

# **Driving Forces for Cell Cluster Shape Evolution and Stability**

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- • The Model
	- Experimental Background
	- Origin of Surface Energy
	- Analysis of the Model
	- Results & Conclusions
- $\bullet$  Linear Stability of a Toroidal Cluster
	- Stability Analysis
	- Formulation of Model
		- Calculating Surface Area and Volume of Perturbed shape
		- Alternate Perturbed Shape
	- Non-constant Surface Energy Density
	- Results & Conclusions

### Directed Self Assembly Experiments





400 um

Dean, D. M., Napolitano, A. P., Youssef, J. and Morgan, J. R. FASEB 2007

# The Phenomenon



A mathematical model of the current system will

- 1. allow for understanding the factors involved in cell cluster reorganization
- 2. offer a framework to organize lab observations

### Spontaneous Climb



The goal - to determine the nature of the cell interactions driving the reorganization of a homotypic cluster







# The Model

A fully dense aggregate is formed The volume remains constant,

$$
v_0=2\pi^2 a(0)b(0)^2=2\pi^2 a(t)b(t)^2
$$

Total surface area of cluster

$$
s(t)=4\pi^2 a(t)b(t)=2v_0/b(t)
$$

As the cluster moves up the pillar,  $a(t)$ decreases and  $b(t)$  increases providing a likely driving force.

Distance to the center of mass from the apex,

$$
\overline{z}(t)=a(t)\tan\alpha-b(t)\sec\alpha\,.
$$





# Possible Origin of Surface Energy

Cell to cell adhesion  $\rightarrow$  Anchoring Junctions  $\rightarrow$  Adherens Junctions Adherens junctions mechanically attaches actin cytoskeletons of connected cells



Generating contraction in these structures consumes ATP which lowers the free energy of the connected cells

This serves as a natural basis for the surface energy of a cell cluster

# The Model

Assume that there is a uniform surface energy density  $\gamma$  associated with the cluster surface

The system free energy in terms of  $b(t)$ is

$$
\mathcal{F}(t)=-v_0\rho g\overline{z}(t)+\gamma 2v_0/b(t)\,.
$$



Rearrangement of cells on cluster surface occurs by surface diffusion with surface mass flux j and surface mobility  $m_s$ 

The energy dissipation is

$$
\mathcal{D}(t) = \int_{S(t)} \frac{1}{m_s} \mathbf{j} \cdot \mathbf{j} \, dS
$$

Points on azimuthal section of surface with respect to the apex of the cone

$$
\mathsf{r}(\theta,\phi) = \{a(t) + b(t) \cos \phi, \overline{z}(t) + b(t) \sin \phi\}
$$

Surface flux is axially symmetric and has the form

$$
\mathbf{j} = f(\phi) \mathbf{g}_{\phi}.
$$

Conservation of mass equation

$$
v_n + \nabla \cdot \textbf{j} = 0
$$

is solved for  $f(\phi)$  where

$$
v_n=\mathsf{n}\cdot\partial_t\,\mathsf{r}(\theta,\phi)
$$



Diffusive system evolves such that

$$
\mathcal{F}'(t)+\frac{1}{2}\mathcal{D}(t)
$$

is stationary under variations in the parameters characterizing the rate of change of configuration (LBF  $\&$  Suresh, Thin Film Materials).

This implies

$$
\frac{\partial}{\partial b'(t)}\left[\mathcal{F}'(t)+\frac{1}{2}\mathcal{D}(t)\right]=0\,.
$$

The minor radius and the time are normalized according to

$$
\tau=\frac{m_s\rho gt}{b_0^2}\,,\quad \beta(\tau)=\frac{b(t)}{b_0}
$$
 where  $\beta(\tau)=1$  as  $b_0=b(0).$ 

The ODE then requires specification of values of the non-dimensional parameters

$$
\omega=\frac{v_0}{b_0^3}\,,\quad \kappa=\frac{\gamma}{\rho g b_0^2}
$$





### Numerical Solution for shape evolution



Results of differential equation for  $\kappa = 100$ 

### Extraction of Surface Energy Density Values

Examination of the governing differential equation reveals that it has the form

$$
A(\alpha, \beta(\tau)) + \frac{\gamma}{\rho g b_0^2} B(\alpha, \beta(\tau)) + \frac{b_0^2}{m_s \rho g} C(\alpha, \beta(\tau), \beta'(\tau)) = 0
$$

For a particular value of  $\alpha$ , observation of the motion  $b(t)$  yields a straight line in the plane below which defines possible values of  $\gamma$  and  $m_s$ .



Foty & Steinberg (05) & Sivansankar et al (99):  $1.556$  x  $10^{\texttt{-4}}$   $\leq$   $\gamma$   $\leq$   $1.522$  x  $10^{\texttt{-3}}$  mJ/m $^2$ 

# Conclusions from the Basic Model

Results reinforce the process of surface area reduction for self assembled clusters

Rate of process affected by system parameters

- $\bullet$   $\kappa$
- $\bullet$   $\alpha$
- $\bullet$   $m_s$

Model can be used to extract approximate values for the surface energy density of the clusters

Model can be extended to study clusters with both uniform and nonuniform shapes

Model does not determine the behavior of clusters after  $a(t) = b(t)$ or the behavior of clusters that do not climb the conical pillar

# Outline

- • The Model
	- Experimental Background
	- Origin of Surface Energy
	- Riemannian Geometry
	- Analysis of the Model
	- Results & Conclusions



- • Linear Stability of a Toroidal Cluster
	- Stability Analysis
	- Formulation of Model
		- Calculating Surface Area of Perturbed shape
		- Alternate Perturbed Shape
	- Non-constant Surface Energy Density
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# Stability of Toroidal Shapes



#### Jeff Morgan Lab



McGraw et al, *Soft Matter* 2010



Pairam & Fernandez-Nieves, *Physics Rev. Letter* 2009

### Linear Stability Analysis of the Toroidal Cluster

The goal - to apply linear stability concepts to determine if the cluster is stable against growth of small amplitude non-uniform deformations



#### Initial equilibrium shape is a uniform torus

If the torus is perturbed slightly, will the perturbed shape tend toward equilibrium or not?

Linear Stability Analysis of the Toroidal Cluster

Pertubations that decrease the free energy of the body grow in amplitude (Carter  $\&$  Glaeser, 1987)

The system free energy is now

$$
\mathcal{F}(t)=\gamma S(t)
$$

Stability determined by change of  $S(t)$  as cluster departs its uniform configuration i.e  $\dot{S}(0)$ 

Development of a perturbation in the minor radius of the form

$$
b(\theta,t)=b_k(t)-c_k(t)(1-\cos k\theta)
$$

As volume is conserved, fluctuation parameters cannot vary independently





# $\gamma$  is spatially constant



Surface of perturbed shape defined by  $\mathbf{r}(\theta,\phi) = (a(t) + b(\theta,t)\cos\phi)\cos\theta\,\mathbf{e}_x$  $+(a(t)+b(\theta,t)\cos\phi)\sin\theta$  e $_{y}$  $+ b(\theta, t) \sin \phi e_z$ 

Surface area found by

$$
S(t)=\int_0^{2\pi}\int_{-\pi}^{\pi}\sqrt{\det\left[G_{\phi\theta}\right]}\,d\phi\,d\theta
$$

Applying limits:  $b_k(0) \to b_0$  and  $c_k(0) \to 0$  as  $t \to 0$ 

$$
\dot{S}(0) = 4\pi^2 b_0 \frac{b_0 + r_0}{3b_0 + r_0} \dot{c}_k(0) \qquad \boxed{\text{Always stable}}
$$

### Alternate perturbed shape



Surface of alternate perturbed shape found  $by$ 

$$
\mathbf{r} = (r_0 + b(\theta, t)(1 + \cos \phi)) \cos \theta \mathbf{e}_x + (r_0 + b(\theta, t)(1 + \cos \phi)) \sin \theta \mathbf{e}_y + b(\theta, t) \sin \phi \mathbf{e}_z
$$

Surface area found by

$$
S(t) = \int_0^{2\pi} \int_{-\pi}^{\pi} \sqrt{\det[G_{\phi\theta}]} \, d\phi \, d\theta
$$
  

$$
\dot{S}(0) = 0 \quad \boxed{\text{Inconclusive}}
$$

With the constraint of  $r_0$ , the uniform toroidal clusters are stable under this particular family of perturbations if  $\gamma$  is everywhere the same

### γ is not spatially constant

![](_page_21_Figure_1.jpeg)

Change in free energy no longer equivalent with change in surface area

# Nonuniform  $\gamma$  with same applied perturbation

Stability now determined by  $\dot{F}(0)$  where

$$
\mathcal{F}(t)=\int_{0}^{2\pi}\left[\gamma(\theta)\int_{-\pi}^{\pi}\sqrt{\det\left[G_{\phi\theta}\right]}\,d\phi\right]d\theta
$$

$$
\overset{\mathsf{f}(r_0,\ b_0,\ k)}{\downharpoonright}\cdot \qquad \qquad \dot{\mathcal{F}}(0)=f(r_0,b_0,k)\ \dot{c}_k(0)
$$

 $\boldsymbol{\Lambda}$ 

 $-2$ 

-4

![](_page_22_Figure_4.jpeg)

![](_page_22_Figure_5.jpeg)

unstable

### Non uniform  $\gamma$  with same applied perturbation

![](_page_23_Figure_1.jpeg)

# $\gamma$  is a function of position on the surface

Similar results are obtained for alternate perturbed shape

Position, amplitude and width of non-zero region of  $\gamma(\theta)$  have been arbitrarily chosen

These parameters influence  $f(r_0, b_0, k)$ 

However unstable configurations do develop from the uniform toroidal shapes

Admittedly  $\gamma$  can vary with  $\phi$ as well as with time

![](_page_24_Figure_6.jpeg)

### Conclusions on Toroidal Stability

From work by McGraw et al (2010) and Pairam (2009) dependence of stability on initial geomtery of cluster and radius of pillar is expected

Linear stability analysis is only valid for finite time intervals

It is sufficient to define a critical value of a measurable parameter which can then be experimentally verified

Next step would be a nonlinear stability analysis

# Summary of Results on Toroidal Clusters

![](_page_26_Figure_1.jpeg)

- •Origin of γ requires further investigation
- •More precise method required to extract values of  $m<sub>s</sub>$
- • Conduct linear stability analysis of toroidal shapes with
	- other family of perturbations
	- more complex surface energy density function
- •For spatially constant  $\gamma$ , conduct a nonlinear stability analysis of the toroidal clusters

![](_page_27_Figure_7.jpeg)

#### My advisor Professor L. Ben Freund

Experimental Collaborators - Professor Jeffrey Morgan Jacqueline Youssef, Dylan Dean, Anthony Napolitano

A publication on the model of the climb of the torus up the conical pillar is currently being revised for Journal of Applied Mechanics with authors Nurse, A., Youssef, J. and Freund, L.B.

Additional work on the action of rho kinase on the climbing process of the cluster of cells can be found at Youssef, J., Nurse, A., Freund, L.B., Morgan, J. PNAS 2011

![](_page_28_Figure_5.jpeg)

![](_page_28_Picture_6.jpeg)