.
#
# meshunit: nm   ## Fundamental mesh measurement unit.  Treated as a label
#
# meshtype: rectangular
# xbase: 0.      ## (xbase,ybase,zbase) is the position, in
# ybase: 0.      ## 'meshunit', of the first point in the data
# zbase: 0.      ## section (below).
#
# xstepsize: 20. ## Distance between adjacent grid pts.: on the x-axis,
# ystepsize: 10. ## 20 nm, etc.  The sign on this value determines the
# zstepsize: 10. ## grid orientation relative to (xbase,ybase,zbase).
#
# xnodes: 200    ## Number of nodes along the x-axis, etc. (integers)
# ynodes: 400
# znodes:   1
#
# xmin:    0.    ## Corner points defining mesh bounding box in
# ymin:    0.    ## 'meshunit'.  Floating point values.
# zmin:  -10.
# xmax: 4000.
# ymax: 4000.
# zmax:   10.
#
# valueunit: kA/m  ## Fundamental field value unit, treated as a label
# valuemultiplier: 0.79577472  ## Multiply file values by this to get
#                              ## true value in 'valueunits'.
#
# ValueRangeMaxMag:  1005.3096  ## These are in file value units, and
# ValueRangeMinMag:  1e-8       ## are used as hints (or defaults) by
#     ## postprocessing programs.  The mmdisp program ignores any points
```

```
#     ## with magnitude smaller than ValueRangeMinMag, and uses
#     ## ValueRangeMaxMag to scale inputs for display.
#
# End: Header
#
## Anything between '# End: Header' and '# Begin: data text',
## '# Begin: data binary 4' or '# Begin: data binary 8' is ignored.
##
## Data input is in 'x-component y-component z-component' triples,
## ordered with x incremented first, then y, and finally z.
#
# Begin: data text
1000 0 0 724.1 0. 700.023
578.5 500.4 -652.36
<...data omitted for brevity...>
252.34 -696.42 -671.81
# End: data text
# End: segment
```

Figure 5: Commented OVF sample file.

16.3.2 The SVF format

The Simple Vector Field (SVF) format is a simple ASCII format supporting irregularly sampled data. It is intended as an aid for importing data from non-OOMMF programs, and is backwards compatible with the format used for problem submissions for the first μMag standard problem[7].

A sample SVF file is shown in Fig. 6. Any line beginning with a '#' character is a comment, all others are data lines. Each data line is a whitespace separated list of 6 elements: the x, y and z components of a node position, followed by the x, y and z components of the field at that position. Input continues until the end of the file is reached.

It is recommended (but not required) that the first line of an SVF file be

```
# SVF-02
```

[7] http://www.ctcms.nist.gov/~rdm/stdprob_1.html

```
# SVF-02
## File: sample.svf
## Boundary-XY: 0.0 0.0 1.0 0.0 1.0 2.0 0.0 2.0 0.0 0.0
## Grid step: .25 .5 0
#  x      y      z        m_x      m_y      m_z
  0.01   0.01   0.01   -0.35537  0.93472 -0.00000
  0.01   1.00   0.01   -0.18936  0.98191 -0.00000
  0.01   1.99   0.01   -0.08112  0.99670 -0.00000
  0.50   0.50   0.01   -0.03302  0.99945 -0.00001
  0.99   0.05   0.01   -0.08141  0.99668 -0.00001
  0.75   1.50   0.01   -0.18981  0.98182 -0.00000
  0.99   1.99   0.01   -0.35652  0.93429 -0.00000
```

Figure 6: Example SVF file.

This will aid automatic file type detection. Also, three special (extended) comments are recognized by the mmDisp display program:

```
## File: <filename or extended filename>
## Boundary-XY: <boundary vertex pairs>
## Grid step: <cell dimension triple>
```

All these lines are optional. The "File" provides a preferred (possibly extended) filename to use for display identification. The "Boundary-XY" line specifies the ordered vertices of a bounding polygon in the xy-plane. If given, mmDisp will draw a frame using those points to ostensibly indicate the edges of the simulation body. Lastly, the "Grid step" line provides three values representing the average x, y and z dimensions of the volume corresponding to an individual node (field sample). It is used by mmDisp to help scale the display.

References

[1] D. V. Berkov, K. Ramstöck and A. Hubert, "Solving Micromagnetic Problems: Towards an Optimal Numerical Method," *Phys. Stat. Sol. (a),* **137**, 207–222 (1993).

[2] M. J. Donahue and R. D. McMichael, "Exchange Energy Representations in Computational Micromagnetics," *Physica B,* **233**, 272–278 (1997).

17 Credits

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[8] http://math.nist.gov/oommf/